OPEN LAB DAY

05.12.13, 18:00 bis 22:00 Amalienstraße 17

www.medien.ifi.lmu.de/openlab

Correction: CD-gain

- control-display gain = unit free coefficient that maps the movement of the pointing device to the movement of the display pointer
 - -gain = 1: display pointer moves exactly the same distance and speed as the control device
 - gain < 1: display pointer moves slower, covering less distance than the control device
 - gain > 1: display pointer moves proportionality farther and faster than the control device cursor movement.

$$CDgain = \frac{V_{point\,er}}{V_{device}}$$

Literature: Géry Casiez et al., "The impact of Control-Display Gain on User Performance in Pointing Tasks". In HCI, Vol.3 2008, pp. 215-250.

Mobile Technologies context and task challenges input technologies challenges in interaction design output technologies

context and task

challenges

input technologies

challenges in interaction design

output technologies

Theories and Models

- Device Support
 - how HCI research started to consider the kinematic chain
 - spatial relationship to the device affects interaction performance and perceived comfort
 - BiTouch Design Space, extension of Guiard's theory
- Gestural Input
 - what we loose when moving from keyboard and mouse and direct touch interaction
 - missing standards, how to describe gestures?
 - gesture documentation
 - physical approach to gestures
- Hand Occlusion
 - how a controlled experiment can help you to come up with an approximate model of you hand occlusion
 - how that inspires design of interaction techniques
 - how to describe the imprecision by extending Fitt's law

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Device Support

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Complex Multi-limb Coordination

- Bimanual interaction
 - is not the sum of two uni-manual actions
 - remember sketchpad!
- Whole body interaction



bimanual interaction

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- symmetric bimanual action: the two hands have the same role
- asymmetric bimanual action: the two hands have different roles

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Guiard's Kinematic Chain

"Under standard conditions, the spontaneous writing speed of adults is **reduced** by some **20%** when instructions **prevent the non-preferred hand** from manipulating the page"

> l'internetie sit une contrastion qui se developpe génération. I d'une mentre deservationne et seu que l'un pourse la contradai :

> Chand qu'une contraction air une dividen changes dans le cos le plu general, le contractible, mo en prestace d'un combinant (d'inggène de l'are le plus somment) aire apost d'une florence on plus géneralement de chalem prostague d'éclosen d'un forjes d'insende.

> la combustion a lieu en general en place Jajance (flamonen), ben que des anaiers comune la cellulair on la boirs plachat, par, nume part, à l'élai boliche, en mot agaition (bases).

le developpement possible de l'incendre neverste la présence des louis factions contenues indignés souvent présentes schemetiquement en revengle. Il detent de du même stit n'y a pas asses d'ais ou d'assygène, de le combuchble

Literature: Yves Guirad (1987). Asymmetric Division of Labor in Human Skilled Bimanual Action: The Kinematic Chain as a Model

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http://www.lobshots.com/wp-content/uploads/2011/08/lobster_560x375.jpg

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Guiard's principles

- Right-to-left spatial reference

- The non-dominant hand sets the frame of reference for the dominant hand
- Left-right contrast in the spatialtemporal scale of motion
 - Non-dominant hand operates at a coarse temporal and spatial scale
- Left hand precedence in action
- Kinematic chain
 - each limb a motor if it contributes to the overall input motion.
- Kinematic chain theory
 - although separated, the two hands behave like being linked within the kinematic chain.





http://www.lobshots.com/wp-content/uploads/2011/08/lobster_560x375.jpg

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How do people naturally hold tablets?



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frame interaction



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frame sinteoaction







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Gestural Input vs. Keyboard+Mouse

- loosing the hover state
- gesture design
 - 'natural' gestures
 - dependent on culture
 - multi-finger chords (what does that remind you of?)
- memorability
 - short-term vs. long-term retention
- gesture discoverability
 - missing standards
- difficult to write, keep track and maintain gesture recognition code
 - detect/resolve conflicts
 between gestures
- and how to communicate and document a gesture?

MORE INFORMATION

Windows system key combinations

- F1: Help
- CTRL+ESC: Open Start menu
- ALT+TAB: Switch between open programs
- ALT+F4: Quit program
- SHIFT+DELETE: Delete item permanently
- Windows Logo+L: Lock the computer (without using CTRL+A

Windows program key combinations

- CTRL+C: Copy
- CTRL+X: Cut
- CTRL+V: Paste
- CTRL+Z: Undo
- CTRL+B: Bold
- CTRL+U: Underline
- CTRL+I: Italic

Mouse click/keyboard modifier combinations

- · SHIFT+right click: Displays a shortcut menu containing alter
- · SHIFT+double click: Runs the alternate default command (th
- ALT+double click: Displays properties
- SHIFT+DELETE: Deletes an item immediately without placin

General keyboard-only commands

- F1: Starts Windows Help
- F10: Activates menu bar options
- SHIFT+F10 Opens a shortcut menu for the selected item (th
- CTRL+ESC: Opens the Start menu (use the ARROW keys to CTRL+ESC)
- CTRL+ESC or ESC: Selects the Start button (press TAB to select the start button)
- CTRL+SHIFT+ESC: Opens Windows Task Manager
- ALT+DOWN ARROW: Opens a drop-down list box
 ALT+TAB: Switch to protect a drop-down list box
- ALT+TAB: Switch to another running program (hold down the



Hardware

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• touch event:

-touch action (down, move, up)

Stream

Generator

Attribute

Generators

-touch ID (1st, 2nd, etc.)

raw input

- series of touch attribute values
 - direction = NW, hit-target = circle

touch event

stream

matched

gestures

Gesture

Picker

Confidence

Calculators

Gesture

Matcher

Gestures

execute

gesture

callback



output technologies

move-with-first-touch-on-star-object-inwest-direction

Literature: Kin,K. et al. "Proton++: A Customizable Declarative Multitouch Framework", UIST 2012

 $M_1^{s:W}$

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output technologies consider attributes: hit-target shape, direction

Proton++ Gesture

 $E_{T_{ID}}^{A_1:A_2:A_3\ldots}$

these touch event symbols

where $E \in \{D, M, U\}$, attribute values $A_1: A_2: A_3, A_1$ corresponds to first attribute etc.

describe a gesture as regular expression over

 $D_1^{S:N}M_1^{S:N}U_1^{S:N}$

context and	Proton++ Gesture
task	 describe a gesture as regular expression over
challenges	these touch event symbols
Device Support	$E_{T_{ID}}^{A_1:A_2:A_3}$ where $E \in \{D,M,U\}$, attribute values $A_1:A_2:A_3, A_1$ corresponds to first attribute etc.
Gestural Input	1 Minute Micro Task:
input technologies	Create the regular expression for this gesture
challenges in interaction design	
output technologies	consider attributes: hit-target shape, direction

context and task

challenges

Device Support

Proton++ Gesture

 $E_{T_{ID}}^{A_1:A_2:A_3\ldots}$

 describe a gesture as regular expression over these touch event symbols

Gestural

input technologies

Input

challenges in interaction design

output technologies consider attributes: hit-target shape, direction where $E \in \{D,M,U\}$, attribute values $A_1:A_2:A_3$, A_1 corresponds to first attribute etc.

 $D_1^{S:N|S} M_1^{S:N|S} * U_1^{S:N|S}$ $(D_1^{s:N} | D_1^{s:S}) (M_1^{s:N} | M_1^{s:S}) * (U_1^{s:N} | U_1^{s:S})$



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Custom Attributes

- for example a pinch attribute:
 - relative movements of multiple touches
 - touches are assigned a 'P' when on average the touches move towards the centroid, an 'S' when the touches move away from the centroid and an 'N'when they stay stationary



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Further Attributes

- Direction Attribute
- Touch Area Attribute
- Finger Orientation Attribute
- Screen Location Attribute

\rightarrow Let's practice that in the exercise

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But: how can we represent this?

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output technologies



Shape-based interaction

- Interaction in the real world uses not just contact points
- We use whole hands, arms, tools
- Cannot be adequately expressed using just contact points
- How can we deal with this?
- Remember the lava lamp in Jeff Han's TED talk? (http://www.youtube.com/watch?v=QKh1Rv0PIOQ)
- Seriously: How can we do useful stuff with this?





Idea: Interaction using a physics simulation

- Take a ready-made physics engine for games
- Represent every interface object as a 3d physical object
- Assign proper weight and friction
- Entire interface behaves like real physics
- How do we deal with shape input?
- Idea: proxy objects
- Material on the following slides by Otmar Hilliges

Approach: Proxy Objects





- [Otmar Hilliges, UIST2008 best paper]
- Special objects introduced into the simulation per contact point
- Incarnation of fingertips in the virtual world
- Collide with other objects and push them aside.

Leveraging Collision Forces



Leveraging Friction Forces



Particle Proxies

- Idea: model contact shape with many proxy objects (particles)
- Collisions obey shape of the contact (e.g., flat or side of the hand)
- Distribution of forces is modeled more accurately (e.g., conforms to 3D shape)













From Tracking to Flow





context and task

challenges

Device Support

Gestural Input

Occlusion

input technologies

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- problem: system generated messages may be positioned under the user's hand.
- one approach: experimental study using a novel combination of video capture, augmented reality marker tracking, and image processing techniques to capture occlusion silhouettes.
- result: five parameter geometric model which matches the silhouette with larger precision than the simple bounding box approach
- useful for occlusion aware interfaces

Literature: Vogel, D. et al. (2009). Hand Occlusion with Tablet-sized Direct Pen Input, CHI'09

Occlusion



Vogel's Controlled Experiment

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(b)

- home target: on the far right side
- measurement target: positioned somewhere on an invisible grid (7 x 11 = 77 different locations)

Literature: Vogel, D. et al. (2009). Hand Occlusion with Tablet-sized Direct Pen Input, CHI'09

(a)

Image Processing

context and task

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- Frame extraction: video frames taken between successful down and up pen event.
 - synchronize video and data log similar to a movie clapperboard: blend in a large red square containing a unique number.
 - Rectification: track fiducial and determine screen corners
 - Isolation: blur filter (noise reduction) + extract blue color channel + applied threshold to create an inverted binary image.

Image Processing

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- Frame extraction: video frames taken between successful down and up pen event.
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Results

- largest occlusion when tapping the top left corner (occlusion rate: 38.8%)
- identified 3 grips
 - large within-subject consistency in occlusion shape.
 - "can we find a simple geometric model that could describe the general shape and position of the occlusion silhouettes?"







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Scalable Circle and Pivoting Rectangle Model

- 5 parameters:
 - q offset from pen position to circle edge
 - -r radius of the circle
 - $-\phi$ rotation angle of circle around p
 - Θ rotation angle of rectangle around the center of the circle
 - w width of rectangular representation of forearm.





Literature: Vogel, D. et al. (2009). Hand Occlusion with Tablet-sized Direct Pen Input, CHI'09

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Occlusion-aware techniques

Occlusion-Aware Interfaces

Daniel Vogel^{1,2} and Ravin Balakrishnan¹

¹Dept. of Computer Science University of Toronto, CANADA ²Dept. of Math & Computer Science Mount Allison University, CANADA

http://www.youtube.com/watch?v=4sOmIhEJ2ac

Occlusions and the Fat Finger Problem

- Fingers and hands can occlude screen objects

 minimize by adapting the screen layout!
- Fingers may hit several small objects

 just use large objects ;-)
- Exact hit point is occluded, precision limited!



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Fat Fingers and FFitts law

- For small targets and fat fingers, there is a limit to pointing precision!
 - Fitt's law fails to predict performance in this situation
- Modify Fitt's law formula to account for precision – think of it like of Newtonian and relativistic physics:
 - at small speeds, both are the same
 - towards the speed of light, they differ

$$T = a + b \log_2 \left(\frac{A}{W} + 1\right) = a + b \log_2 \left(\frac{A}{\sqrt{2\pi e}\sigma} + 1\right)$$
$$T = a + b \log_2 \left(\frac{A}{\sqrt{2\pi e}(\sigma^2 + \sigma_a^2)} + 1\right)$$

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Take-away message

- Three on-going research challenges with touch and pen input
 - device support
 - -gestural input
 - occlusion & fat fingers
- Approaches:
 - analyzing interaction using the kinematic chain
 - apply, extend and test existing theories from other fields (psychology, mathematics, linguistics, physics)
- In particular: the body's spatial relationship affects interaction performance and perceived comfort (was that the case in desktop env.?)

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