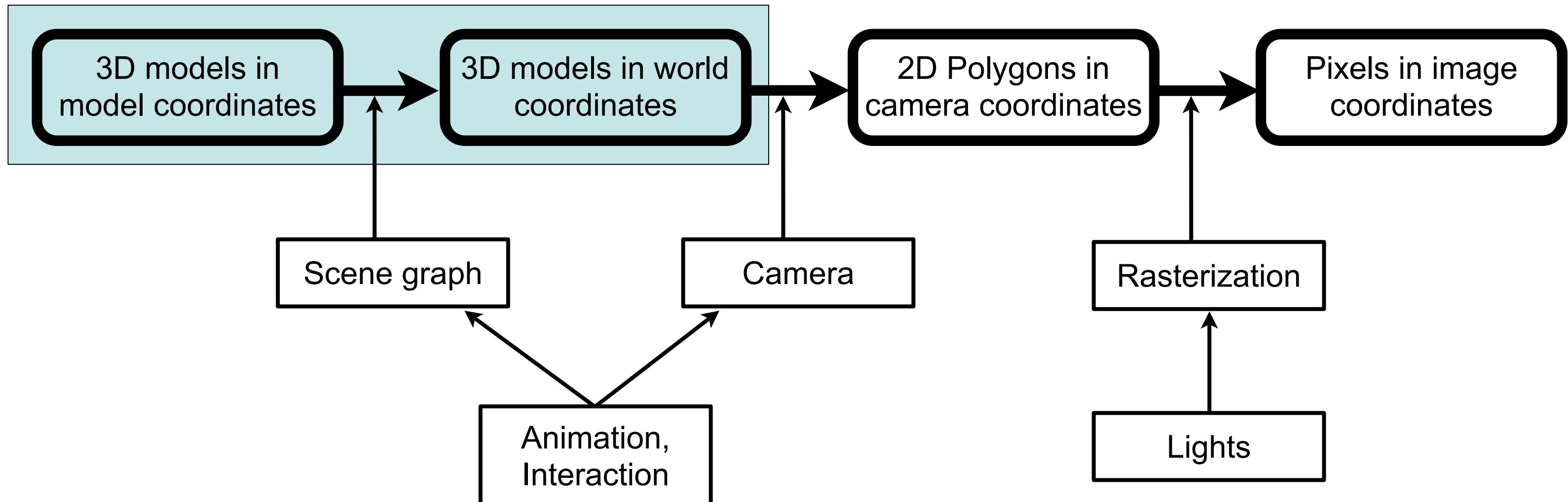


# Computer Graphics 1

Chapter 2 (May 19th, 2011, 2-4pm):  
3D Modeling

# The 3D rendering pipeline (our version for this class)

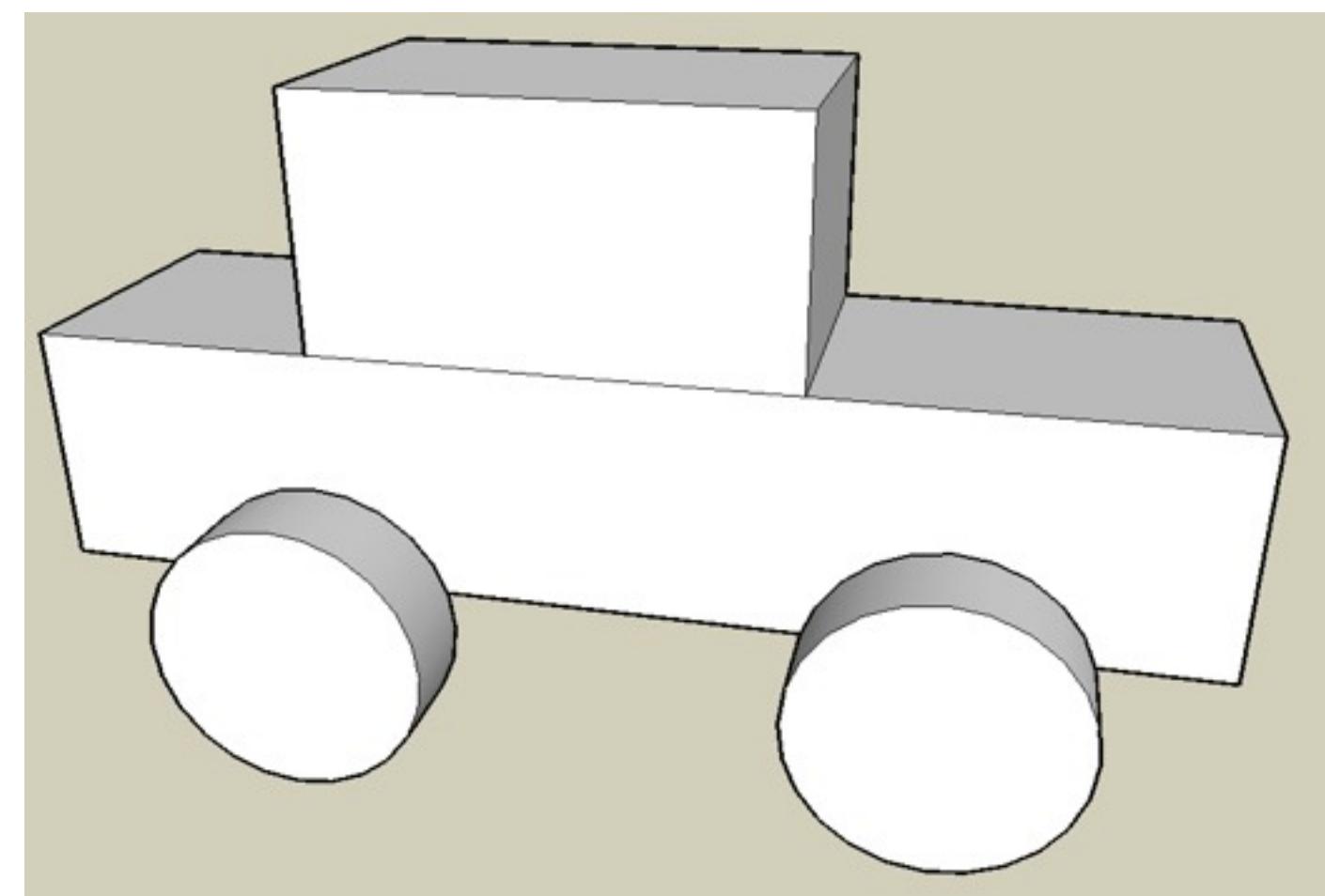


# Chapter 2 - 3D modeling

- Geometric Primitives
- Constructive Solid Geometry (CSG)
- Polygon Meshes
- Extrusion & Rotation
- Interpolation Curves
- Levels Of Detail (LOD)
- Volume- and Point-based Graphics

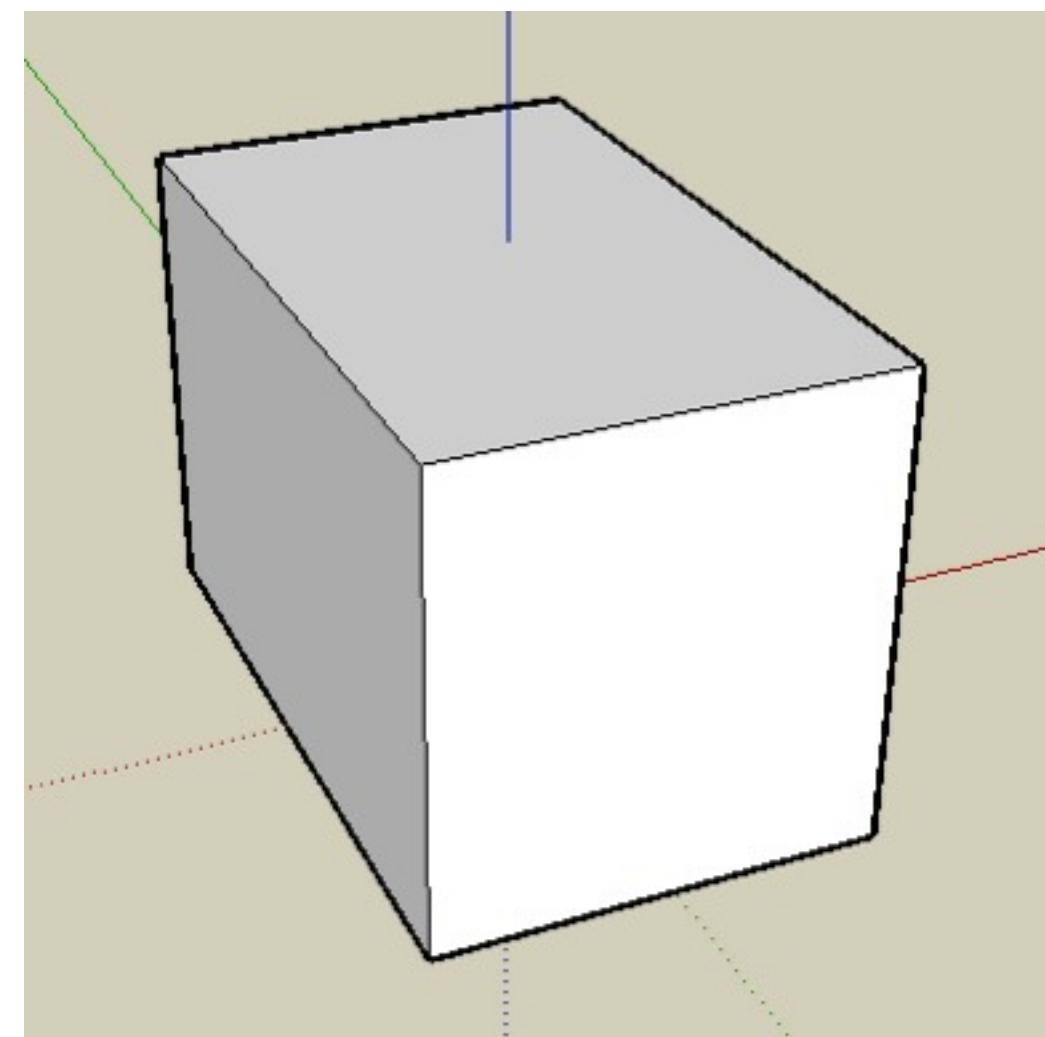
# Geometric Primitives

- Simplest way to describe geometric objects
- Can be used directly by some renderers (e.g., Ray tracing)
- Can be transformed into polygons easily (Tesselation)
- Can be transformed into Voxels easily
- Useful for creating simple block world models
- Good start for modeling in VRML/X3D
- Objects can intersect/penetrate



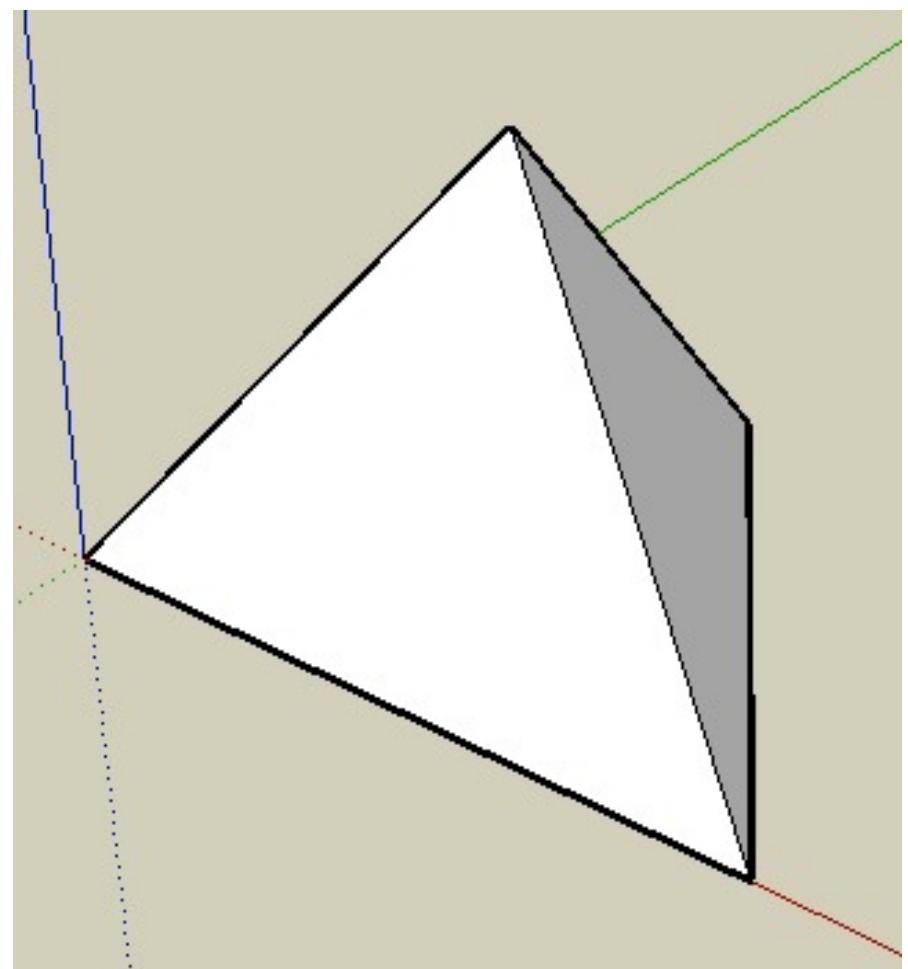
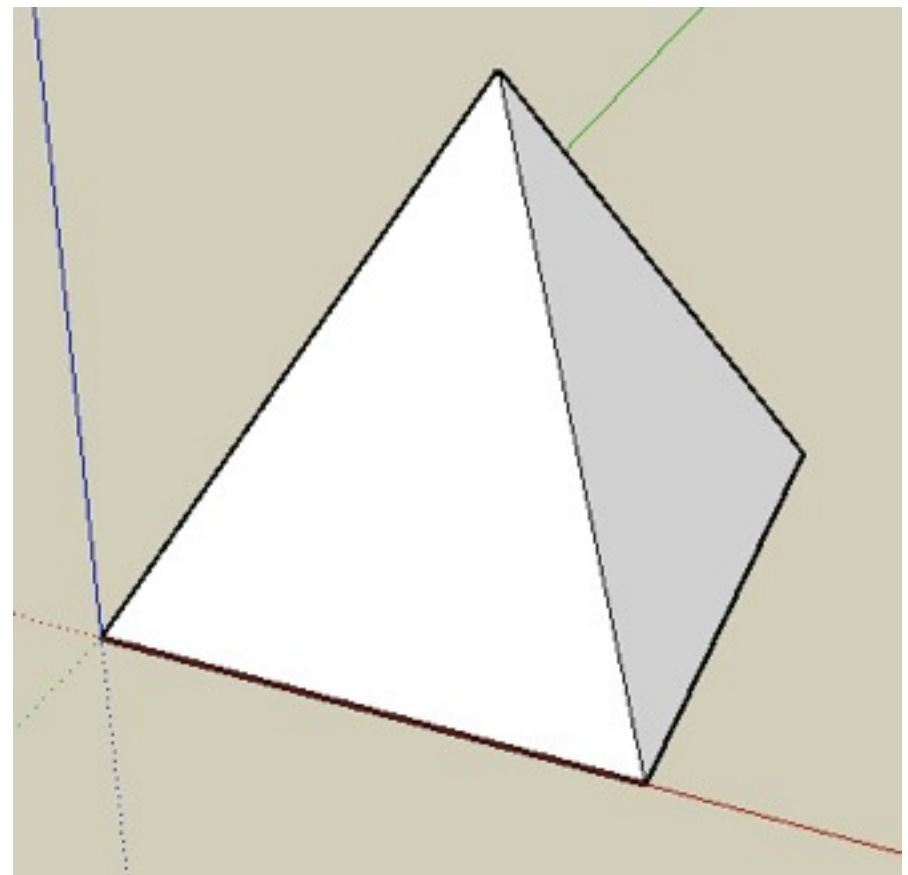
# Box

- Described by (width, length, height)
- Origin usually in the center
- 8 points, 12 edges, 6 rectangles, 12 triangles



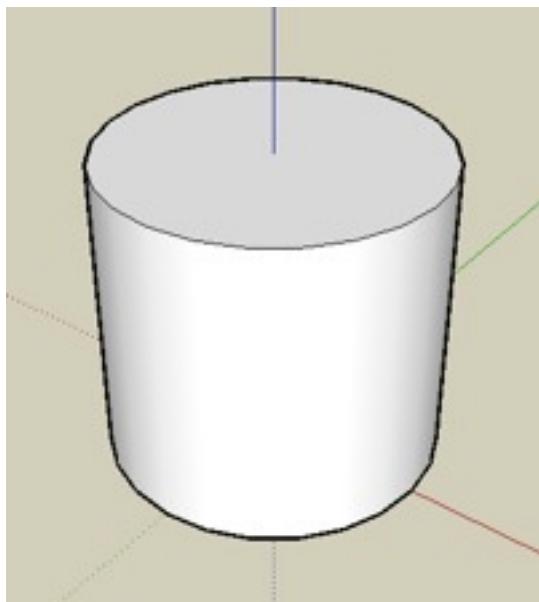
# Pyramid, Tetrahedron

- Basis of pyramid = rectangle
  - given by (width, length, height)
  - 5 points, 8 edges, 6 triangles
- 
- Basis of tetrahedron = triangle
  - given by (width, length, height)
  - 4 points, 6 edges, 4 triangles,

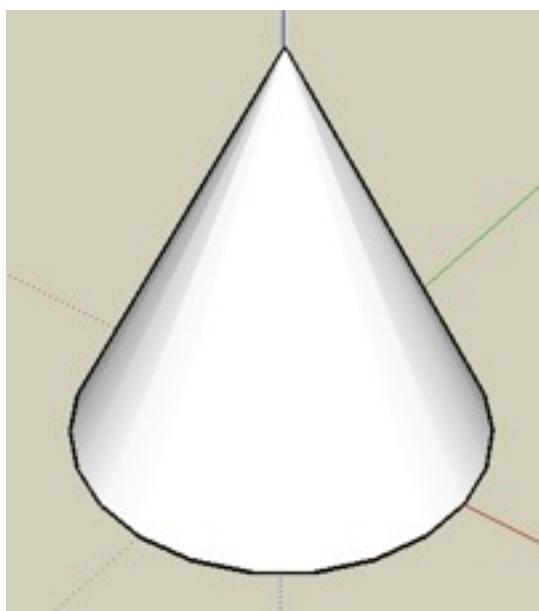


# Cylinder, cone, truncated cone

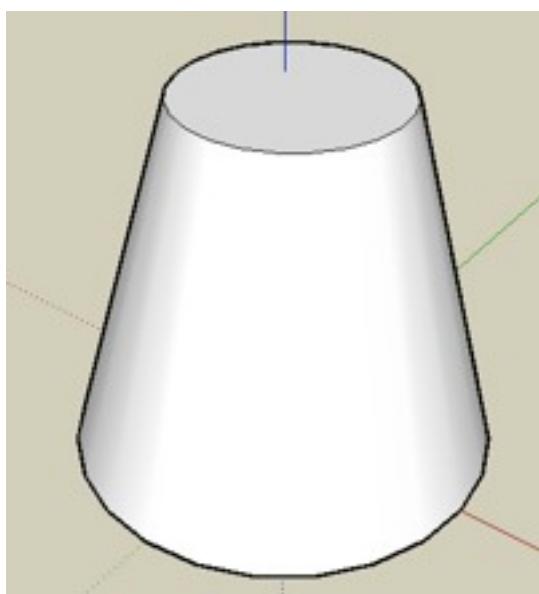
- Cylinder given by (radius, height)
- Number of polygons dep. on tessellation



- Cone given by (radius, height)
- Number of polygons dep. on tessellation

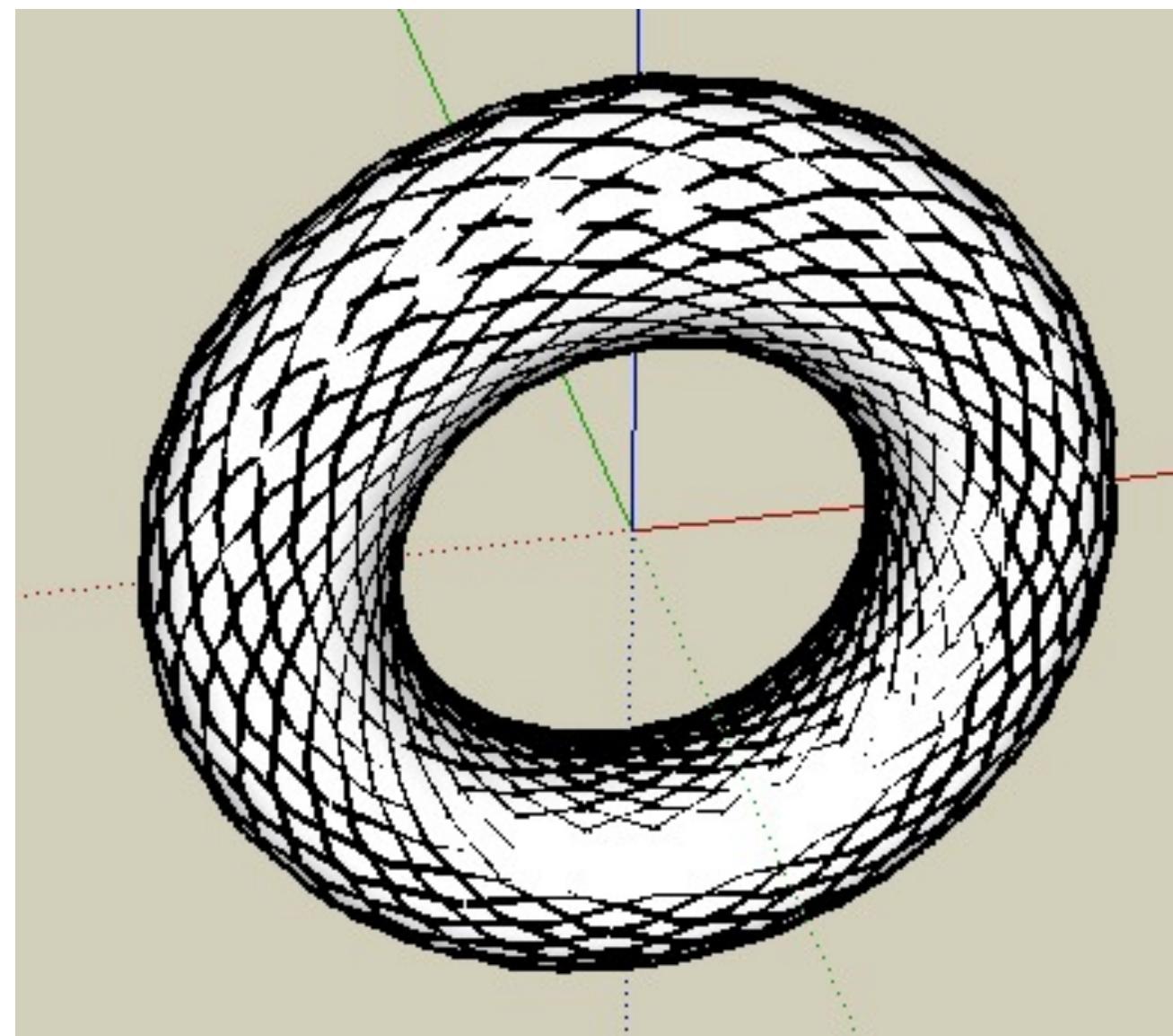
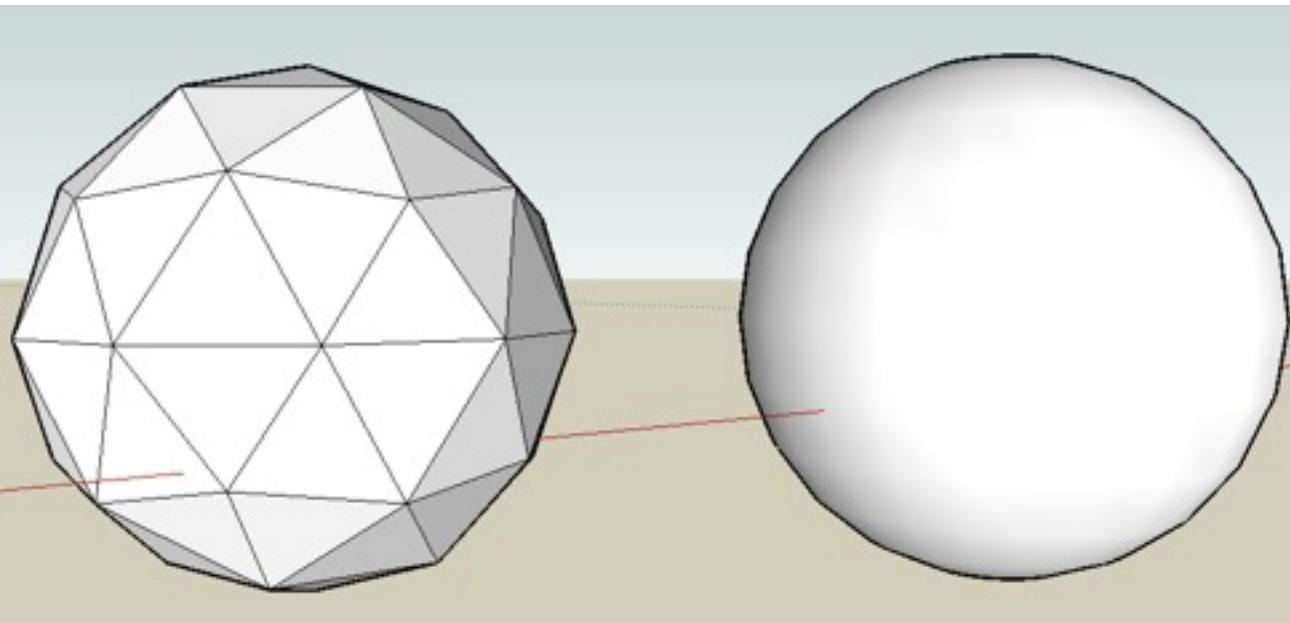


- Truncated cone given by ( $r_1, r_2, \text{height}$ )
- Number of polygons dep. on tessellation
- Which of these would you rather have if you only had one available?



# Sphere, Torus

- Sphere is described by (radius)
- Torus is defined by (radius1, radius2)
- Number of polygons dep. on tessellation



# Geometric Primitives: Summary

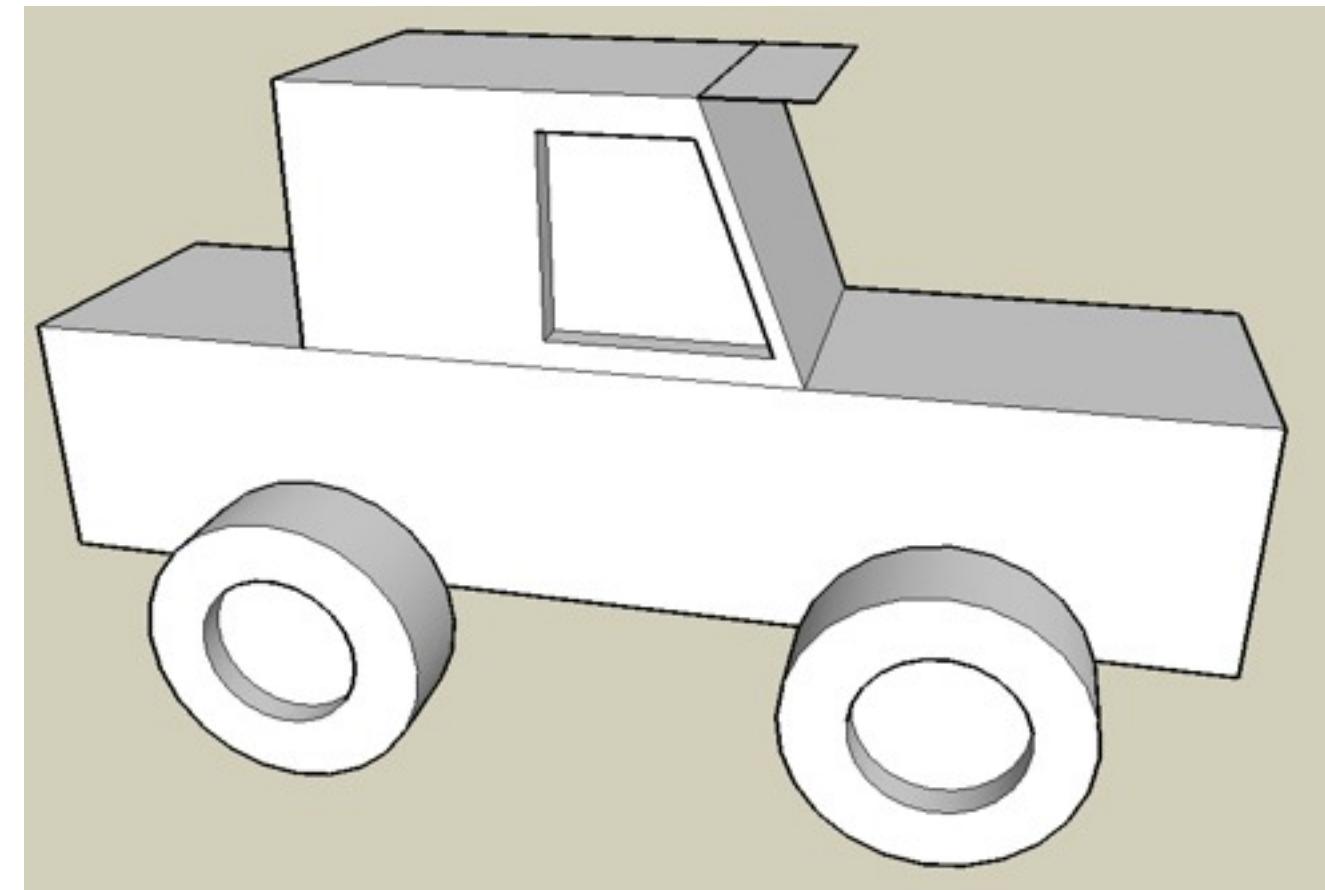
- Not all of these exist in all graphics packages
  - Some packages define additional primitives (dodecahedron, teapot...;-)
  - Practically the only way to model VRML or X3D in a text editor
  - Can give quite accurate models
  - Extremely lean! very few polygons
  - Think of application areas even in times of powerful PC graphics cards!
- 
- 
- 
-

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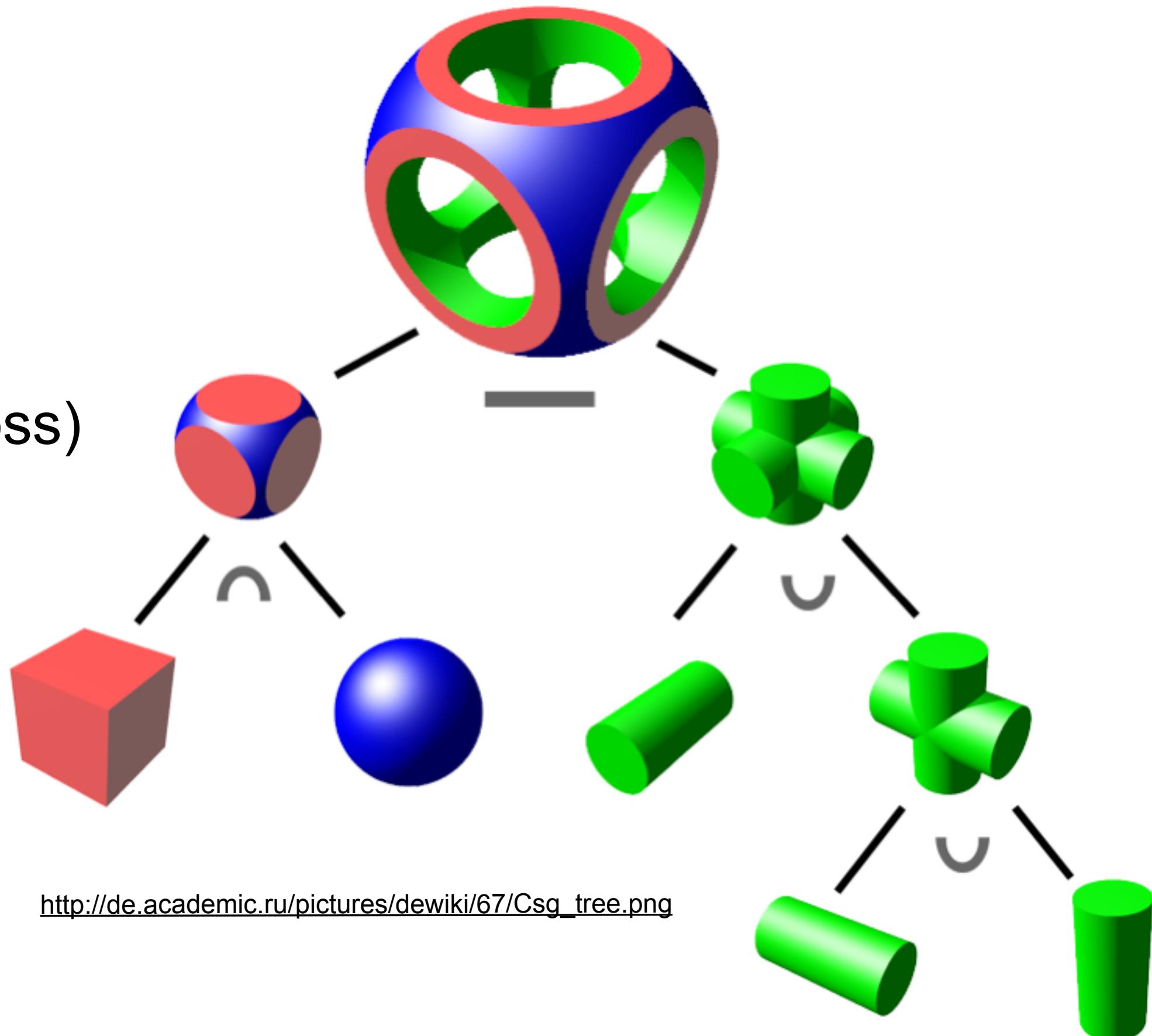
# Constructive Solid Geometry

- Basic idea: allow geometric primitives and all sorts of boolean operations for combining them
- Can build surprisingly complex objects
- Good for objects with holes (often the simplest way)
- Basic operations:
  - **Or**: combine the volume of 2 objects
  - **And**: intersect the volume of 2 objects
  - **Not**: all but the volume of an object
  - **Xor**: all space where 1 object is, but not both
- Think about:
  - wheels of this car
  - tea mug
  - coke bottle (Problems??)



# CSG: a complex Example

- rounded\_cube =  
cube **And** sphere
- cross =  
cyl1 **Or** cyl2 **Or** cyl3
- result =  
rounded\_cube **And** (**Not** cross)
- Think: Are CSG operations  
associative?
  -
- ...commutative?
  -

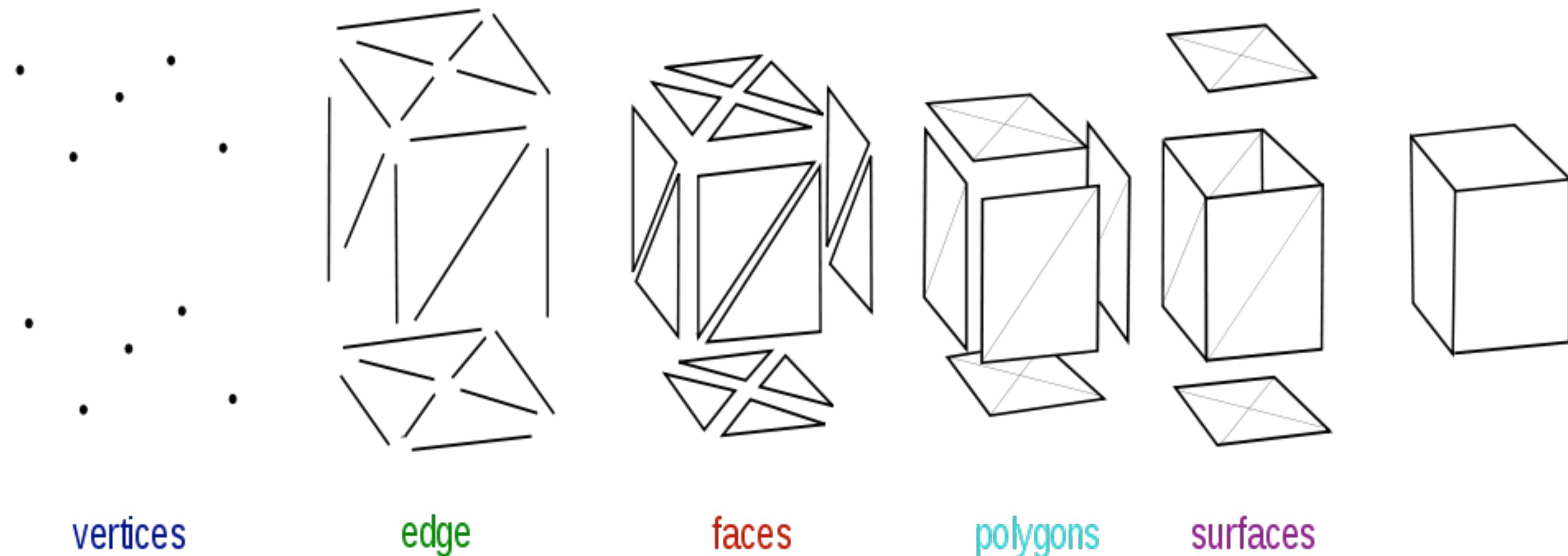


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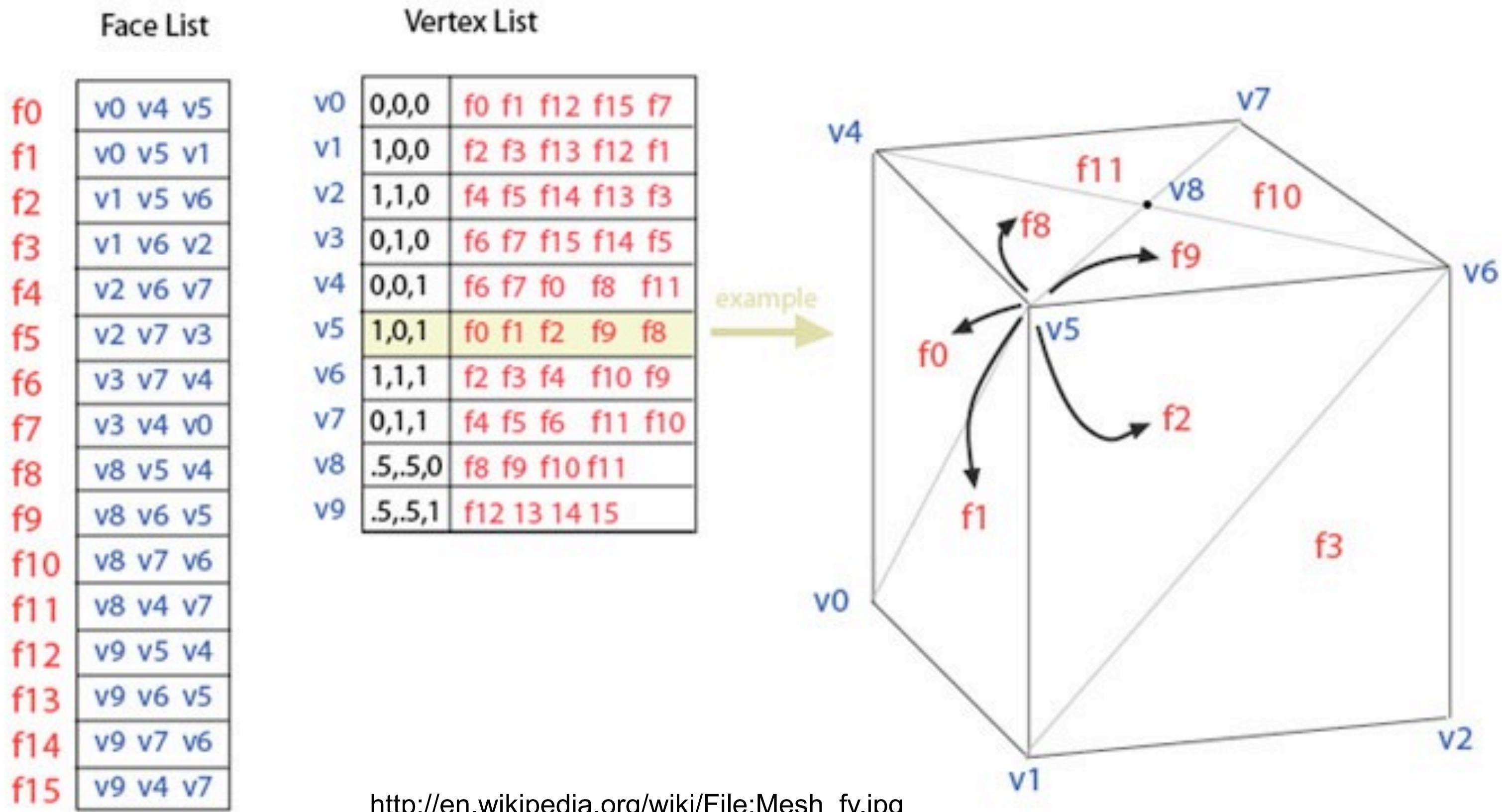
# Polygon Meshes

- Describe the surface of an object as a set of polygons
- Mostly use triangles, since they are trivially convex and flat
- Current graphics hardware is optimized for triangle meshes



[http://en.wikipedia.org/wiki/File:Mesh\\_overview.svg](http://en.wikipedia.org/wiki/File:Mesh_overview.svg)

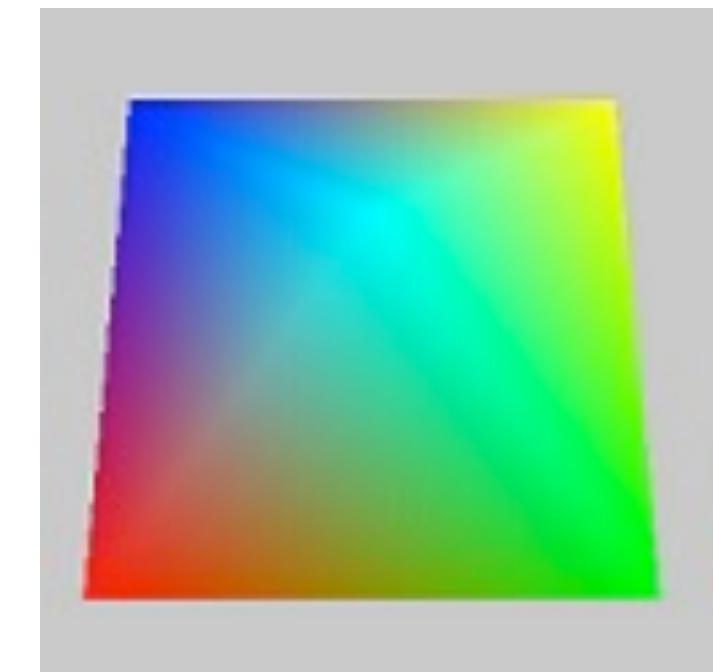
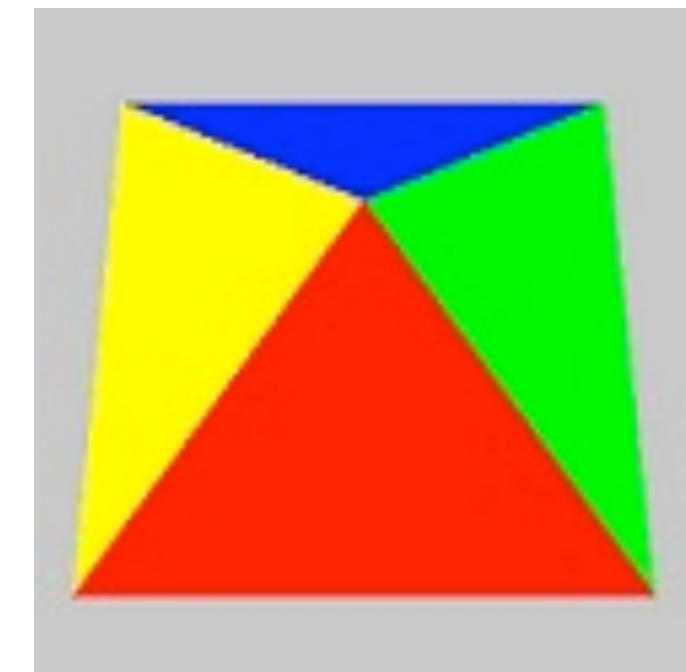
# Face-Vertex Meshes



[http://en.wikipedia.org/wiki/File:Mesh\\_fv.jpg](http://en.wikipedia.org/wiki/File:Mesh_fv.jpg)

# Polygon Meshes: optional data

- Color per vertex or per face: produces colored models
- Normal per vertex: allows free control over the normals
  - can mix smooth and sharp edges
  - wait for shading chapter ;-)
- Texture coordinates per vertex
  - wait for texture chapter ;-)



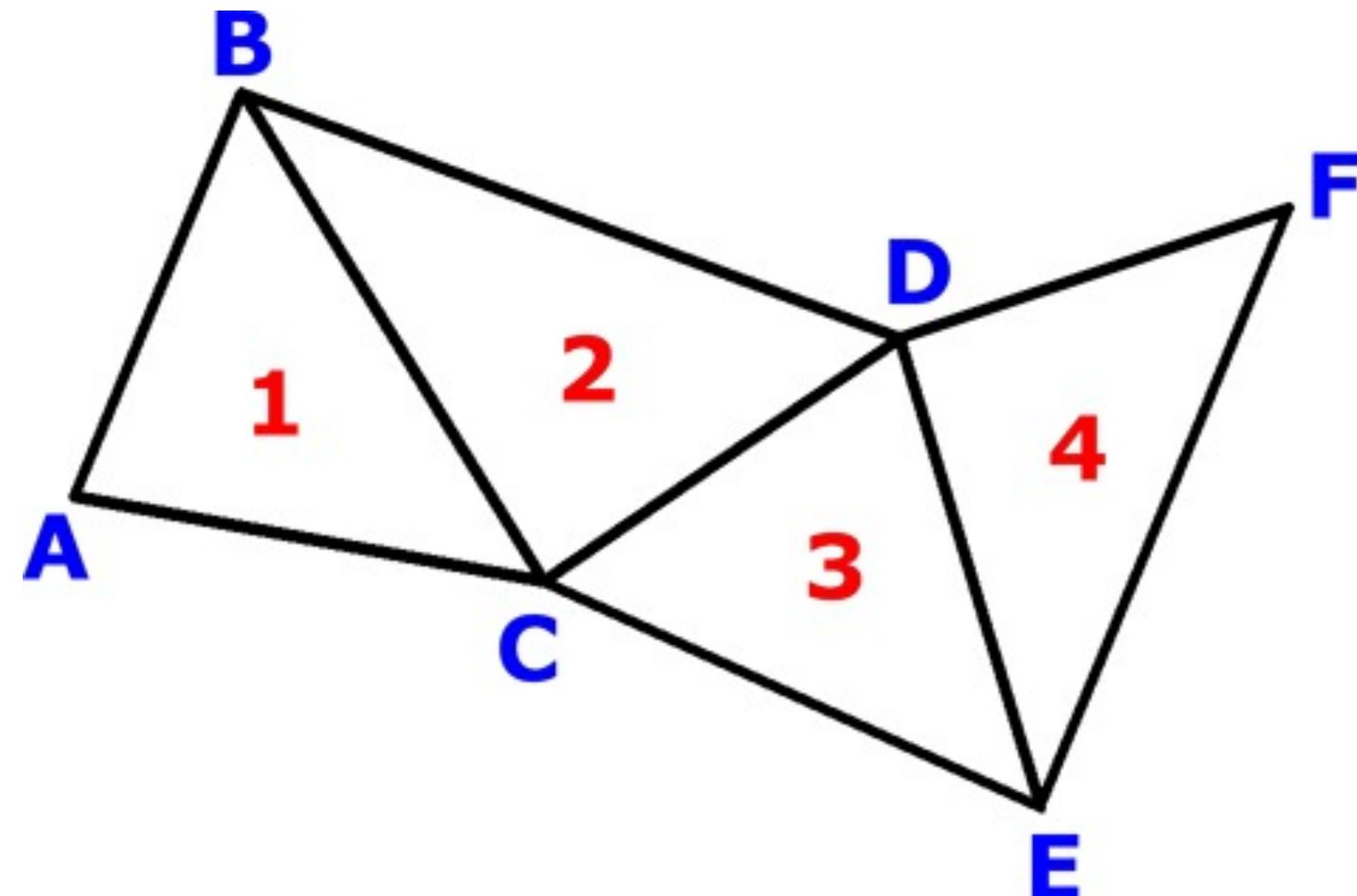
[http://en.wikipedia.org/wiki/File:Triangle\\_Strip.png](http://en.wikipedia.org/wiki/File:Triangle_Strip.png)

# Polygon Meshes: other descriptions

- Other representations for polygon meshes exist
  - optimized for analyzing and modifying topology
  - optimized for accessing large models
  - optimized for fast rendering algorithms
  - optimized for graphics hardware

- Example: triangle strip

- needs  $N+2$  points for  $N$  polygons
  - implicit definition of the triangles
  - optimized on graphics hardware

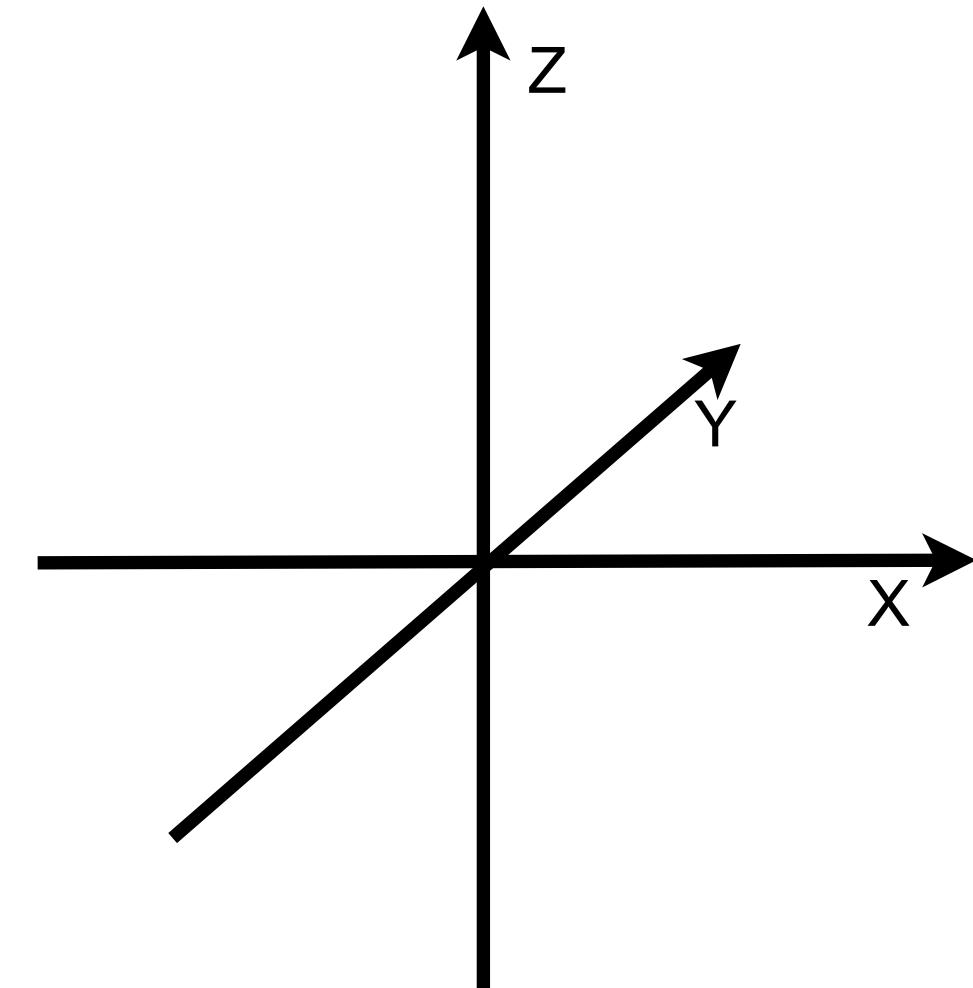


[http://en.wikipedia.org/wiki/File:Triangle\\_Strip.png](http://en.wikipedia.org/wiki/File:Triangle_Strip.png)

# Practical example: VRML IndexedFaceSet

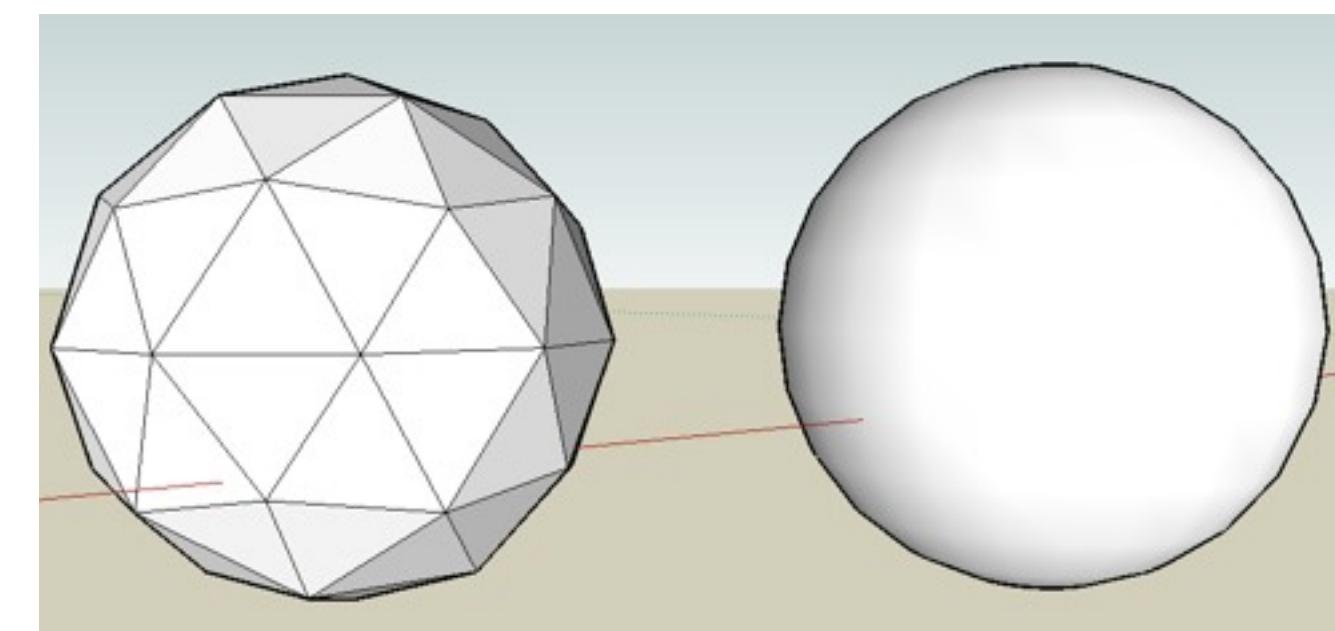
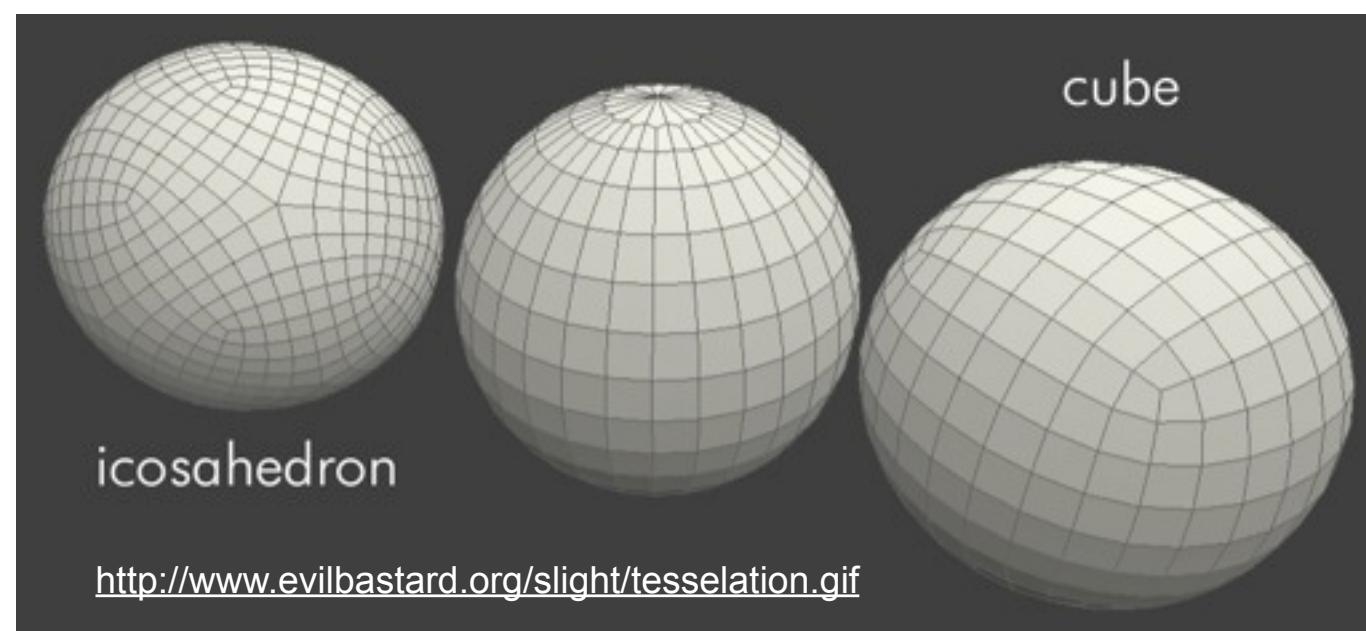
Quiz: what is given by the following piece of VRML code??

```
geometry IndexedFaceSet {  
    coord Coordinate {  
        point [ -1 0 1, 1 0 1, -1 0 -1, 1 0 -1, 0 1 0 ]  
    }  
    coordIndex [ 0, 1, 4, -1,  
                1, 3, 4, -1,  
                3, 2, 4, -1,  
                2, 0, 4, -1,  
                1, 0, 2, 3, -1 ]  
}
```



# Approximating Primitives by Polygon Meshes

- Trivial for non-curved primitives...
- The curved surface of a cylinder, sphere etc. must be broken down into polygons somehow (Tesselation).
- Not trivial and certainly not unique!
- Goal: small polygons for strong curvature, larger ones for areas of weak curvature
  - This means ideally constant polygon size for a sphere
  - Where do I know this problem from??? Hmm...

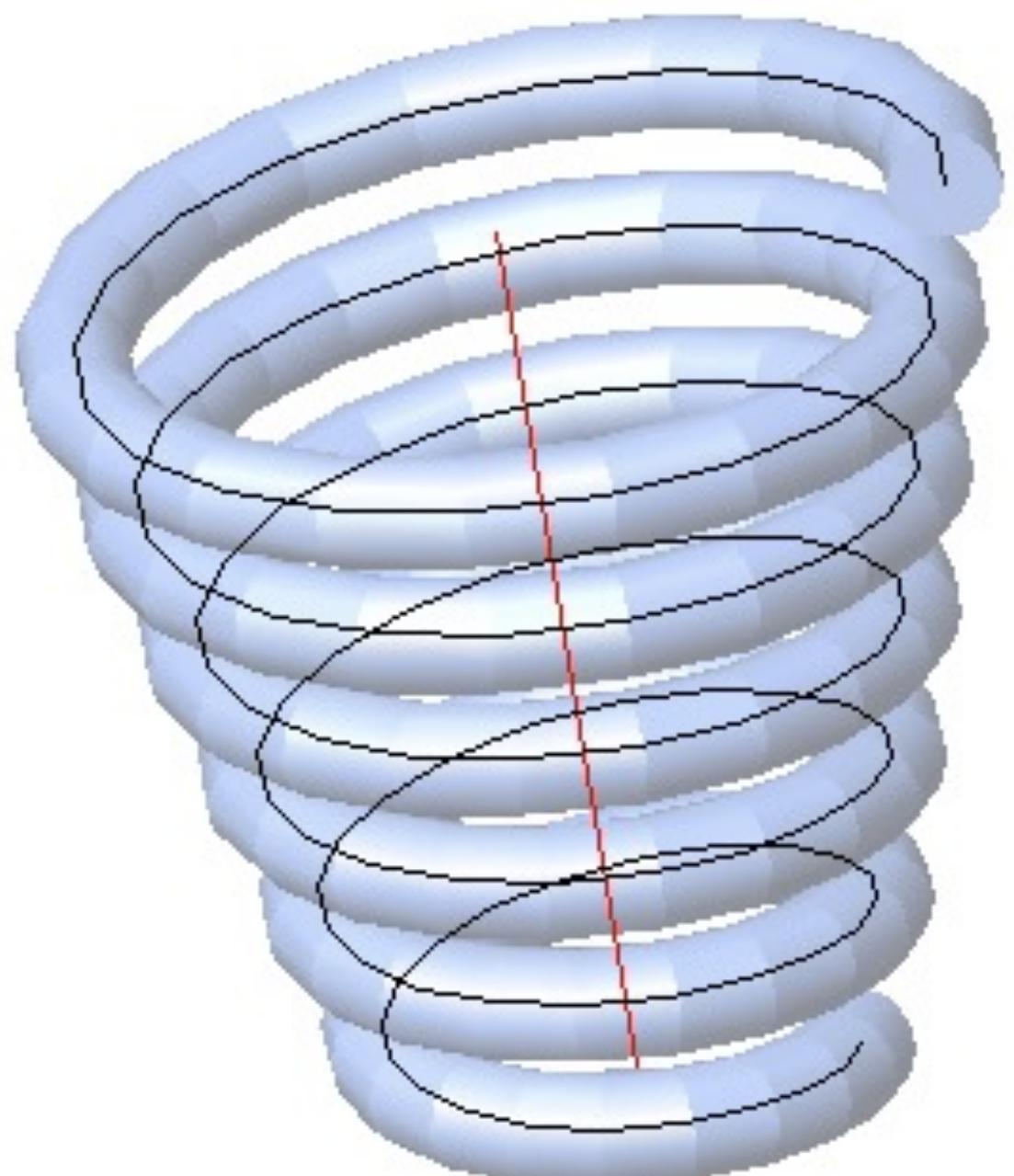


# Chapter 2 - 3D modeling

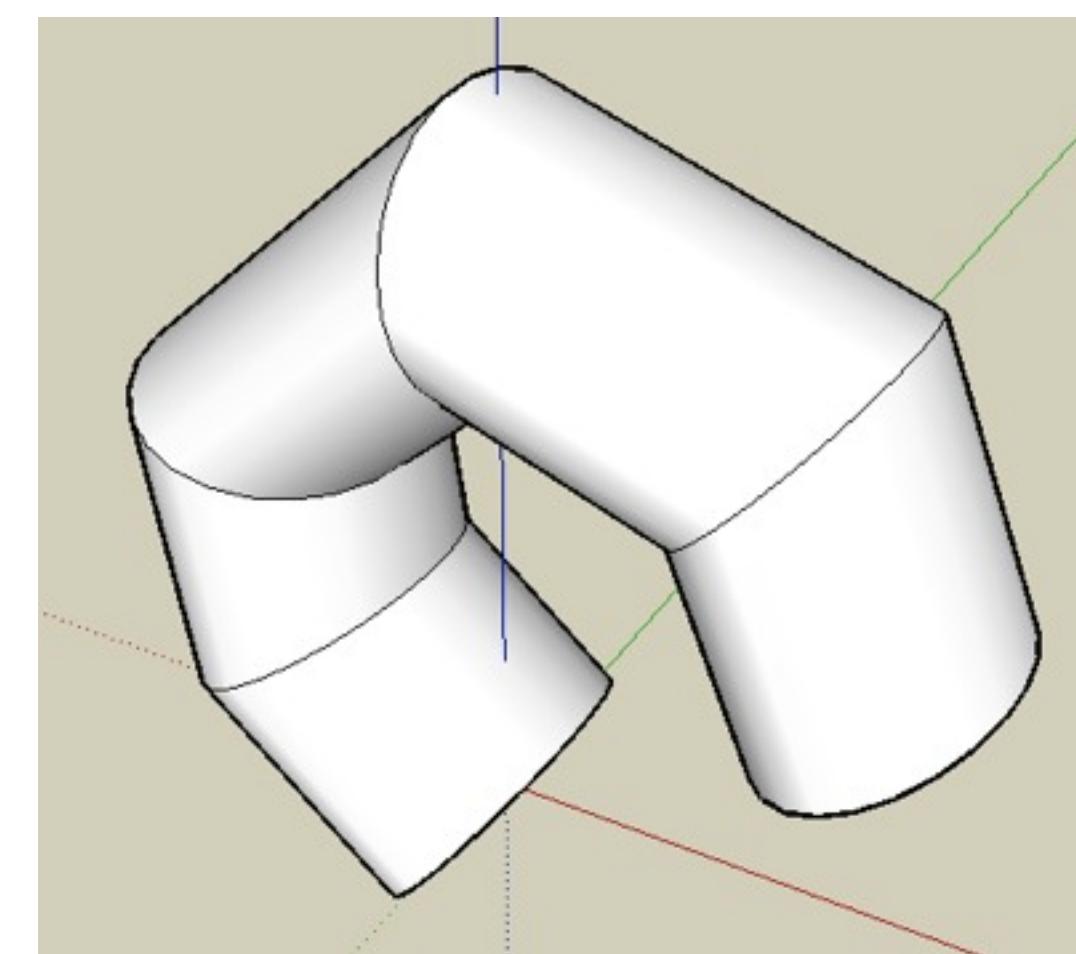
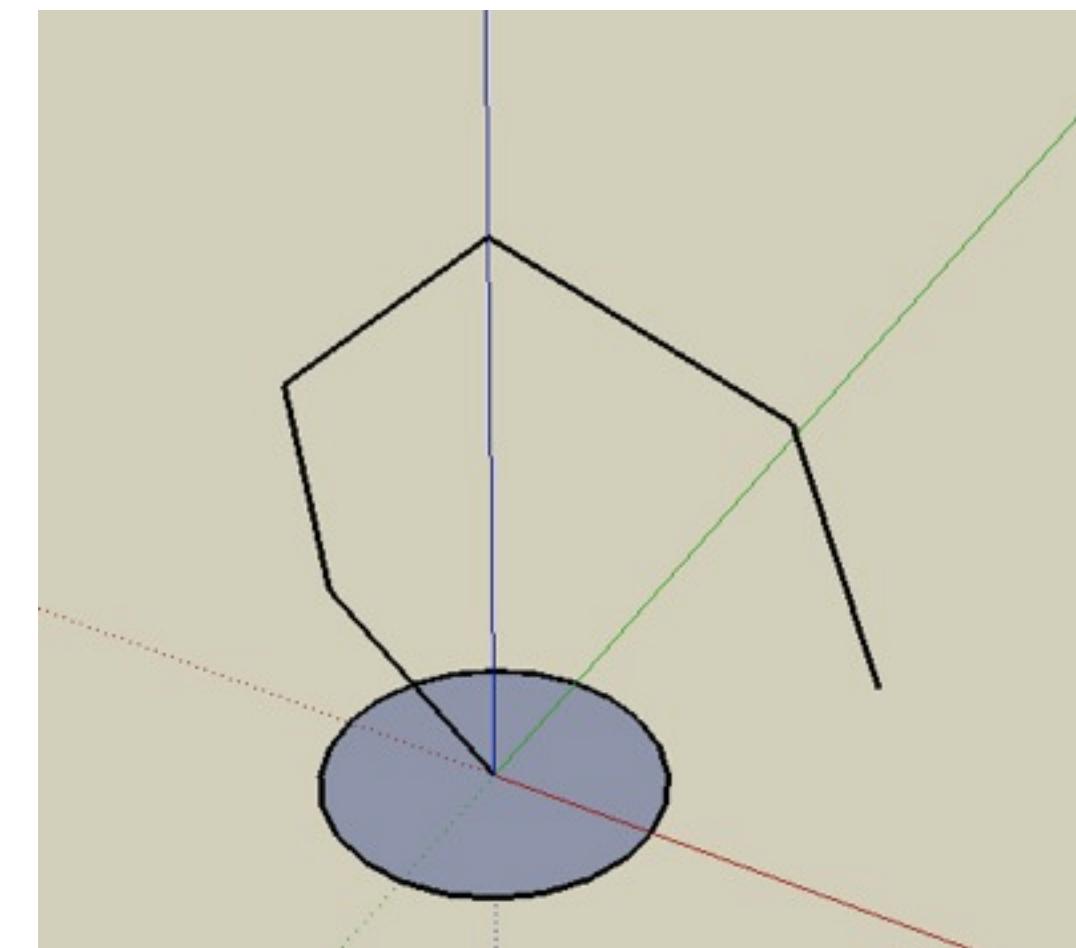
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# Extrusion (sweep object)

- Move a 2D shape along an arbitrary path
- possibly also scale in each step



<http://www.cadimage.net/cadtutor/lisp/helix-02.gif>



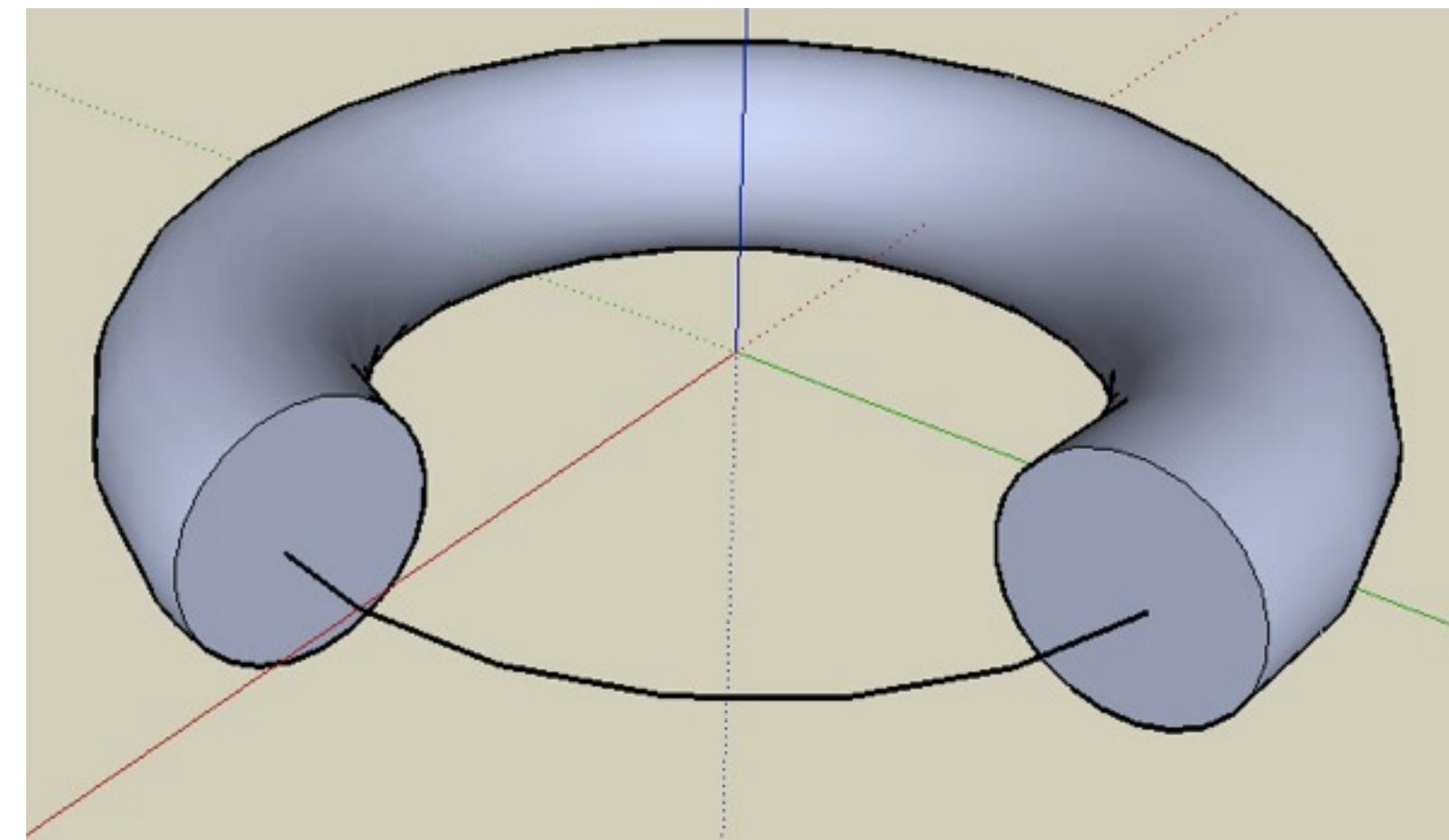
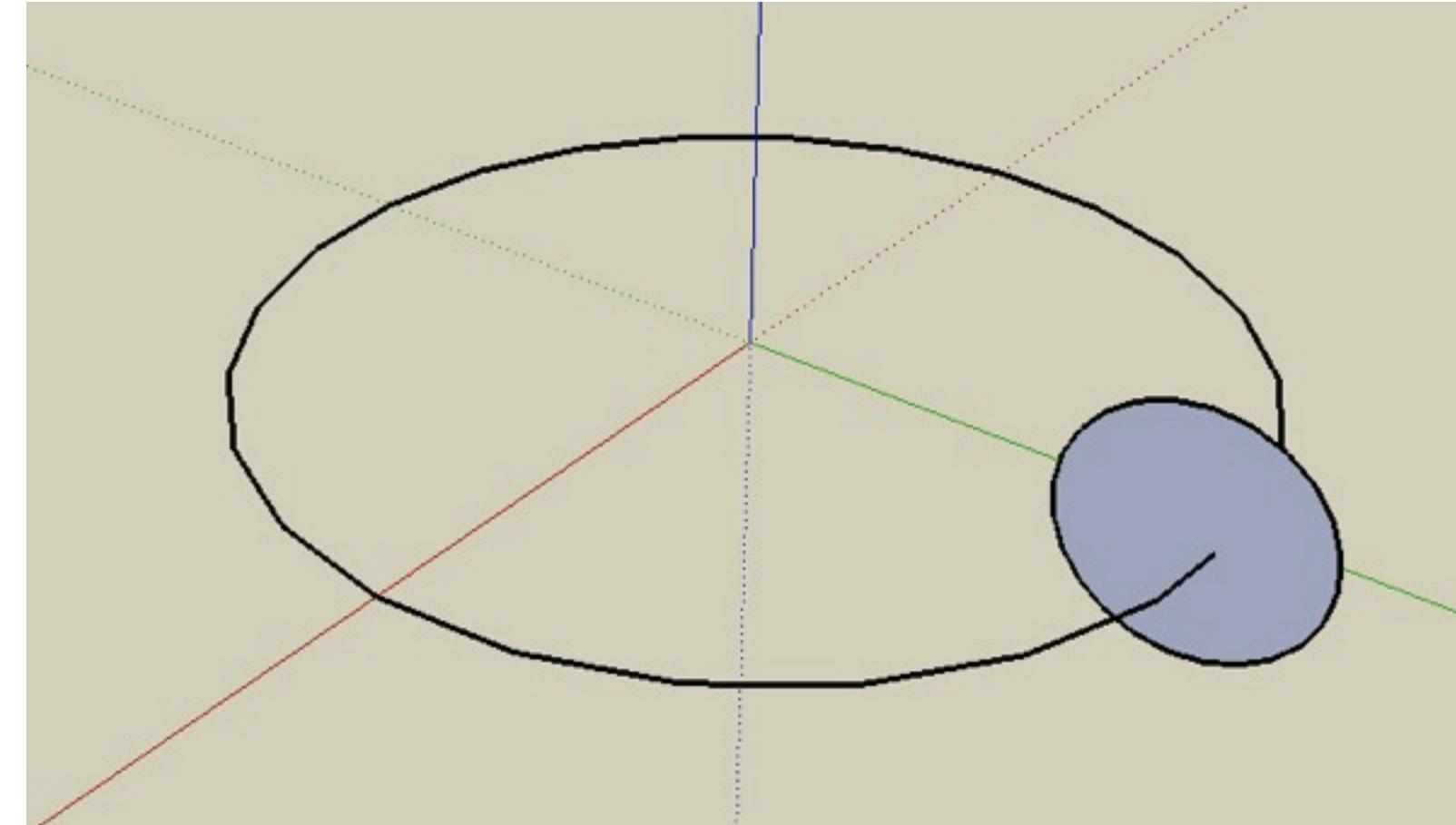
# Rotation

- Rotate a 2D shape around an arbitrary axis
- Can be expressed by extrusion along a circle

- How can we model a vase?

- - - - -

- How a Coke bottle?

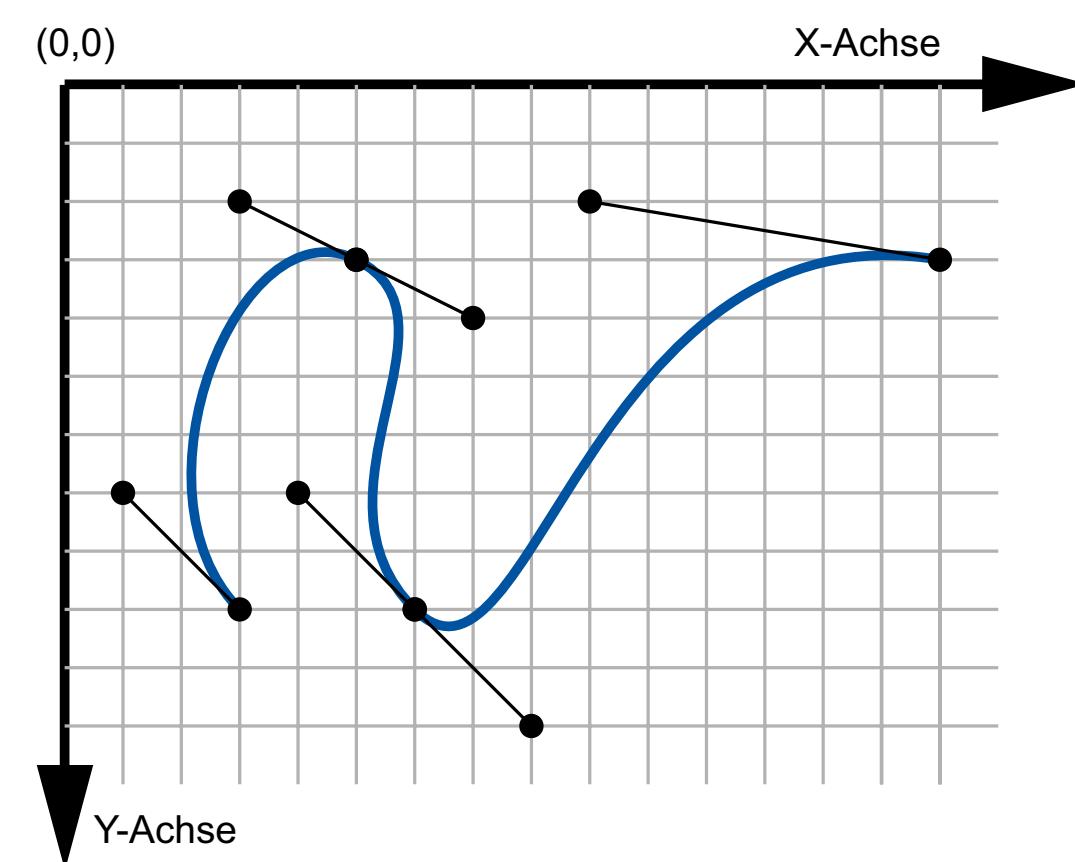
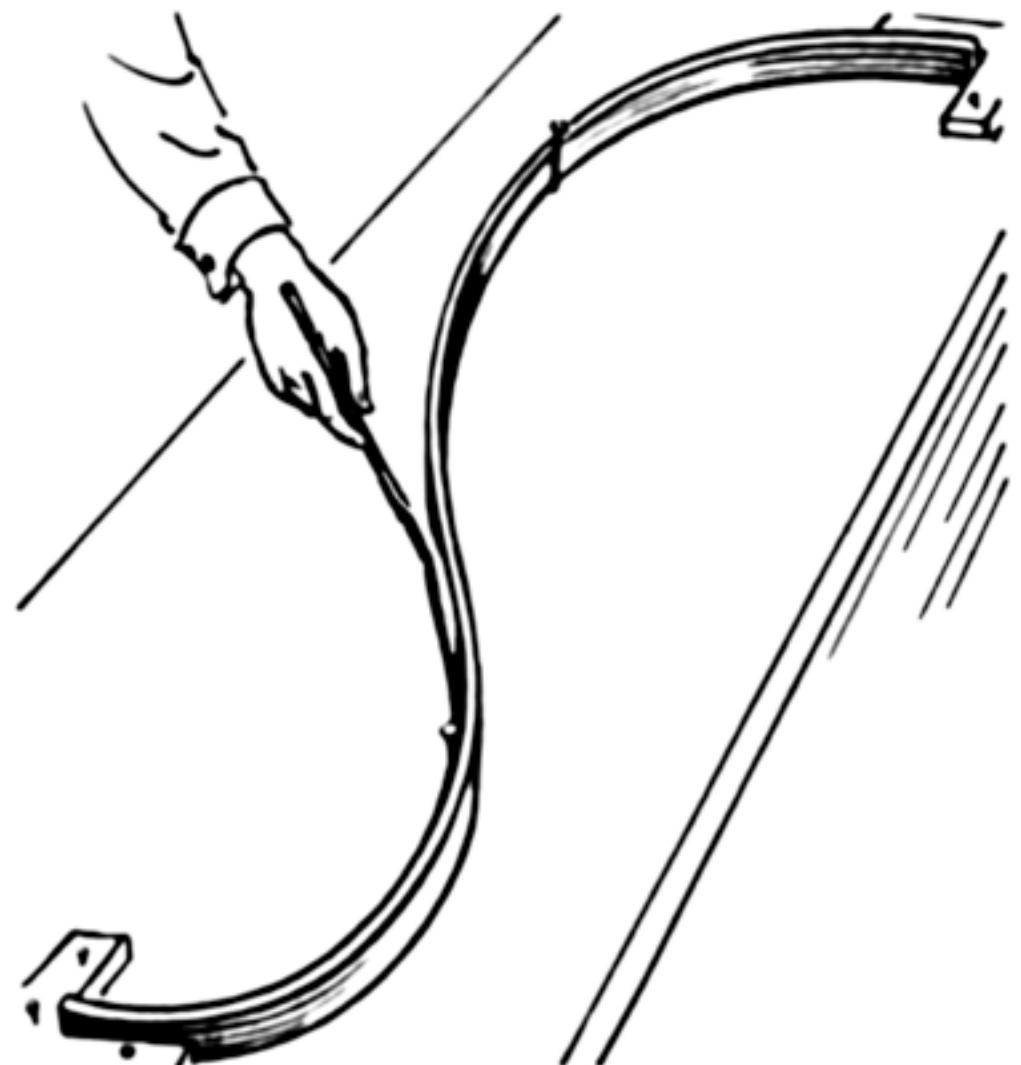


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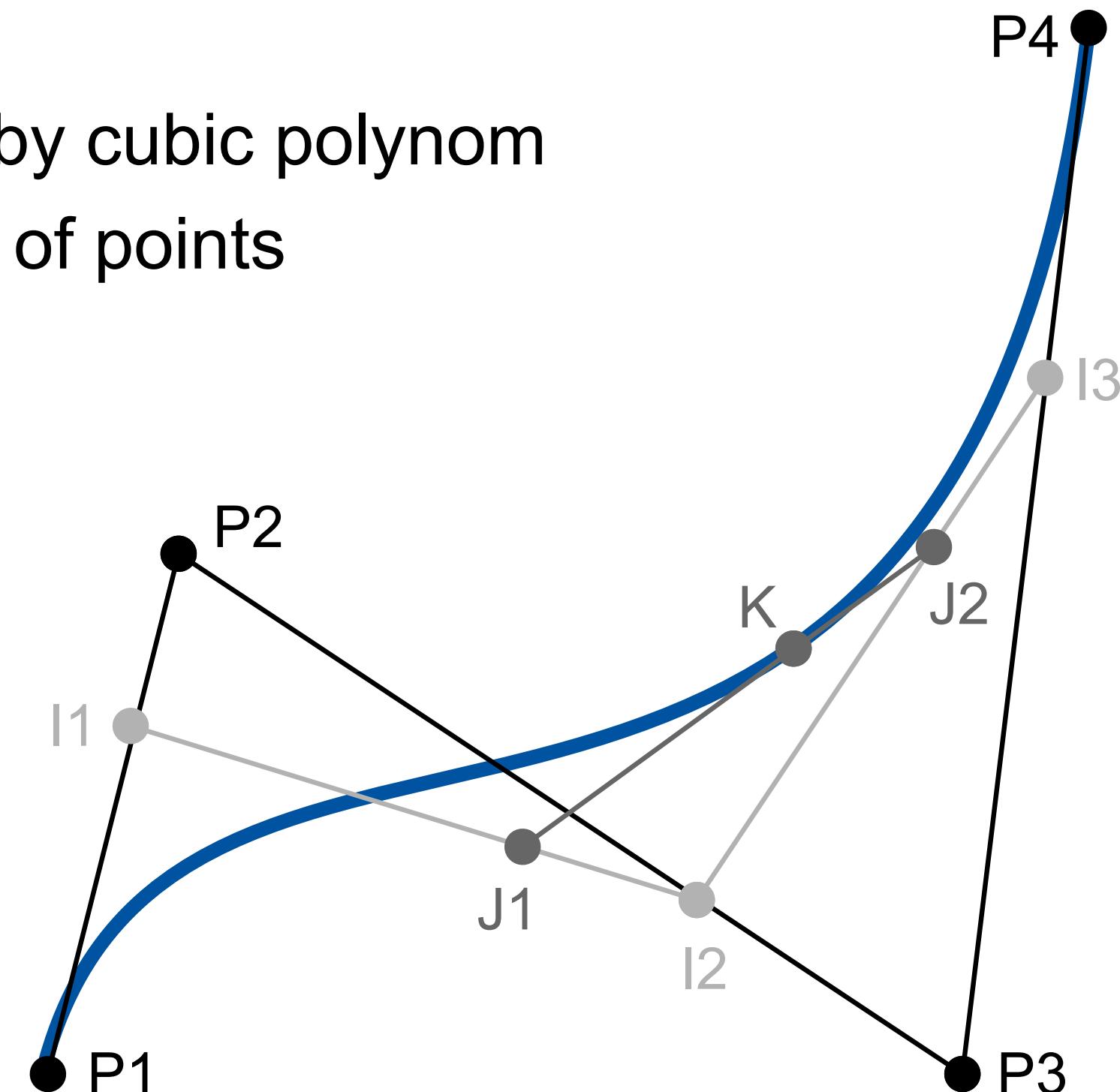
# Interpolation Curves, Splines

- Original idea: „Spline“ used in ship construction to build smooth shapes:
  - Elastic wooden band
  - Fixed in certain positions and directions
  - Mathematically simulated by interpolation curves
  - piecewise described by polygons
- Different types exist
- Control points my be on the line or outside of it.



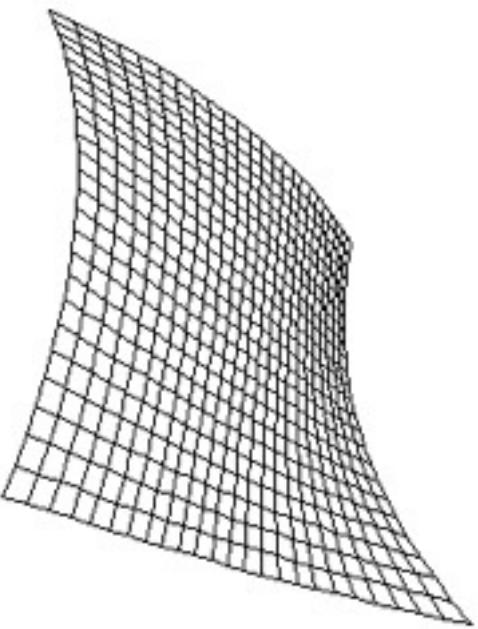
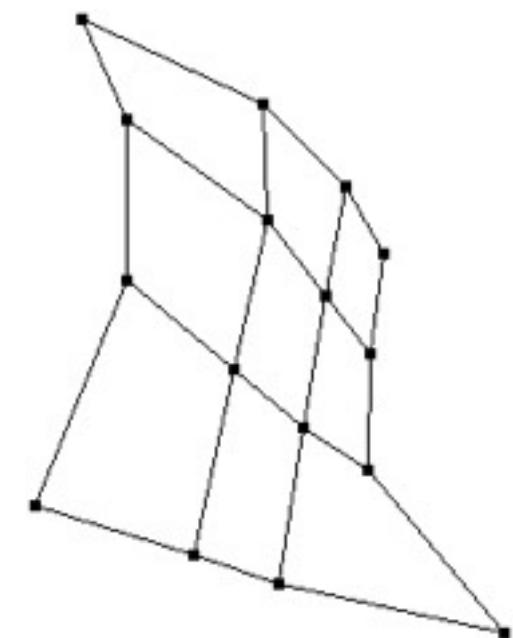
# Bezier Curves (and Casteljau Algorithm)

- Bezier curves first used in automobile construction (1960s, Citroen)
- Degree 1: straight line interpolated between 2 points
- Degree 2: quadratic polynom
- Degree 3: cubic bezier curve, described by cubic polynom
- Curve is always contained in convex hull of points
- Algorithm (defines line recursively):
  - I1 is linearly interpolated between P1 and P2
  - I2 ... between P2 and P3
  - I3 ... between P3 and P4
  - J1 ... between I1 and I2
  - J2 ... between I2 and I3
  - K ... between J1 and J2
  - The bezier curve is the sum of all points K
- see <http://files.dmke.de/bezier.html> !!!



# Bezier patches

- Combine 4 Bezier curves along 2 axes
- Share 16 control points
- Results in a smooth surface
- Entire surface is always contained within the convex hull of all control points
- border line is fully determined by border control points
- several patches can be combined
  - connect perfectly if border control points are the same.
- Other interpolation surfaces based on other curves
- advantage: move just one control point to deform a larger surface...



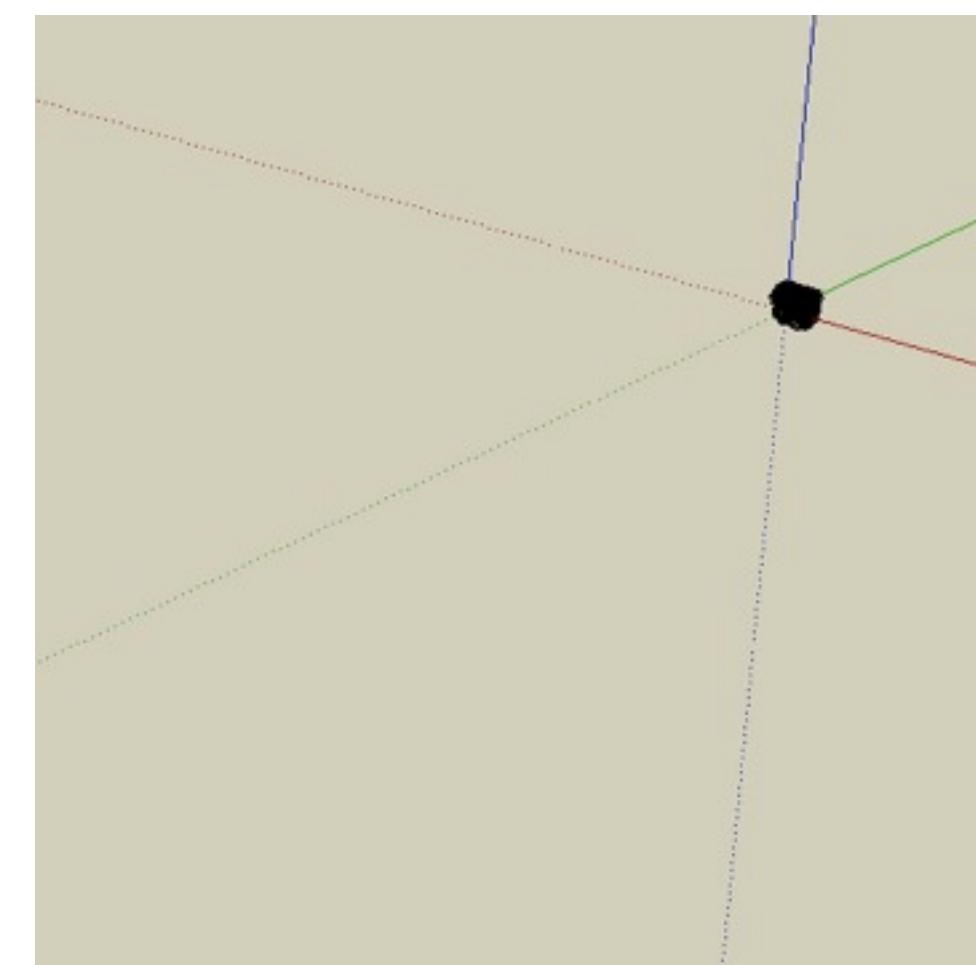
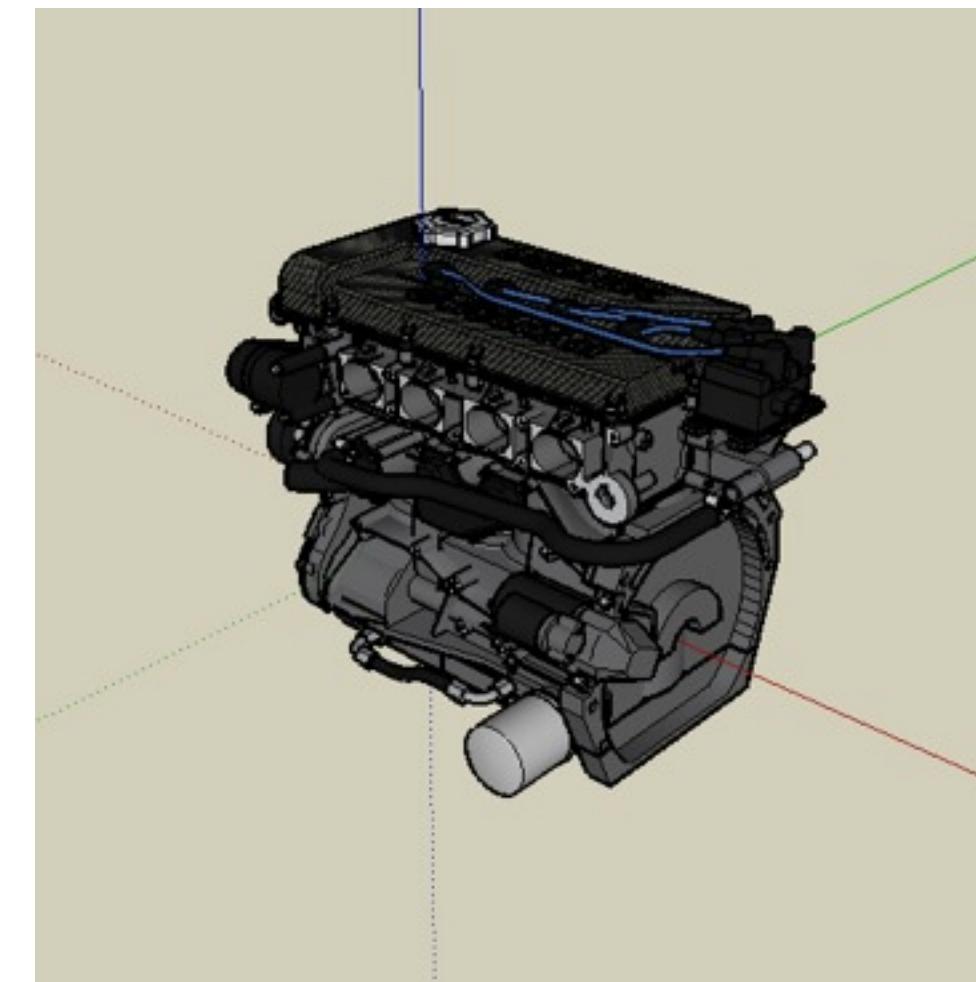


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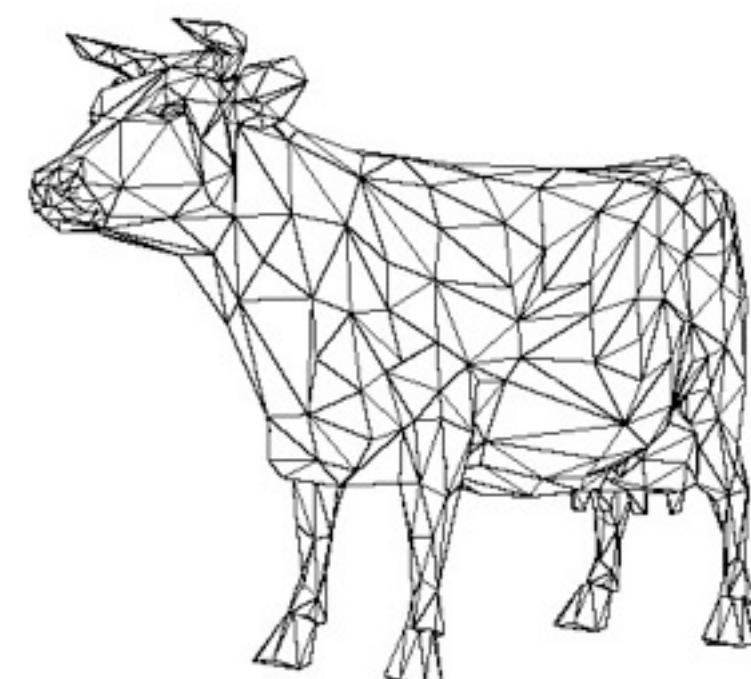
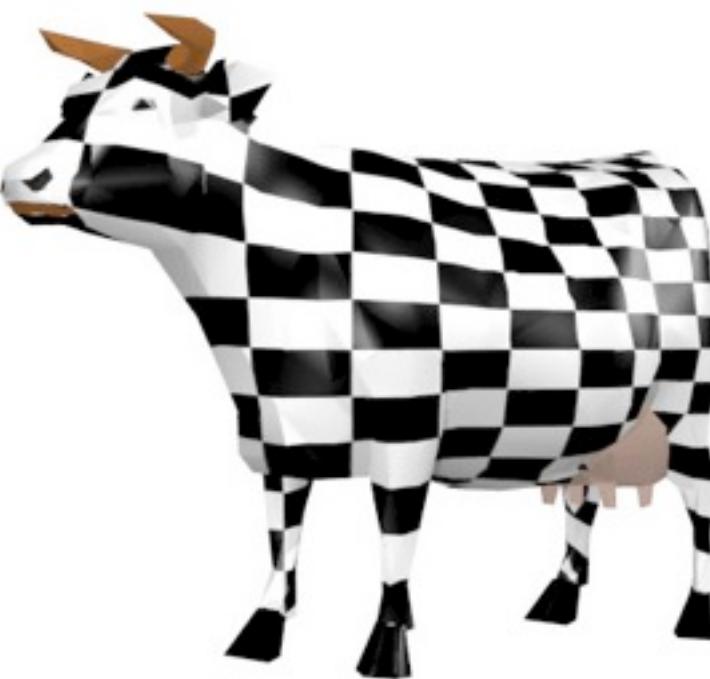
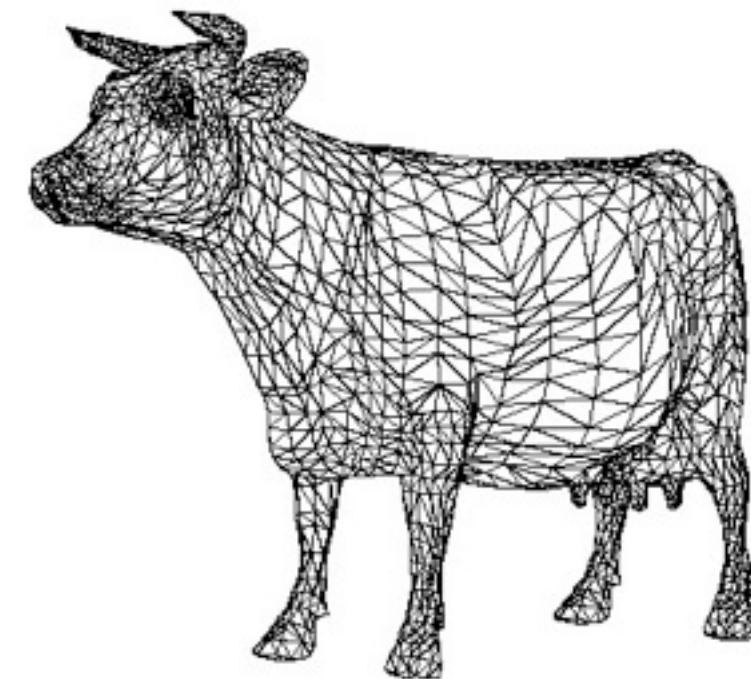
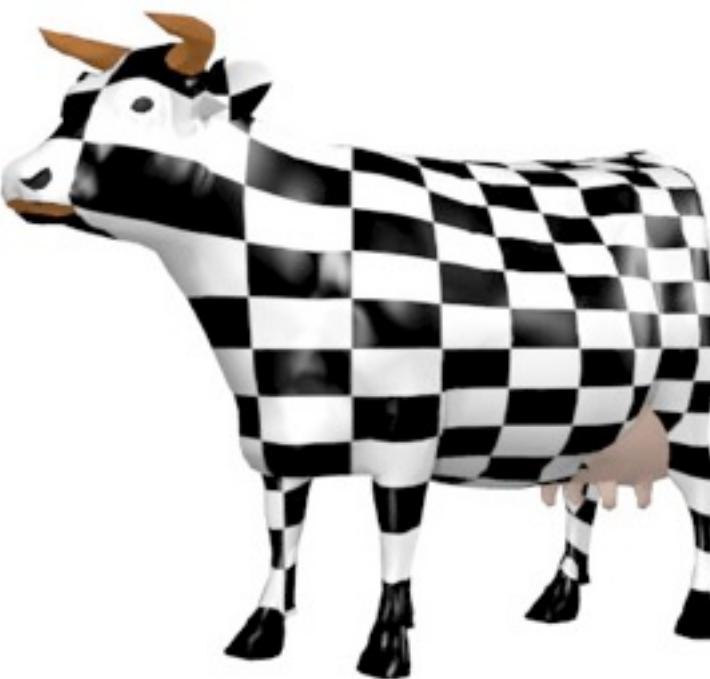
# Levels of Detail

- Assume you have a very detailed model
  - from close distance, you need all polygons
  - from a far distance, it only fills a few pixels
  - How can we avoid drawing all polygons?
- 
- 
- 



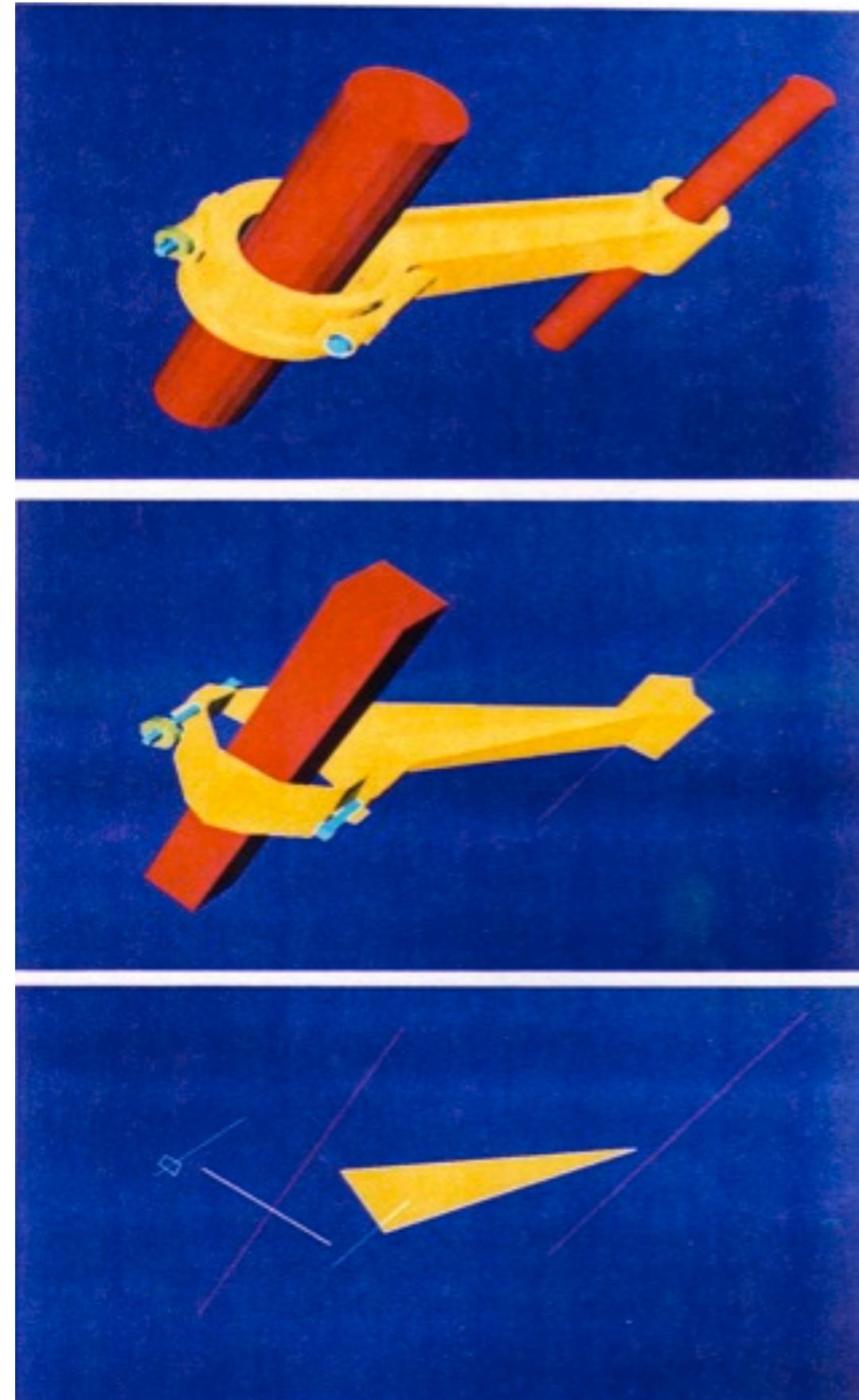
# Mesh reduction

- Original: ~5.000 polygons
  - Reduced model: ~1.000 polygons
  - ==> about 80% reduction
- 
- Very strong reductions possible, depending on initial mesh
  - Loss of shape if overdone



# A method for polygon reduction

- Rossignac and Borell, 1992, „Vertex clustering“
- subdivide space into a regular 3D grid
- for each grid cell, melt all vertices into one
  - choose center of gravity of all vertices as new one
  - triangles within one cell disappear
  - triangles across 2 cells become edges (i.e. disappear)
  - triangles across 3 cells remain
- good guess for the minimum size of a triangle
  - edge length roughly = cell size
- yields constant vertex density in space
- does not pay attention to curvature
- more: <http://mkrus.free.fr/CG/LODS/xrds/>



# Billboard

- A flat object which is always facing you
- Very cheap in terms of polygons (2 triangles)
- Needs a meaningful texture
- Example (from SketchUp): guy in the initial empty world rotates about his vertical axis to always face you

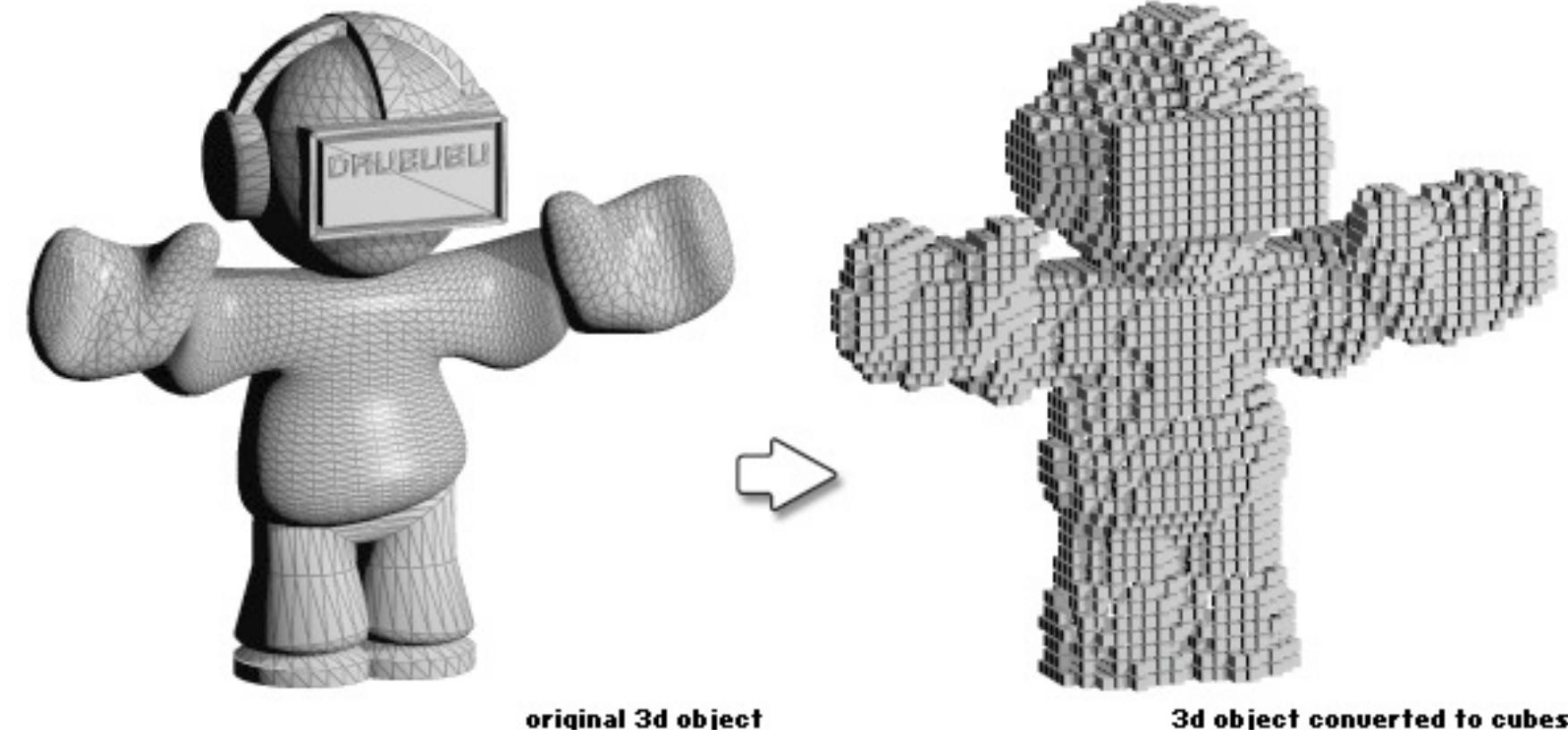


# Chapter 2 - 3D modeling

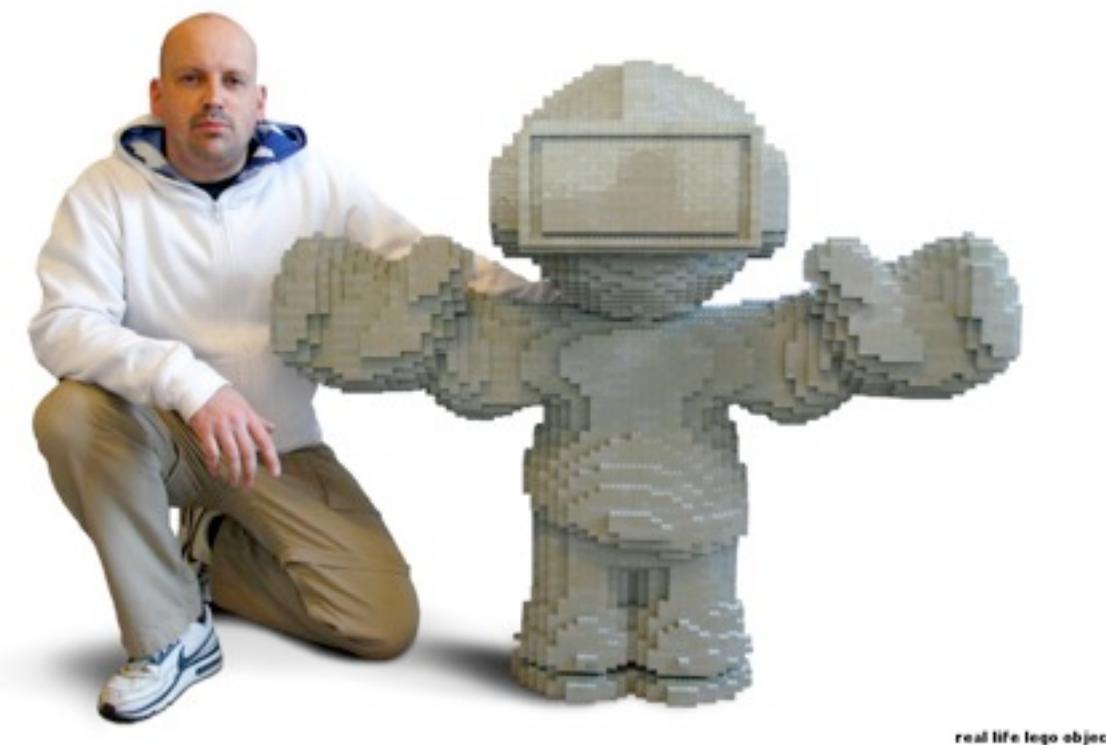
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# Voxel data

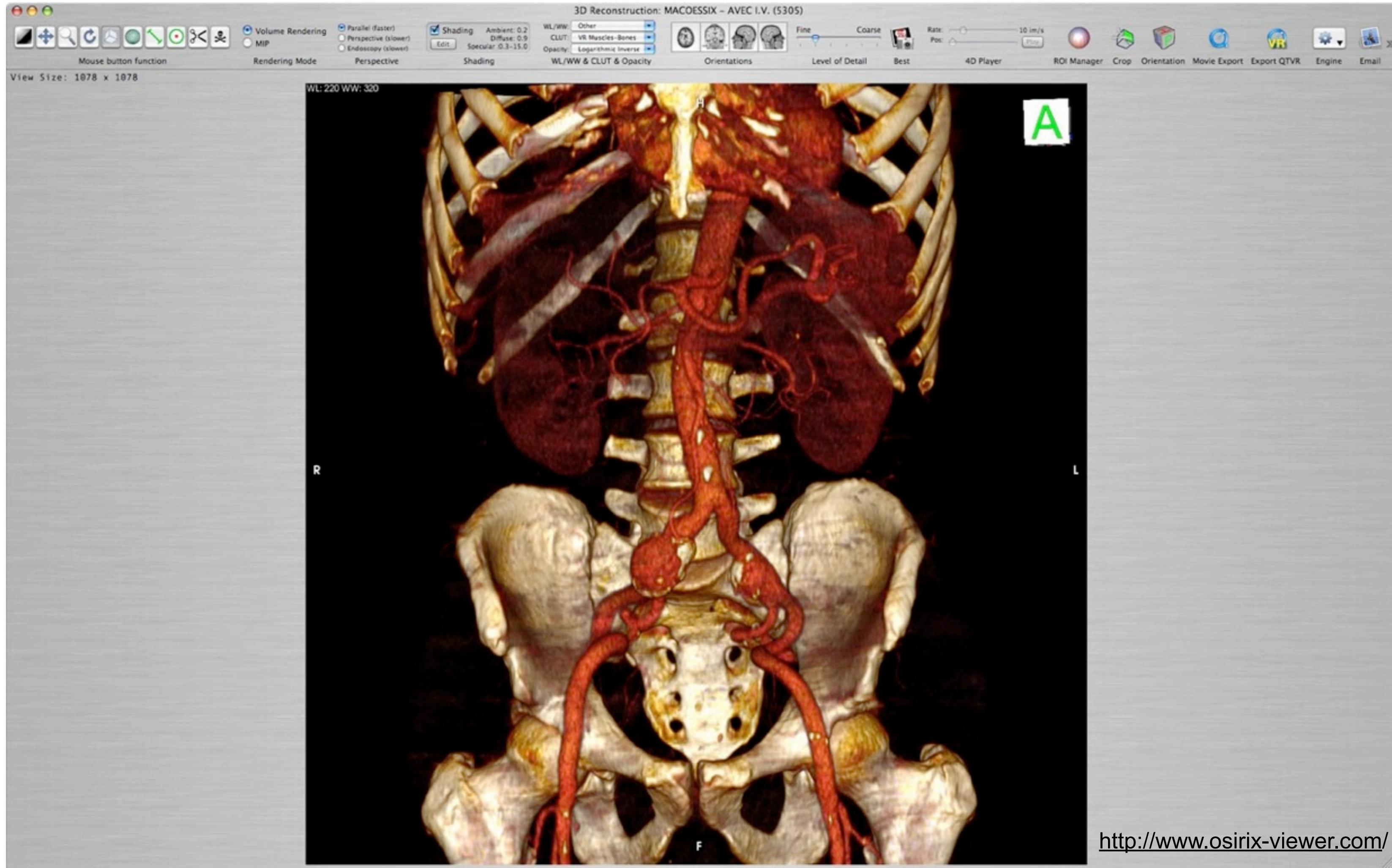
- „Voxel“ = „Volume“ + „Pixel“, i.e., voxel = smallest unit of volume
- Regular 3D grid in space
- Each cell is either filled or not
- Memory increases (cubic) with precision



- Easily derived from CSG models
- Also the result of medical scanning devices
  - MRI, CT, 3D ultrasonic
- Volume rendering = own field of research
- Surface reconstruction from voxels



<http://www.drububu.com/tutorial/voxels.html>



# Point-based graphics

- Objects represented by point samples of their surface („Surfels“)
- Each point has a position and a color
- Surface can be visually reconstructed from these points
  - purely image-based rendering
  - no mesh structure
  - very simple source data (x,y,z,color)
- Point-data is acquired e.g., by 3D cameras
- Own rendering techniques
- Own pipeline
- ==> own lecture ;-)



(C) 2004, CRS4 - Data courtesy of Stanford University