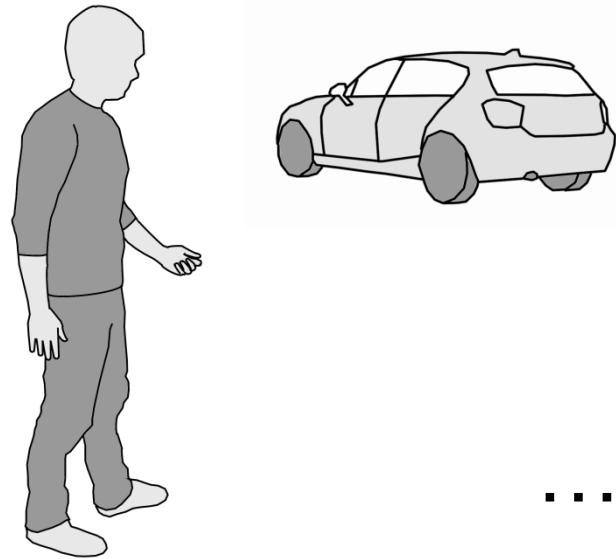


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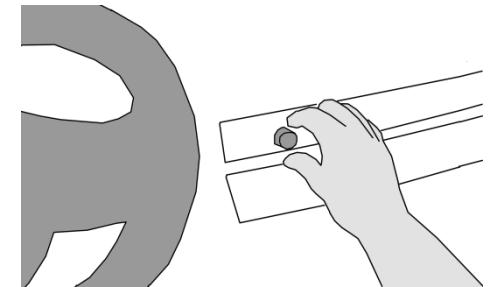
Approach...



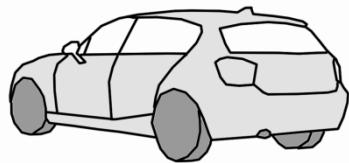
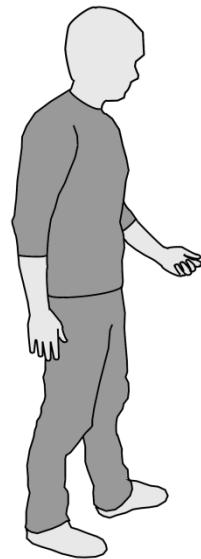
...configure...



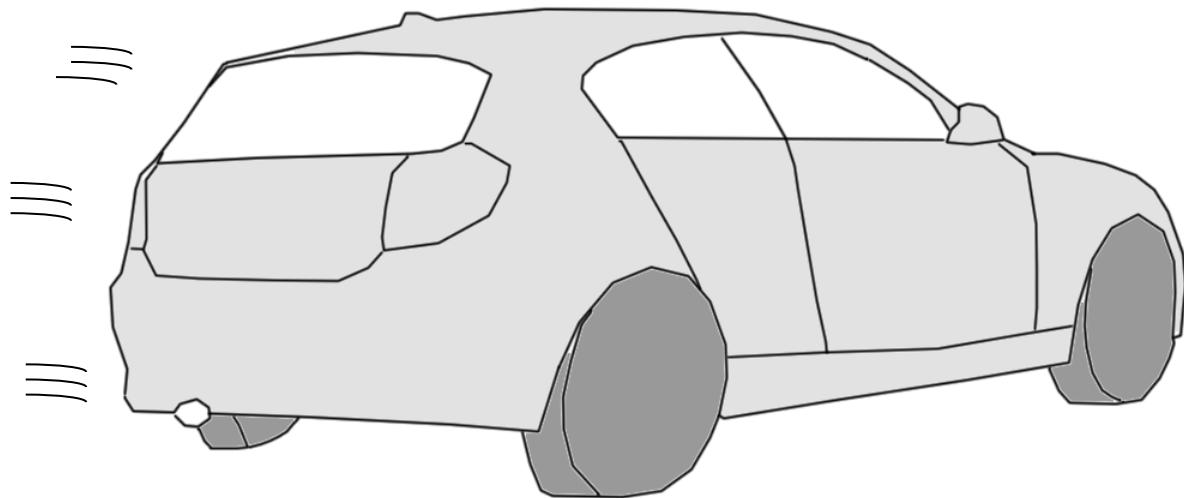
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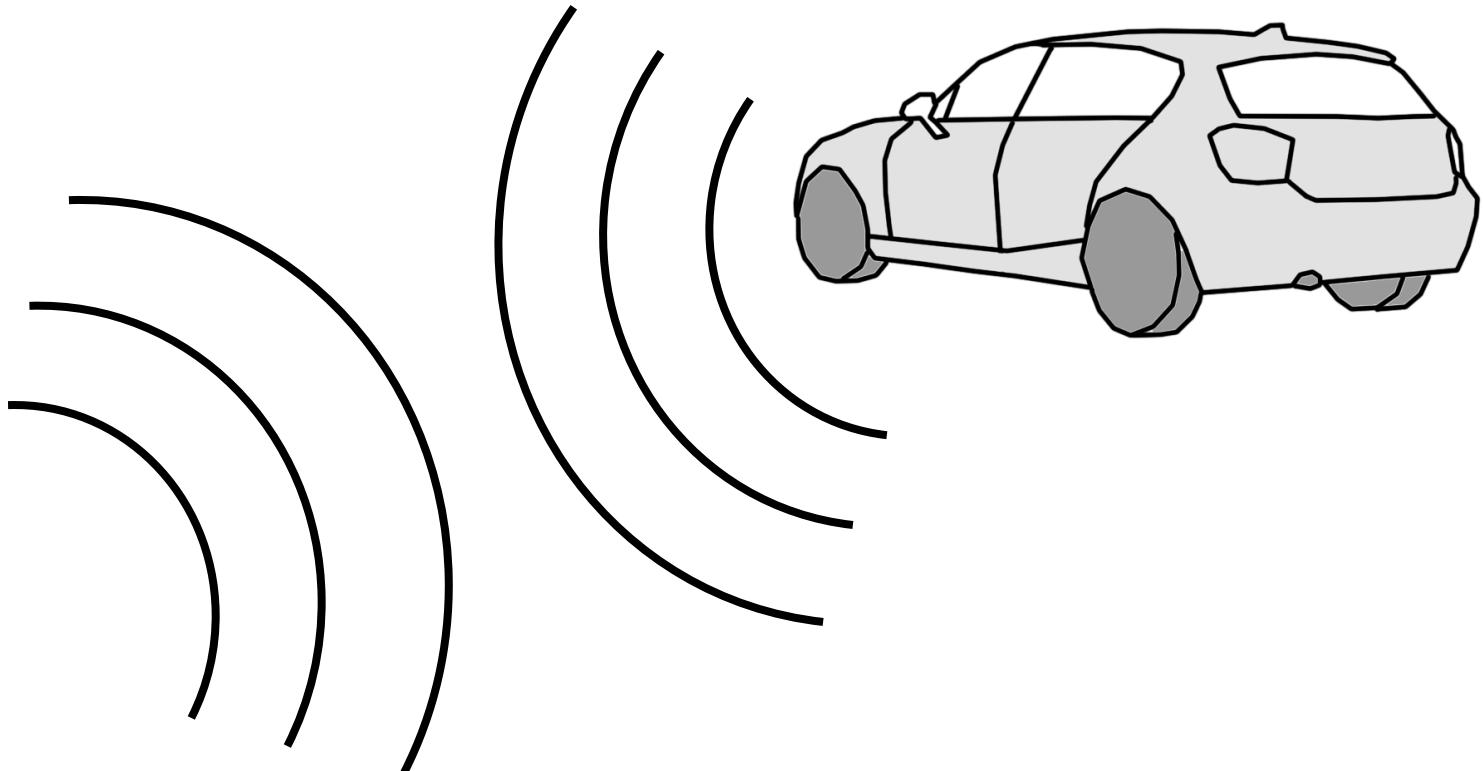
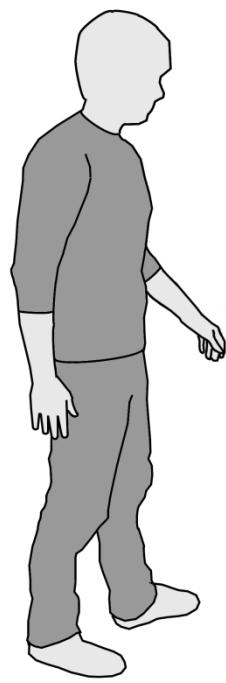


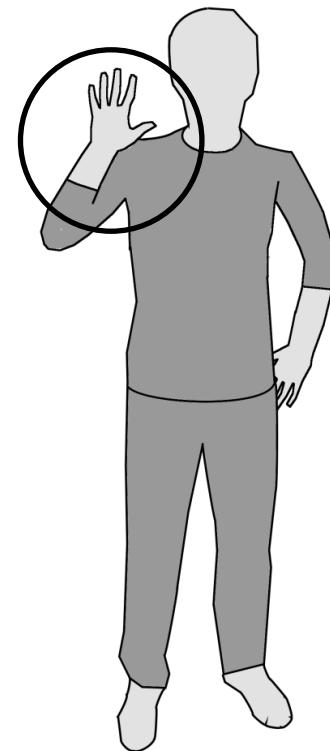
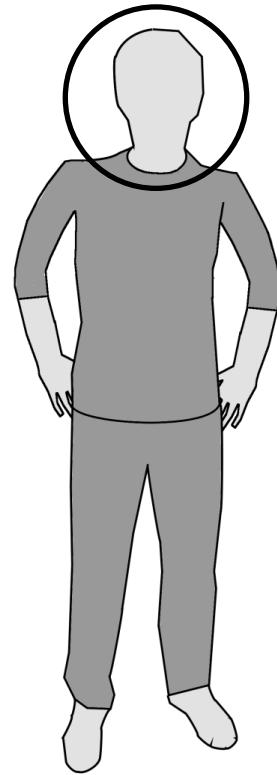
Approach...

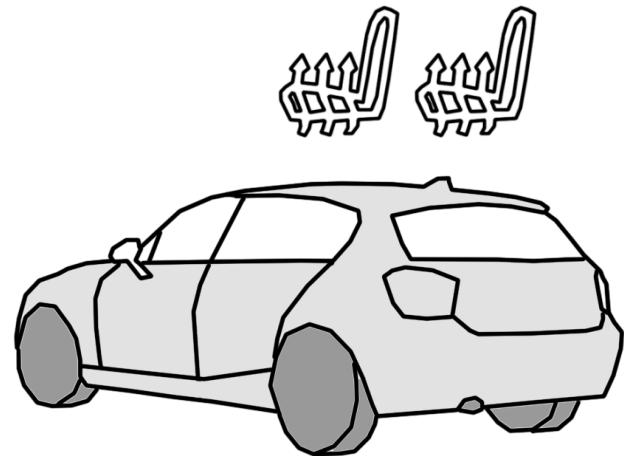
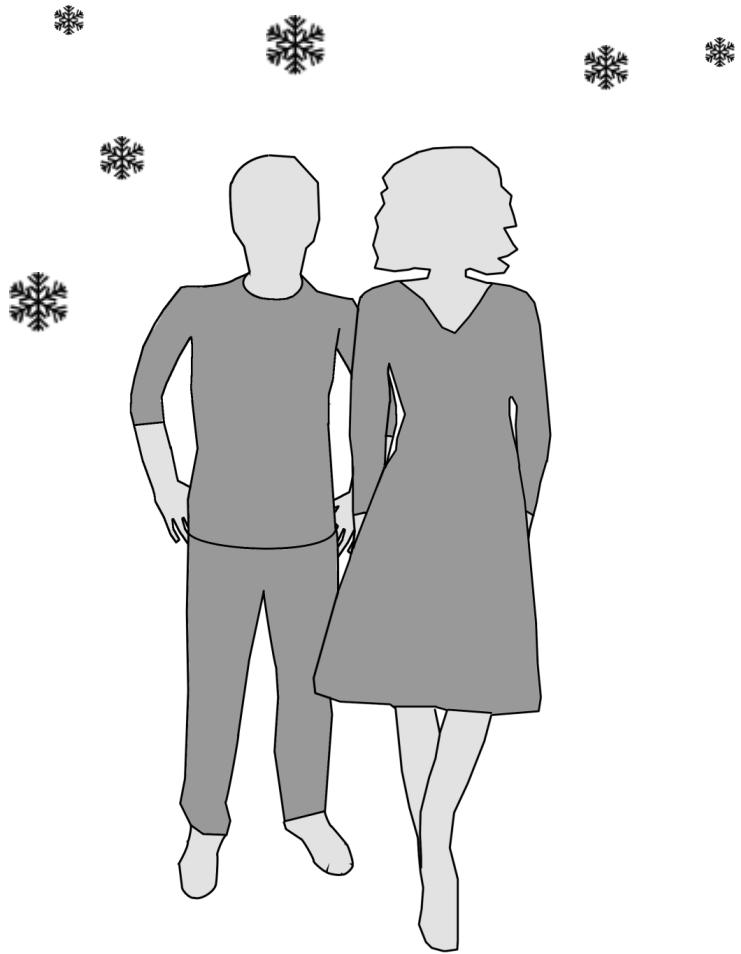


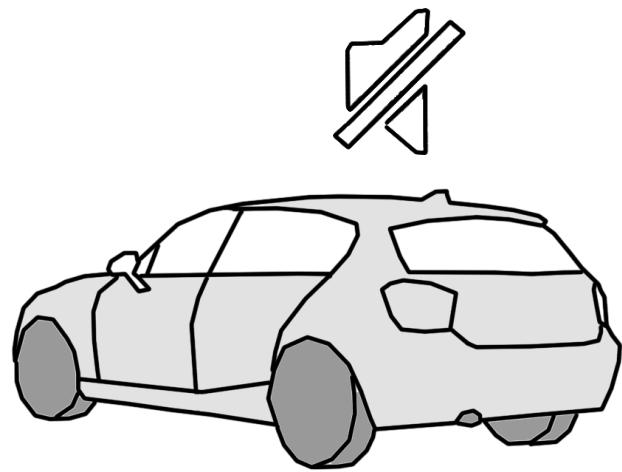
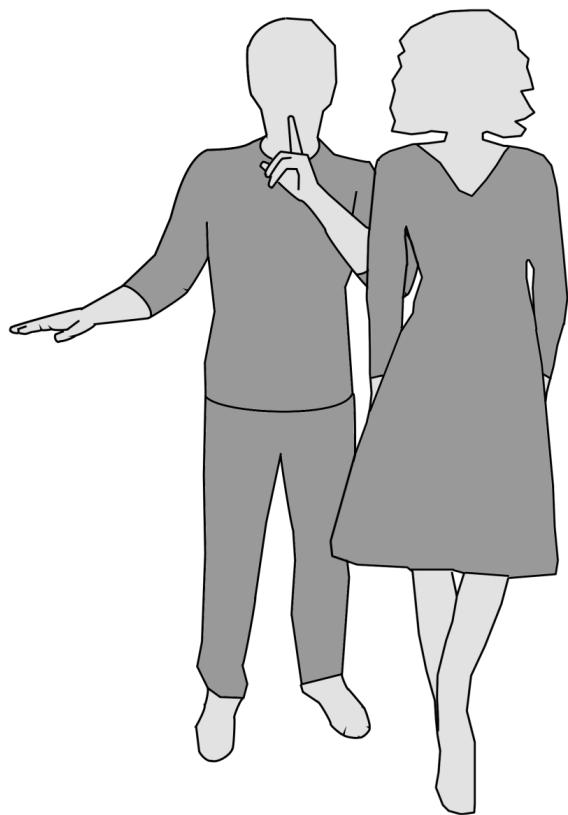
...drive!

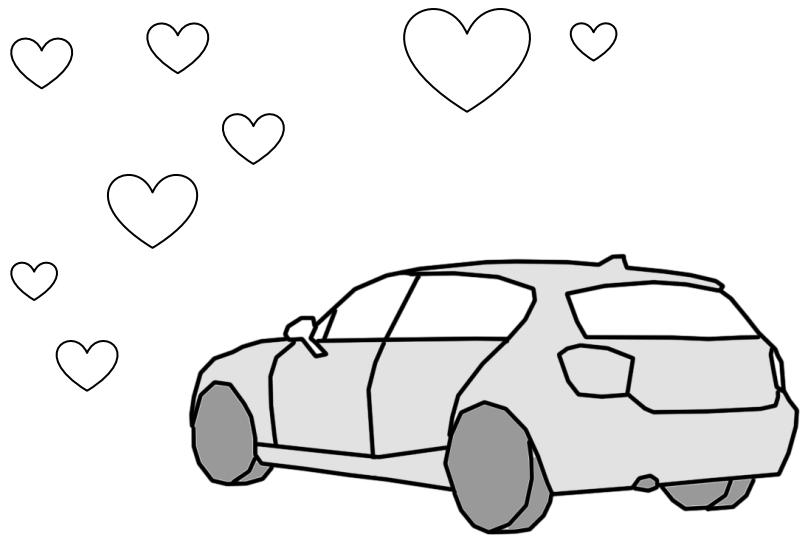


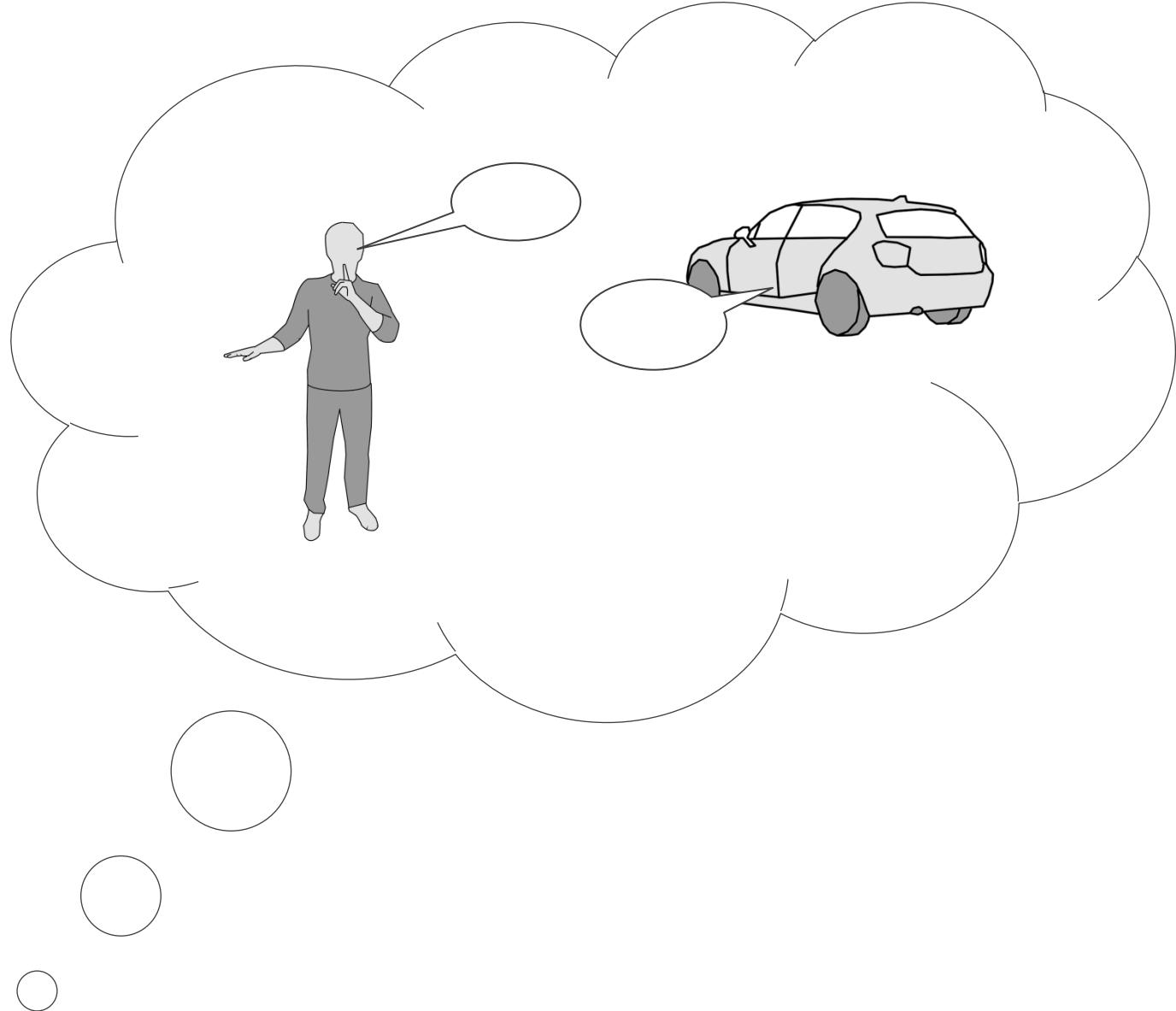












implicit

sensors

height

temperature

number of people

open arms

show fingers

wave

cross arms

explicit

implicit sensing of the surrounding

sensors

height

temperature

number of people



context model

implicit sensing of the surrounding

sensors

height

temperature

rain

number of people

walking speed

calendar data

baggage

identities

light conditions

**explicit
gestures while approaching the car**

open arms
wave show fingers
cross arms

concrete commands



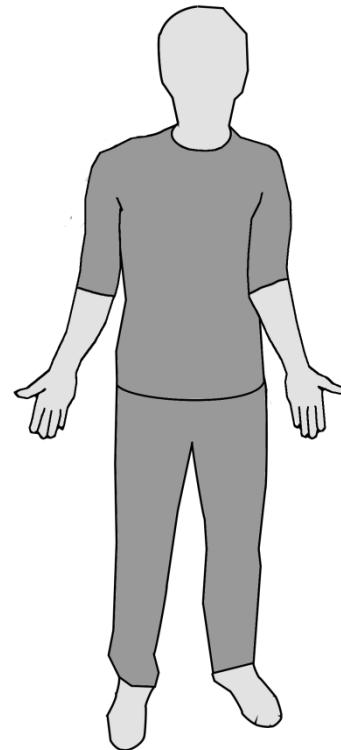
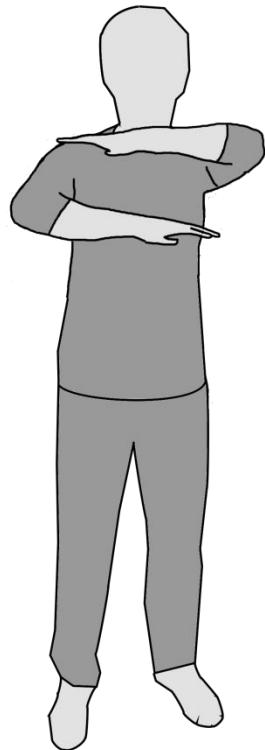
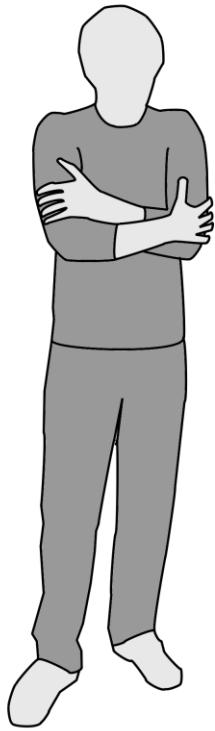
wave

open arms

show fingers

cross arms

explicit
gestures while approaching the car



**explicit
gestures while approaching the car**

implicit

sensors

height

temperature

intelligent



wave

cross arms

number of people

configuration

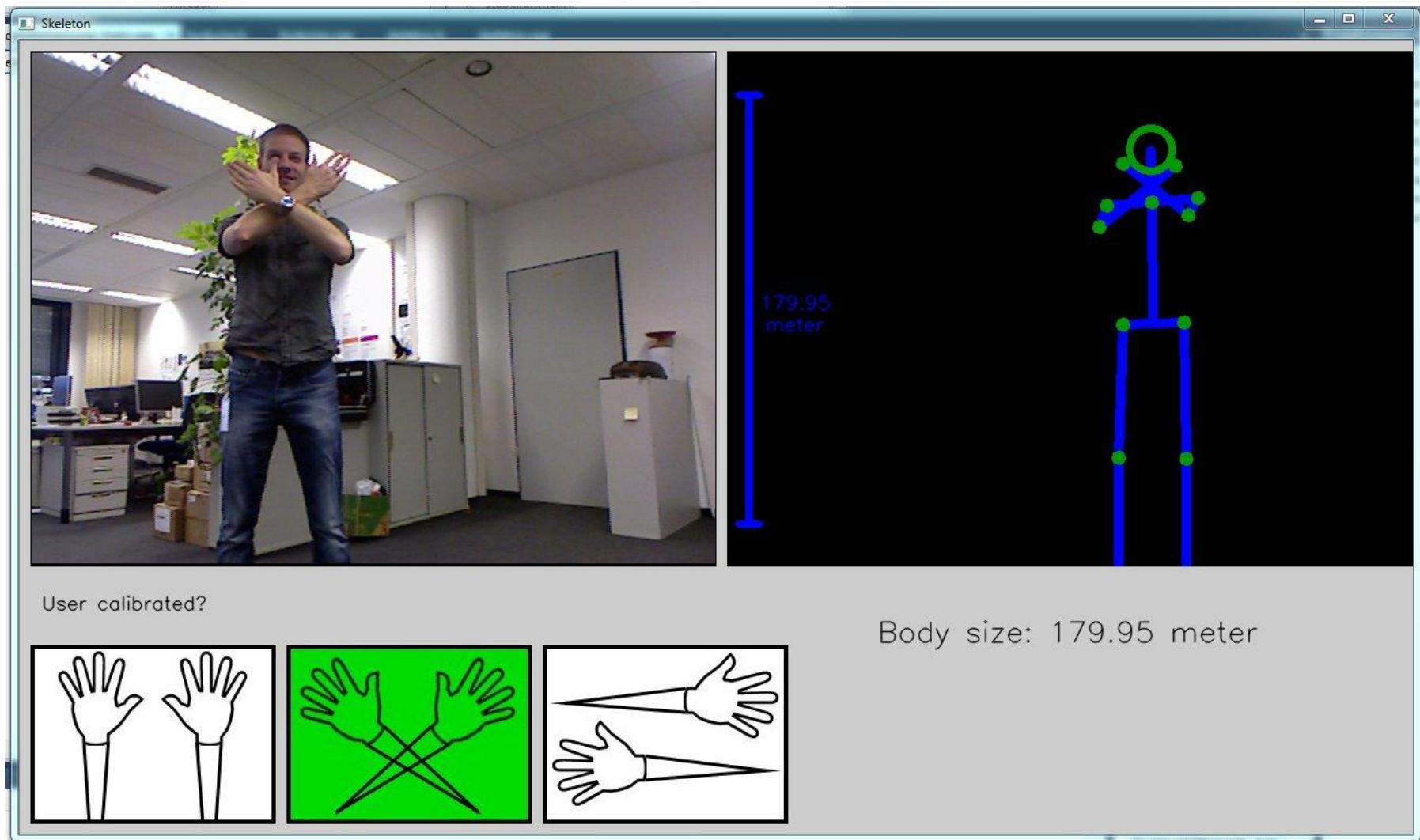
open arms

show fingers

explicit

OpenNI™





```
graph LR; A[concepts] --> B[connect to car]; B --> C[testing]; B -- feedback --> A;
```

concepts

connect
to car

testing

Using the last steps
exploring natural interaction for automotive use cases

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Thank you for your
attention