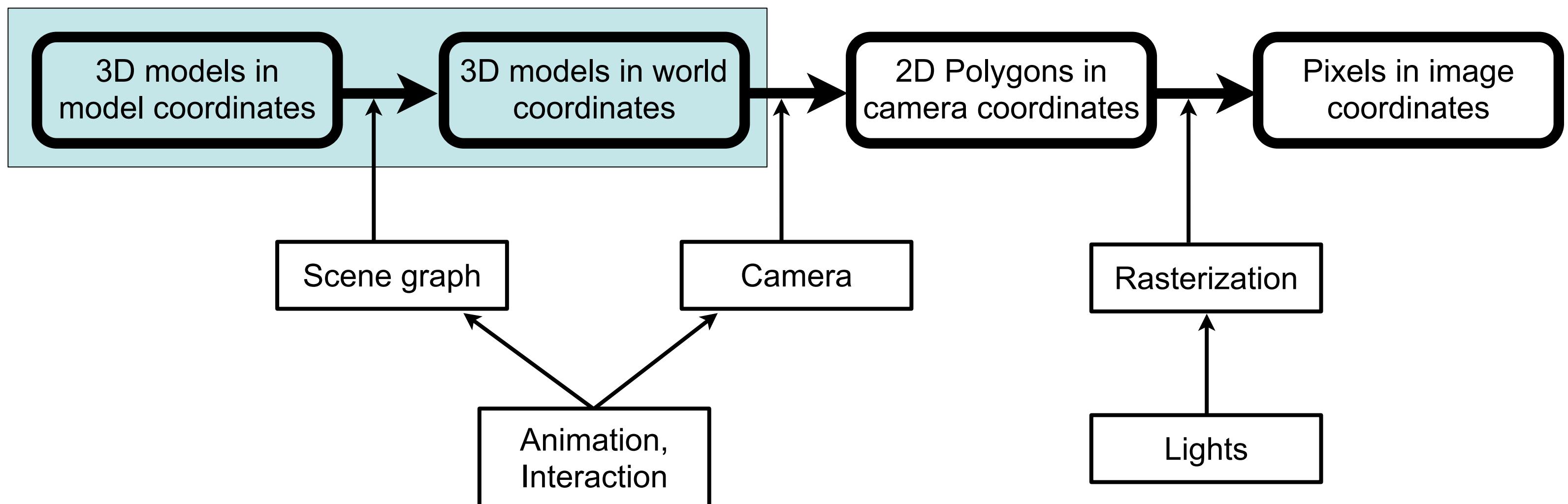


Computer Graphics 1

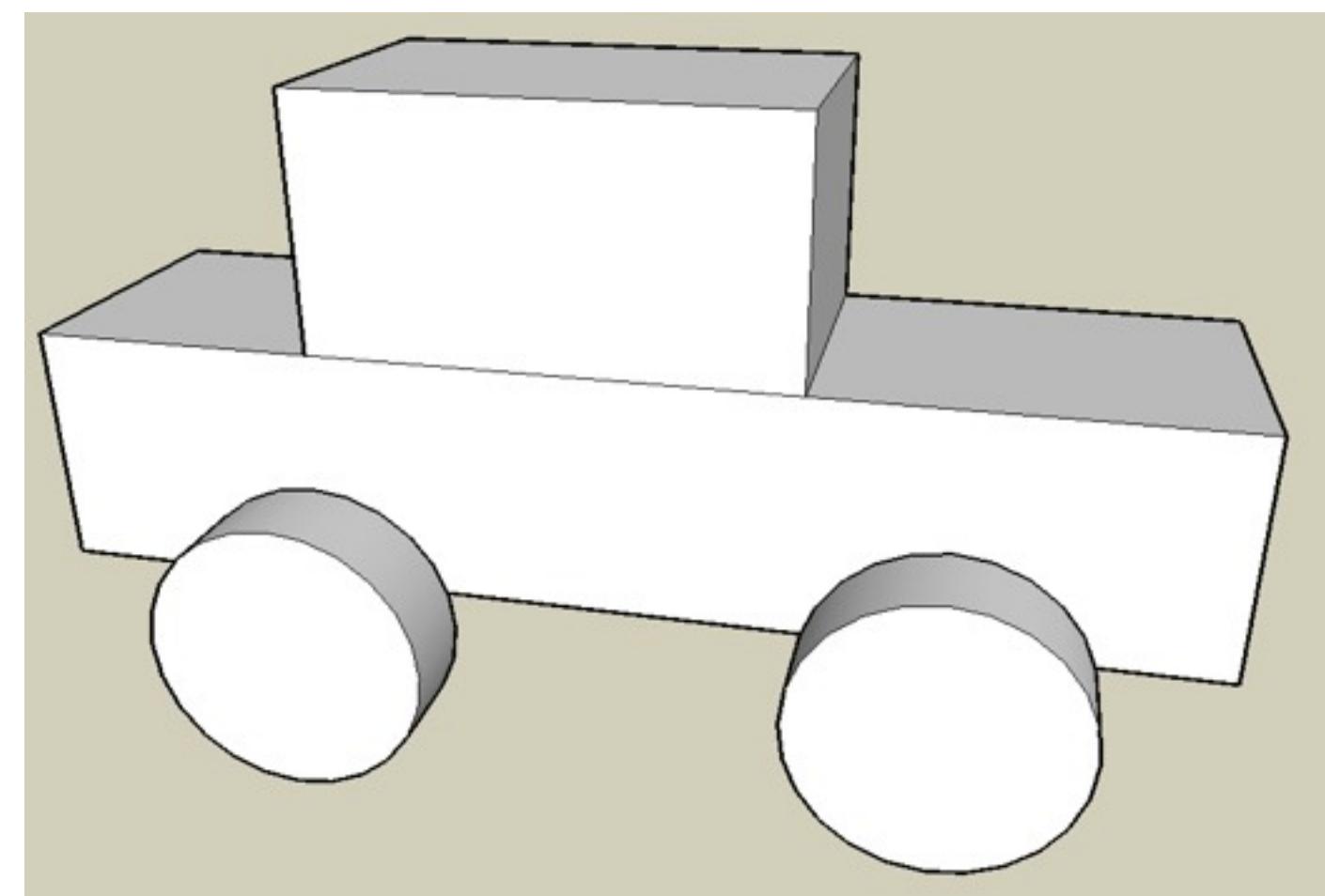
Chapter 2 (April 29th, 2010, 2-5pm):
3D models and their descriptions

The 3D rendering pipeline (our version for this class)



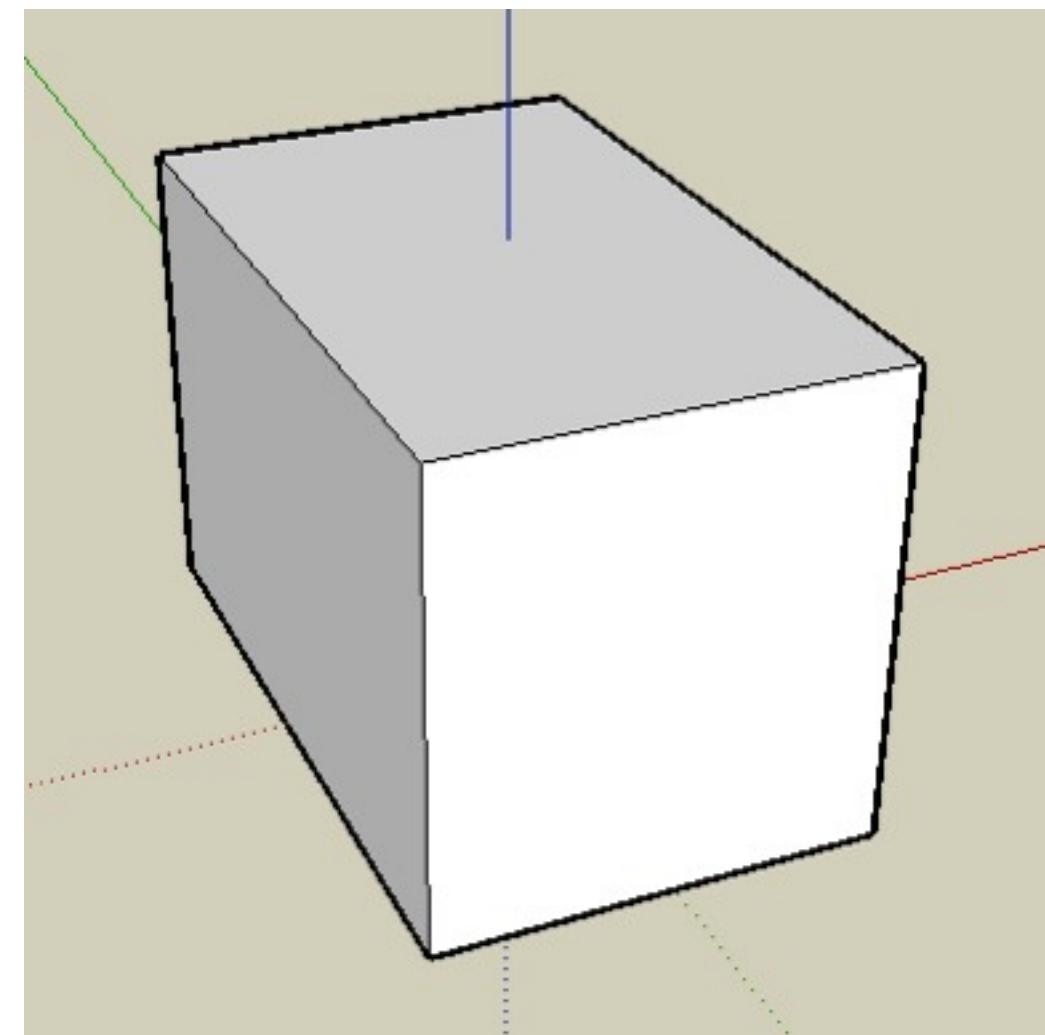
Geometric Primitives

- Simplest way to describe geometric objects
- Can be used directly by some renderers (e.g., Ray tracing)
- Can be transformed into polygons easily (Tesselation)
- Can be transformed into Voxels easily
- Useful for creating simple block world models
- Good start for modeling in VRML/X3D
- Objects can intersect/penetrate



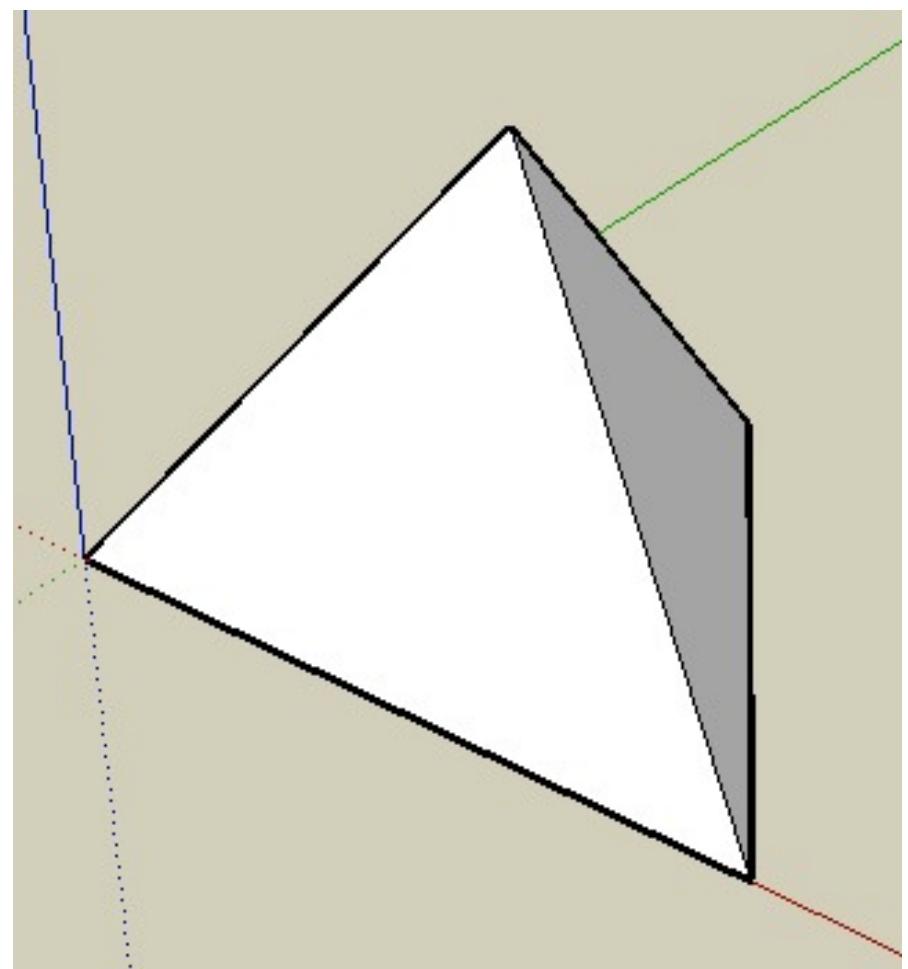
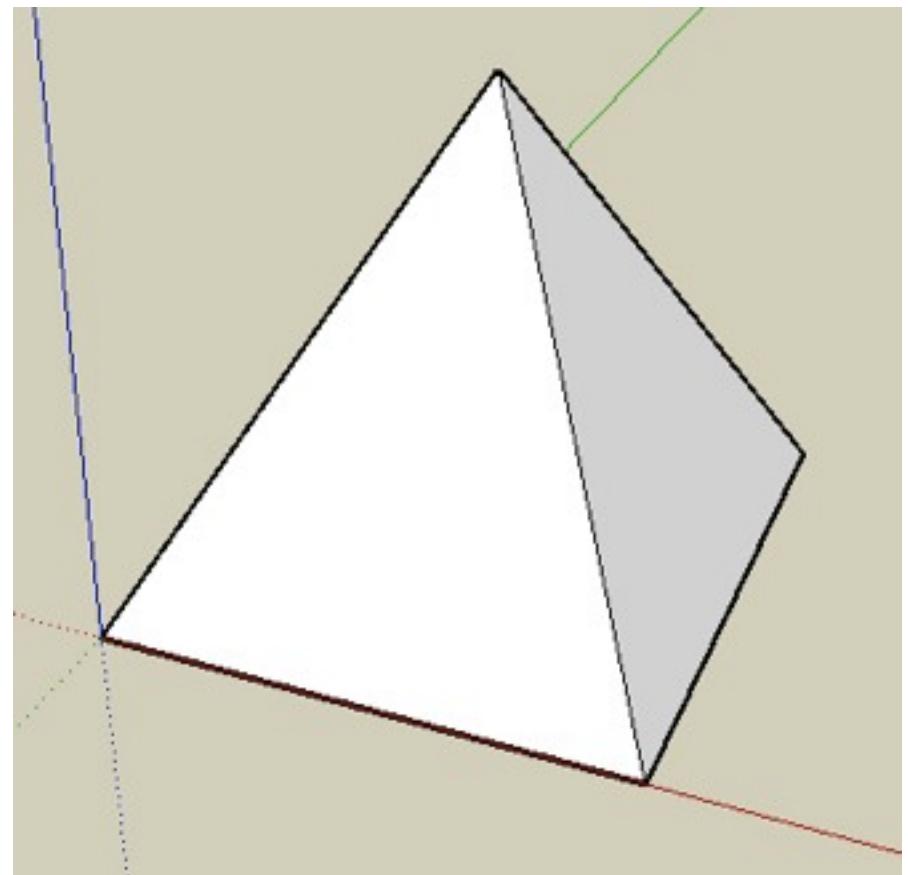
Box

- Described by (width, length, height)
- Origin usually in the center
- 8 points, 12 edges, 6 rectangles, 12 triangles



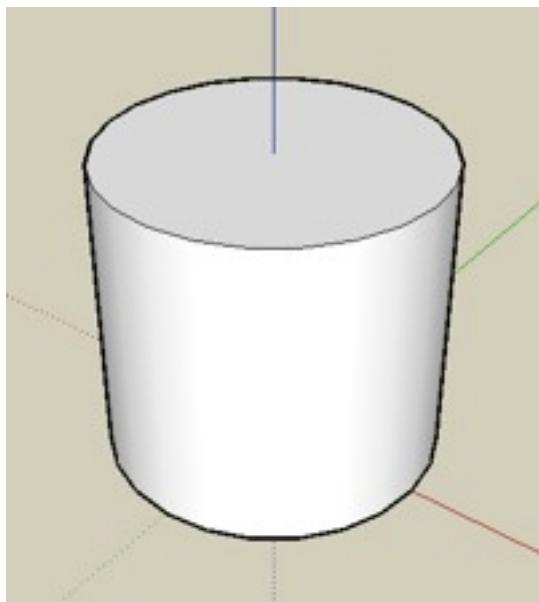
Pyramid, Tetrahedron

- Basis of pyramid = rectangle
 - given by (width, length, height)
 - 5 points, 8 edges, 6 triangles
-
- Basis of tetrahedron = triangle
 - given by (width, length, height)
 - 4 points, 6 edges, 4 triangles,

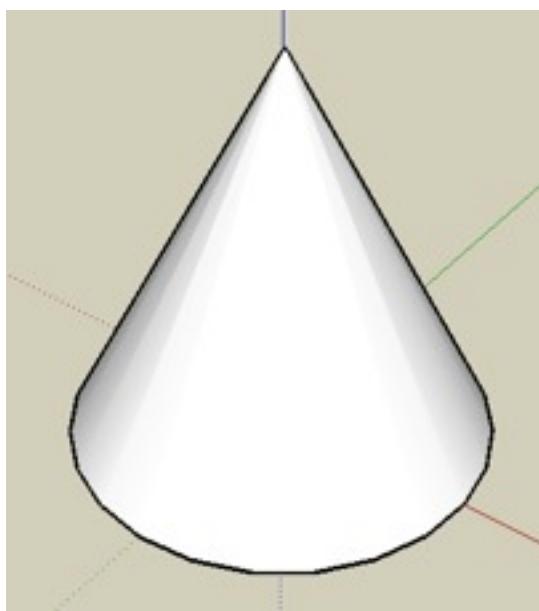


Cylinder, cone, truncated cone

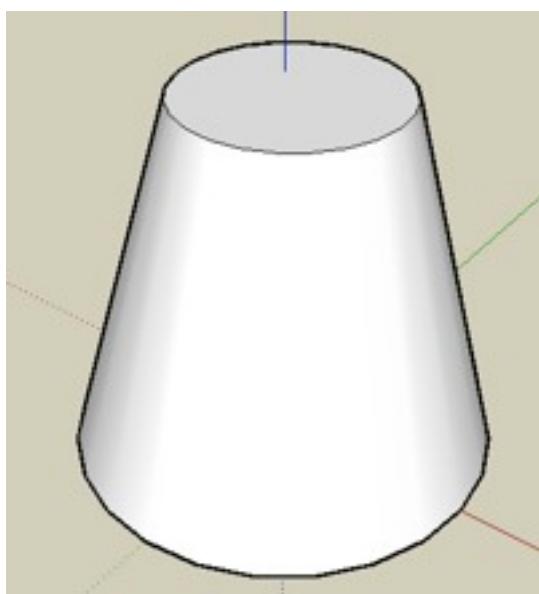
- Cylinder given by (radius, height)
- Number of polygons dep. on tessellation



- Cone given by (radius, height)
- Number of polygons dep. on tessellation

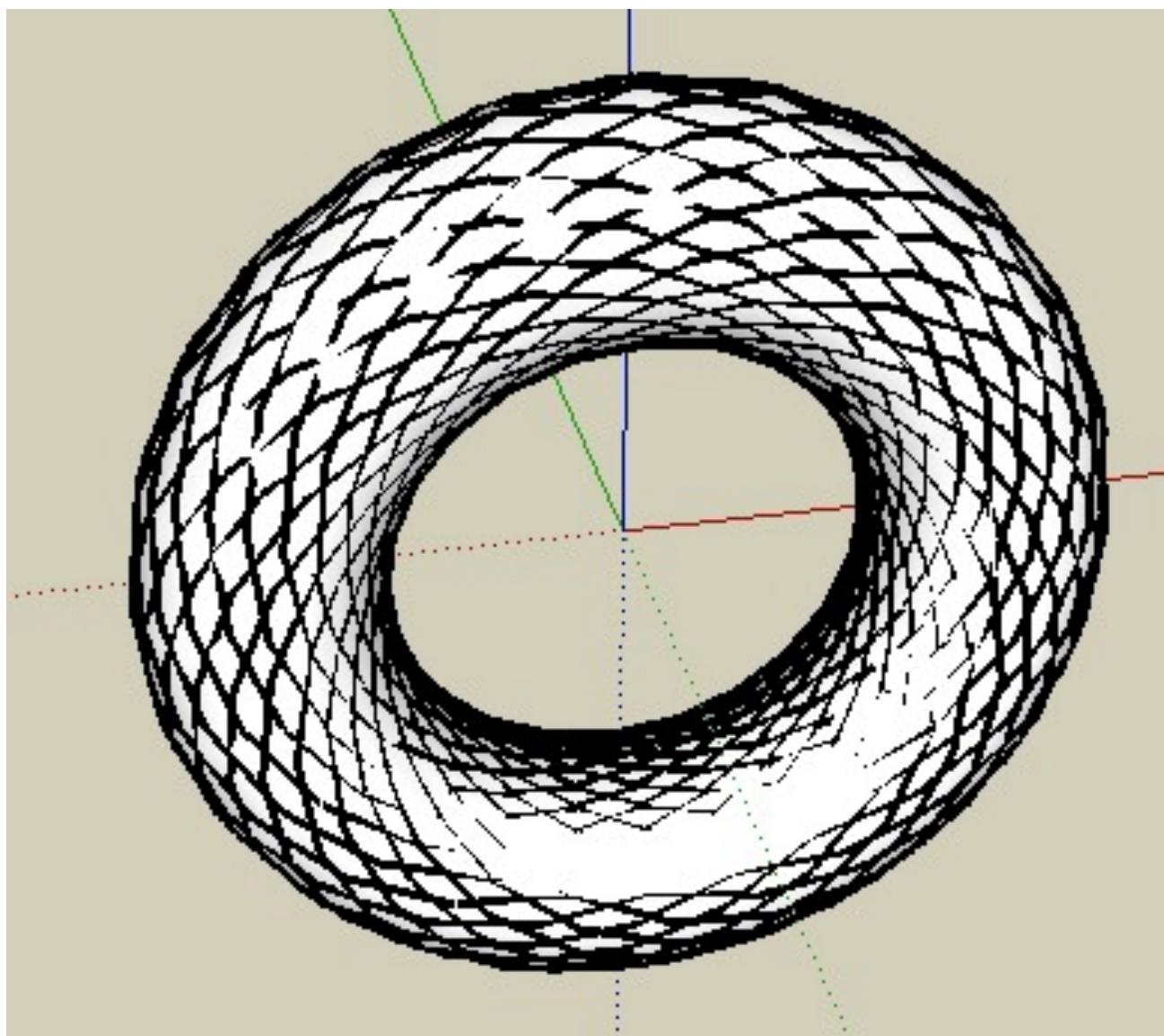
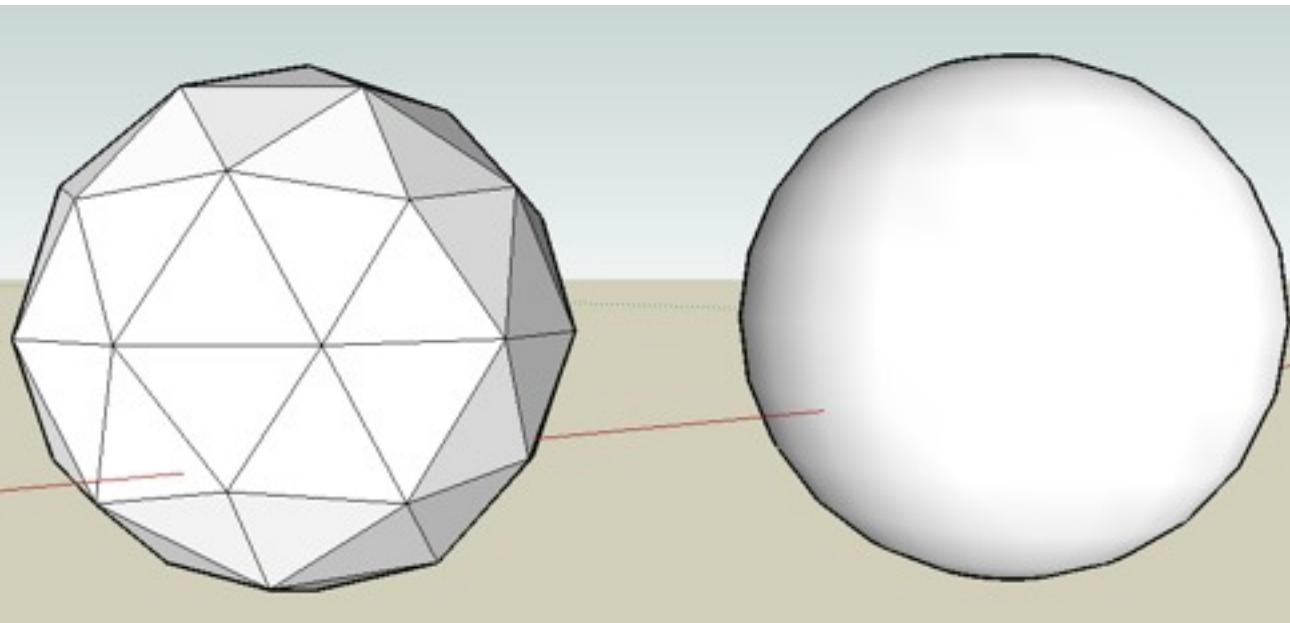


- Truncated cone given by (r_1, r_2, height)
- Number of polygons dep. on tessellation
- Which of these would you rather have if you only had one available?



Sphere, Torus

- Sphere is described by (radius)
- Torus is defined by (radius1, radius2)
- Number of polygons dep. on tessellation

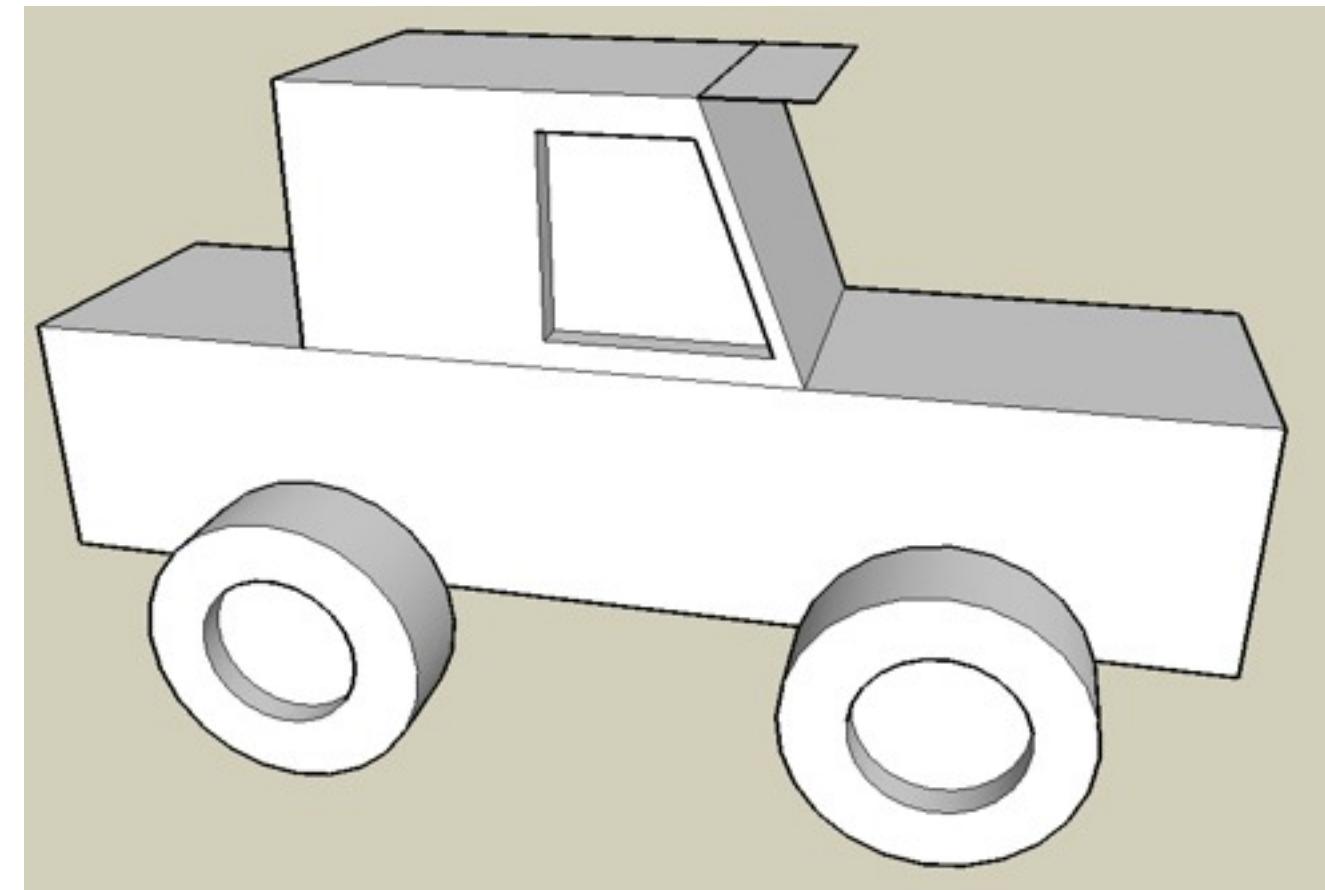


Geometric Primitives: Summary

- Not all of these exist in all graphics packages
 - Some packages define additional primitives (dodecahedron, teapot...;-)
 - Practically the only way to model VRML or X3D in a text editor
 - Can give quite accurate models
 - Extremely lean! very few polygons
 - Think of application areas even in times of powerful PC graphics cards!
-
-
-
-

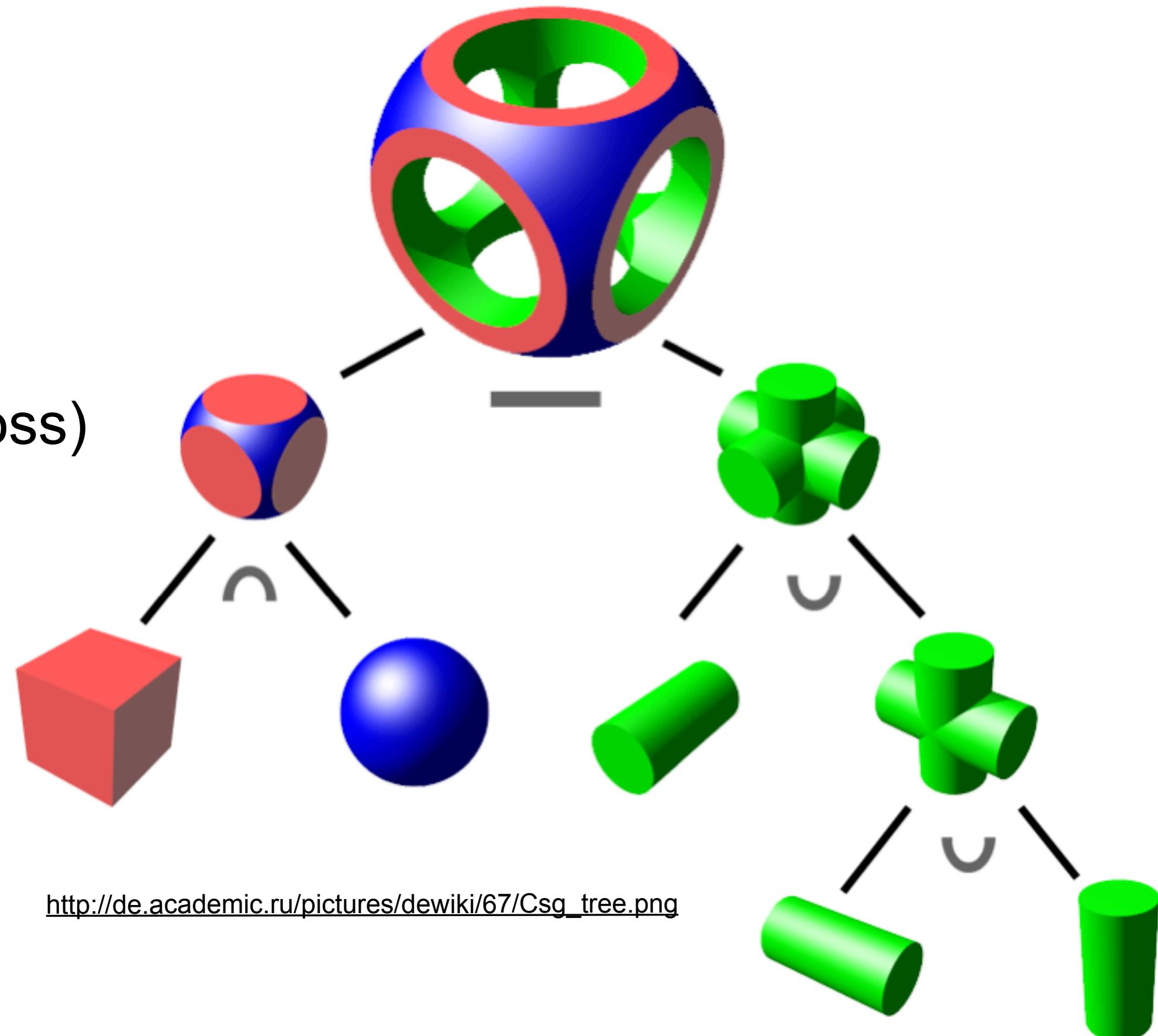
Constructive Solid Geometry

- Basic idea: allow geometric primitives and all sorts of boolean operations for combining them
- Can build surprisingly complex objects
- Good for objects with holes (often the simplest way)
- Basic operations:
 - **Or**: combine the volume of 2 objects
 - **And**: intersect the volume of 2 objects
 - **Not**: all but the volume of an object
 - **Xor**: all space where 1 object is, but not both
- Think about:
 - wheels of this car
 - tea mug
 - coke bottle (Problems??)



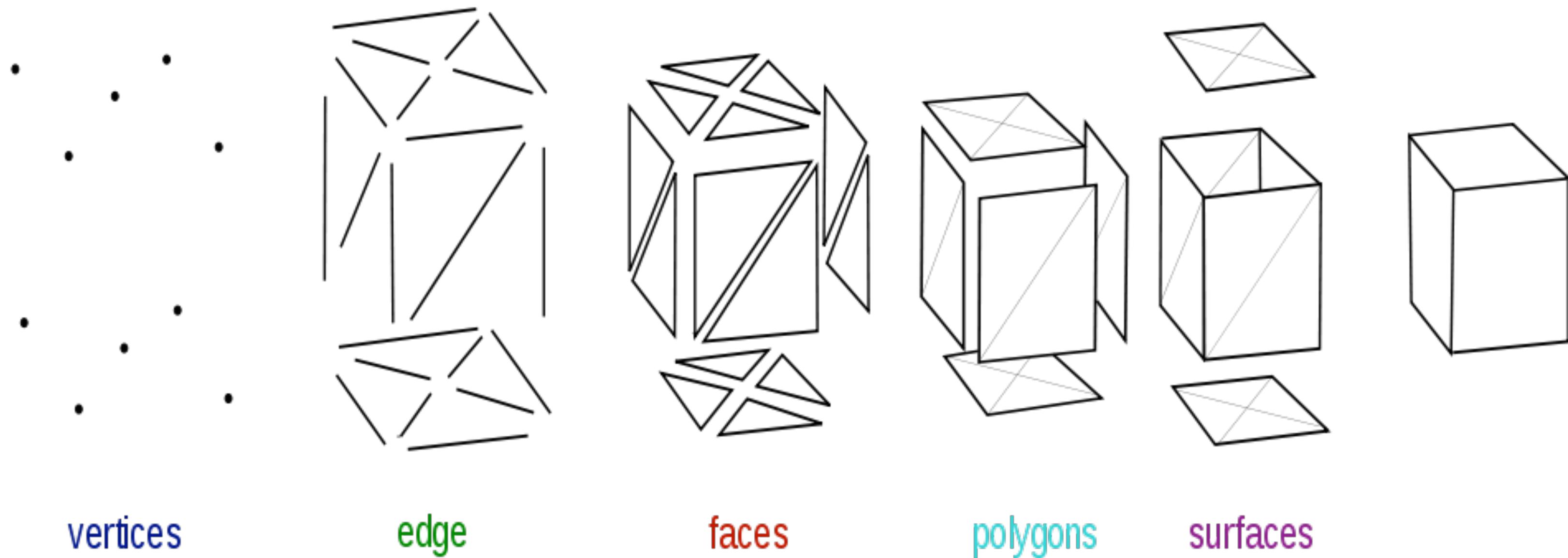
CSG: a complex Example

- rounded_cube =
cube **And** sphere
- cross =
cyl1 **Or** cyl2 **Or** cyl3
- result =
rounded_cube **And** (**Not** cross)
- Think: Are CSG operations
associative?
 -
- ...commutative?
 -



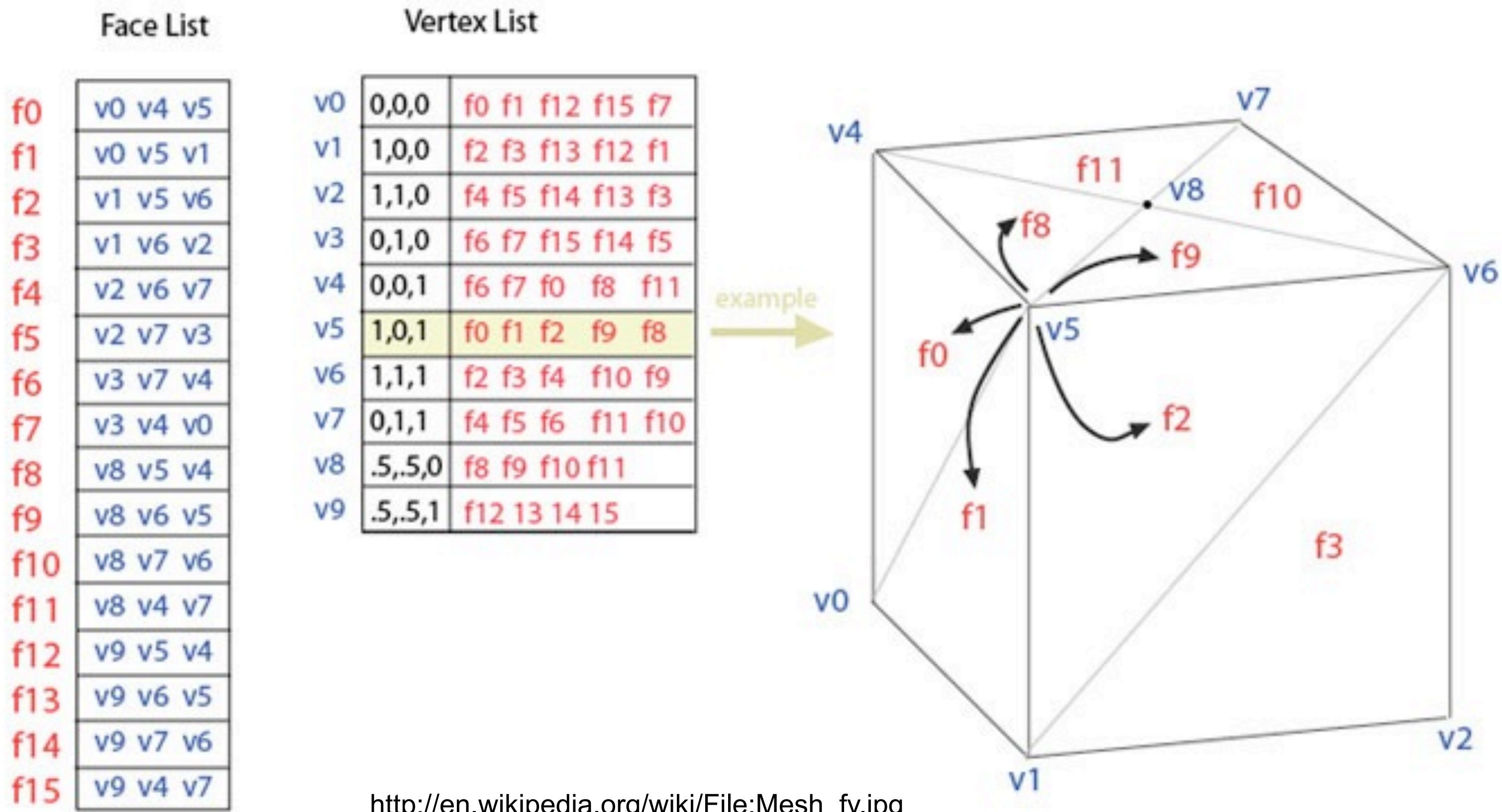
Polygon Meshes

- Describe the surface of an object as a set of polygons
- Mostly use triangles, since they are trivially convex and flat
- Current graphics hardware is optimized for triangle meshes



http://en.wikipedia.org/wiki/File:Mesh_overview.svg

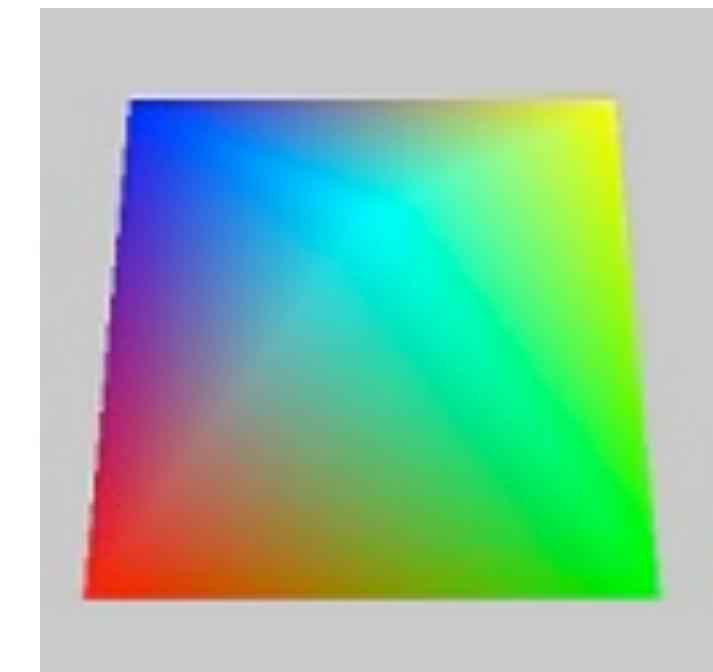
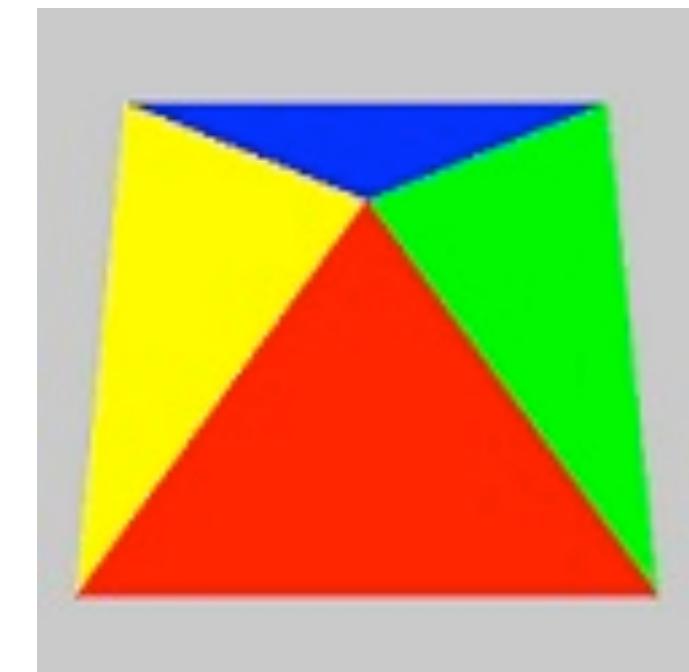
Face-Vertex Meshes



http://en.wikipedia.org/wiki/File:Mesh_fv.jpg

Polygon Meshes: optional data

- Color per vertex or per face: produces colored models
- Normal per vertex: allows free control over the normals
 - can mix smooth and sharp edges
 - wait for shading chapter ;-)
- Texture coordinates per vertex
 - wait for texture chapter ;-)



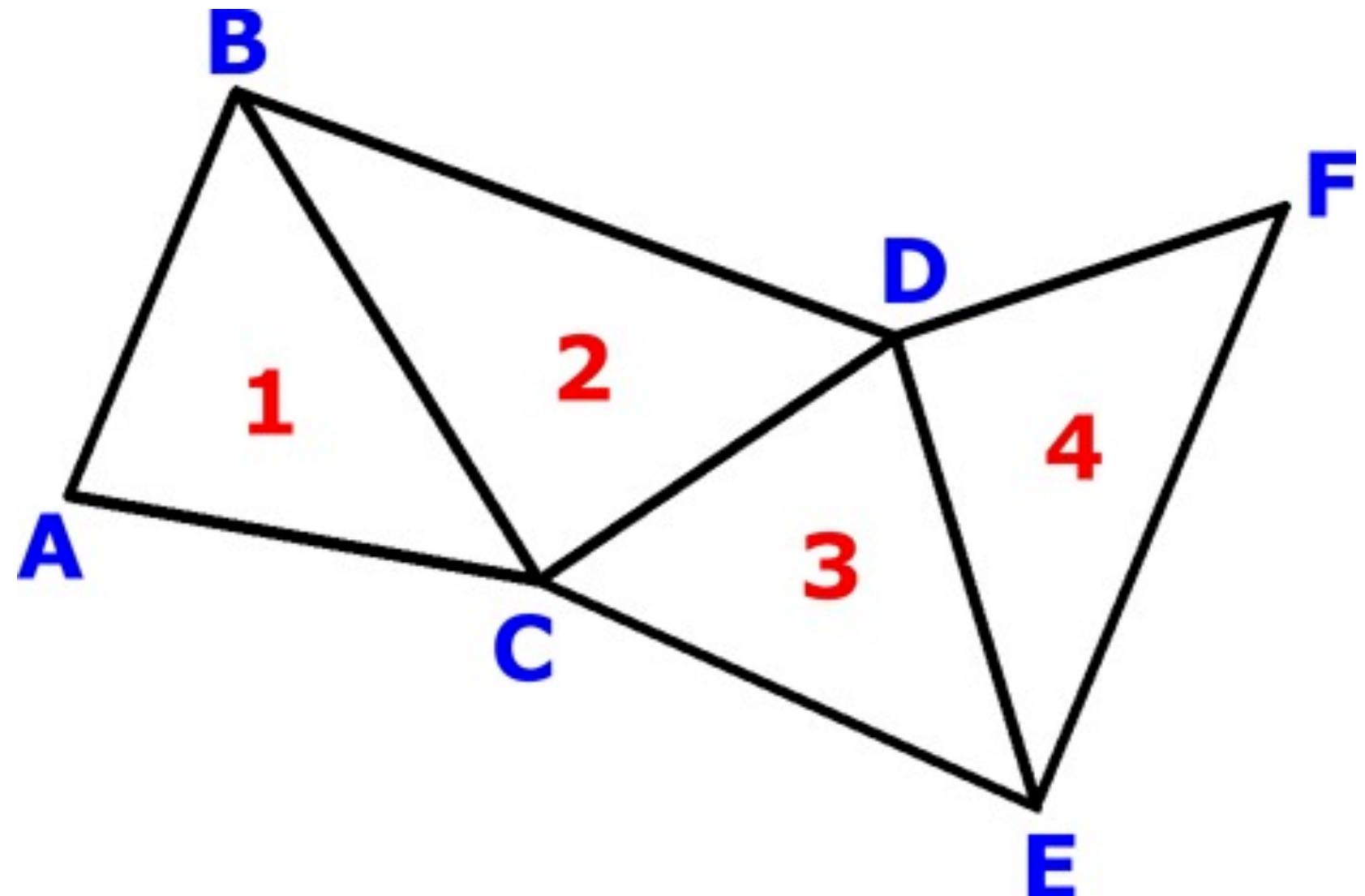
http://en.wikipedia.org/wiki/File:Triangle_Strip.png

Polygon Meshes: other descriptions

- Other representations for polygon meshes exist
 - optimized for analyzing and modifying topology
 - optimized for accessing large models
 - optimized for fast rendering algorithms
 - optimized for graphics hardware

- Example: triangle strip

- needs $N+2$ points for N polygons
 - implicit definition of the triangles
 - optimized on graphics hardware

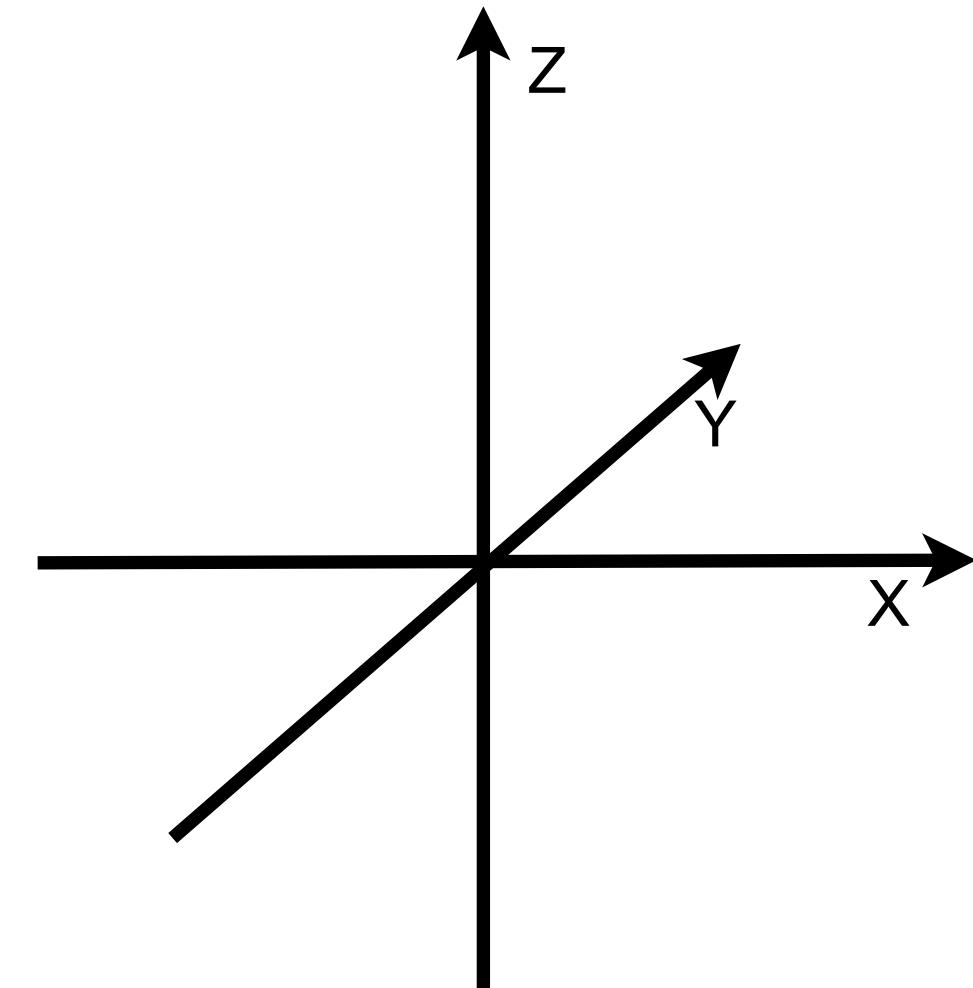


http://en.wikipedia.org/wiki/File:Triangle_Strip.png

Practical example: VRML IndexedFaceSet

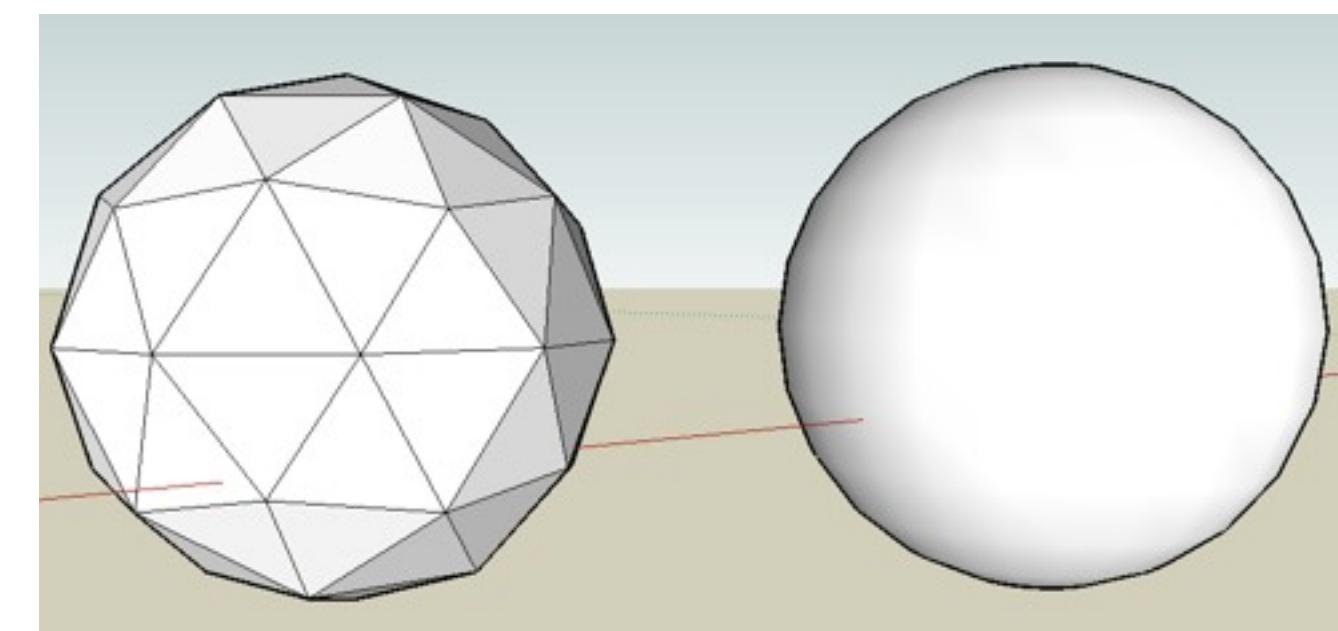
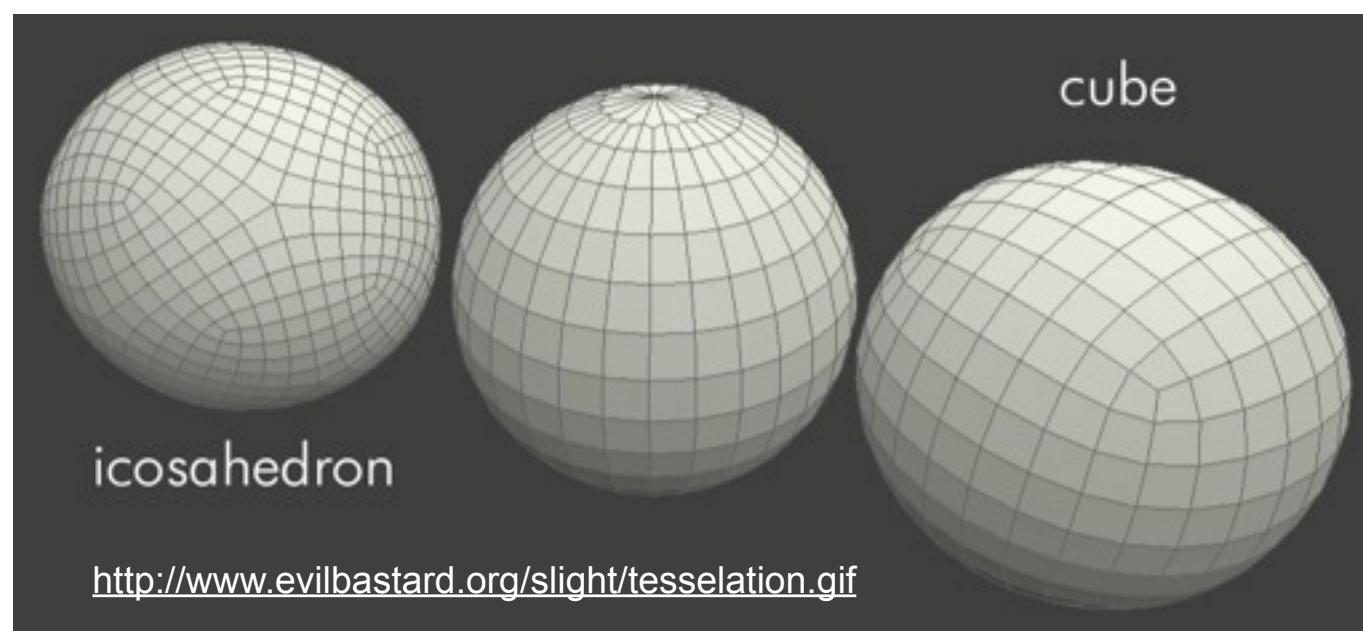
Quiz: what is given by the following piece of VRML code??

```
geometry IndexedFaceSet {  
    coord Coordinate {  
        point [ -1 0 1, 1 0 1, -1 0 -1, 1 0 -1, 0 1 0 ]  
    }  
    coordIndex [ 0, 1, 4, -1,  
                1, 3, 4, -1,  
                3, 2, 4, -1,  
                2, 0, 4, -1,  
                1, 0, 2, 3, -1 ]  
}
```



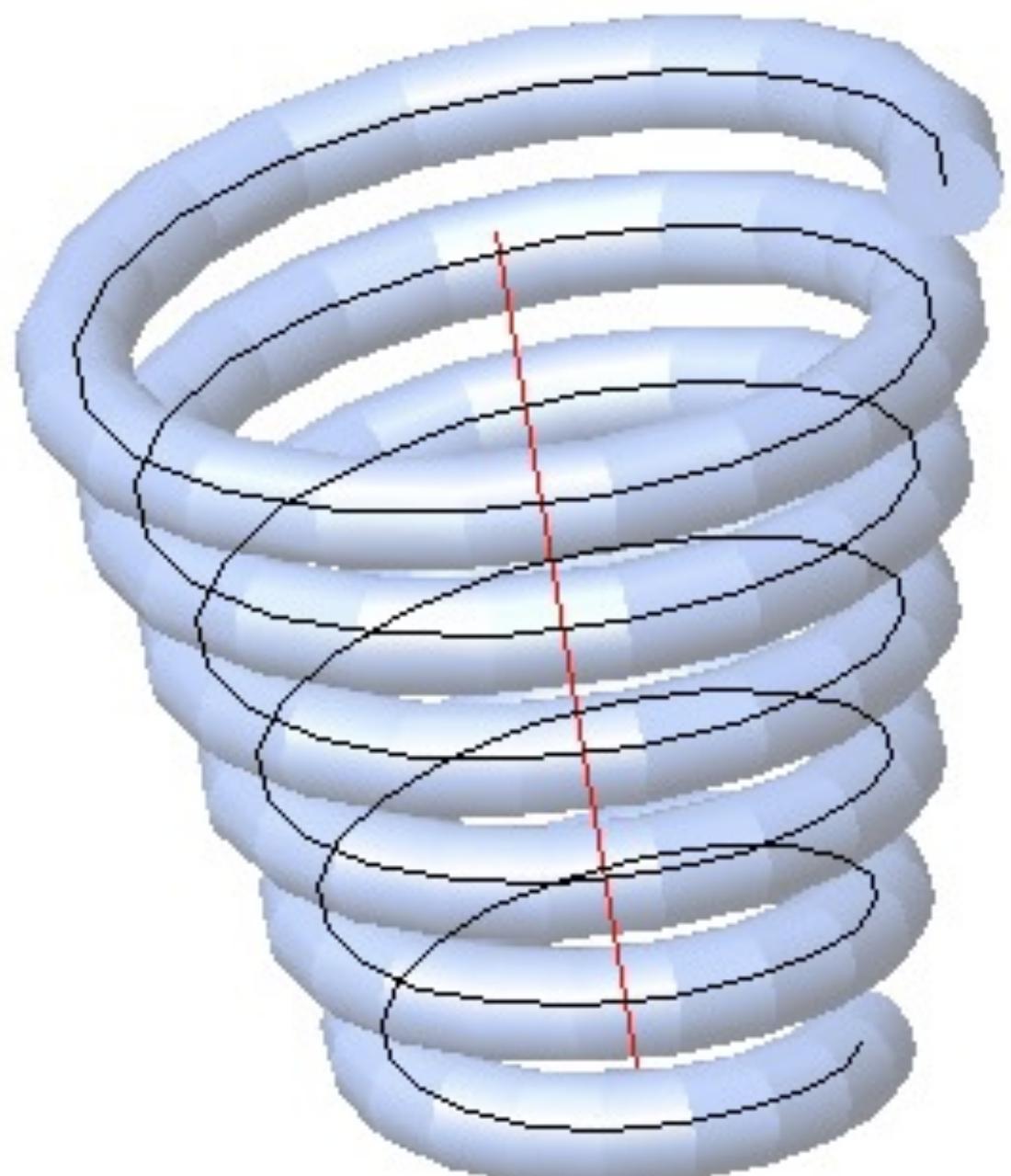
Approximating Primitives by Polygon Meshes

- Trivial for non-curved primitives...
- The curved surface of a cylinder, sphere etc. must be broken down into polygons somehow (Tesselation).
- Not trivial and certainly not unique!
- Goal: small polygons for strong curvature, larger ones for areas of weak curvature
 - This means ideally constant polygon size for a sphere
 - Where do I know this problem from??? Hmm...

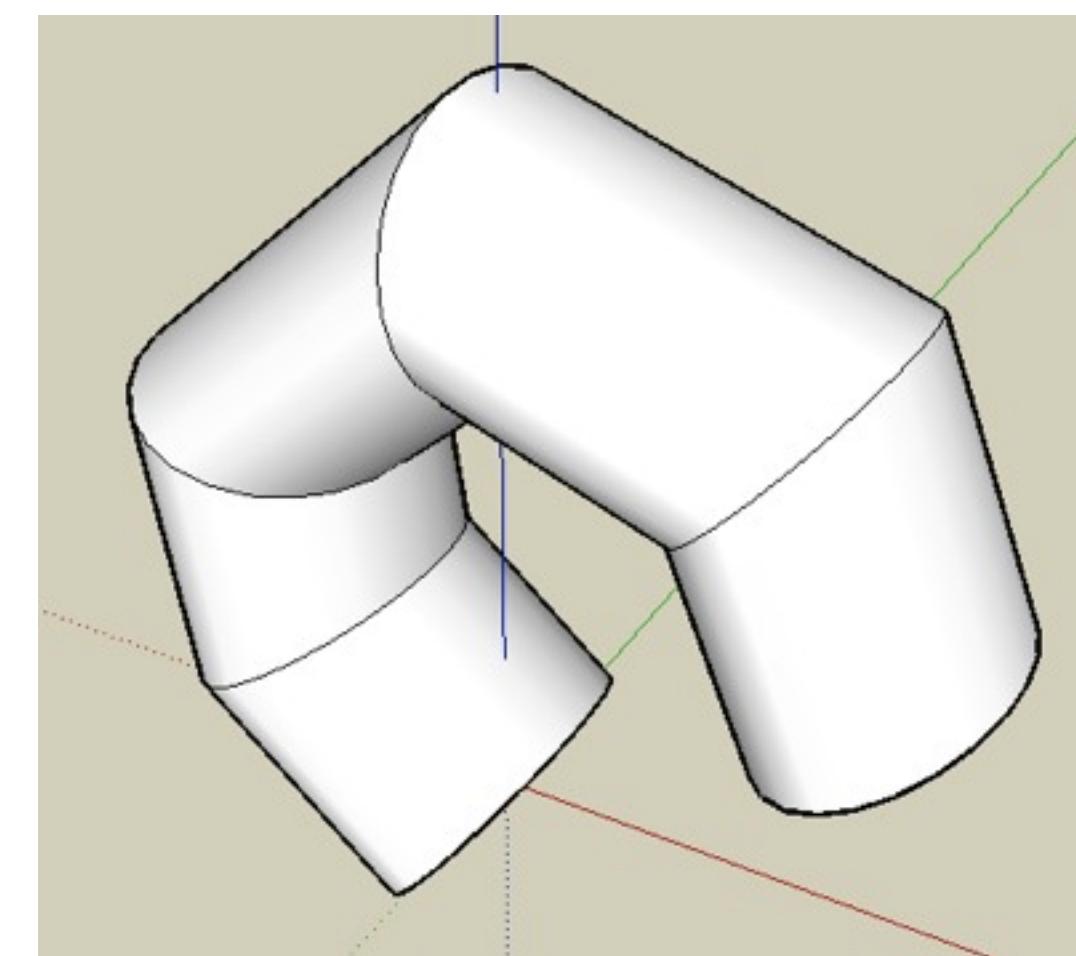
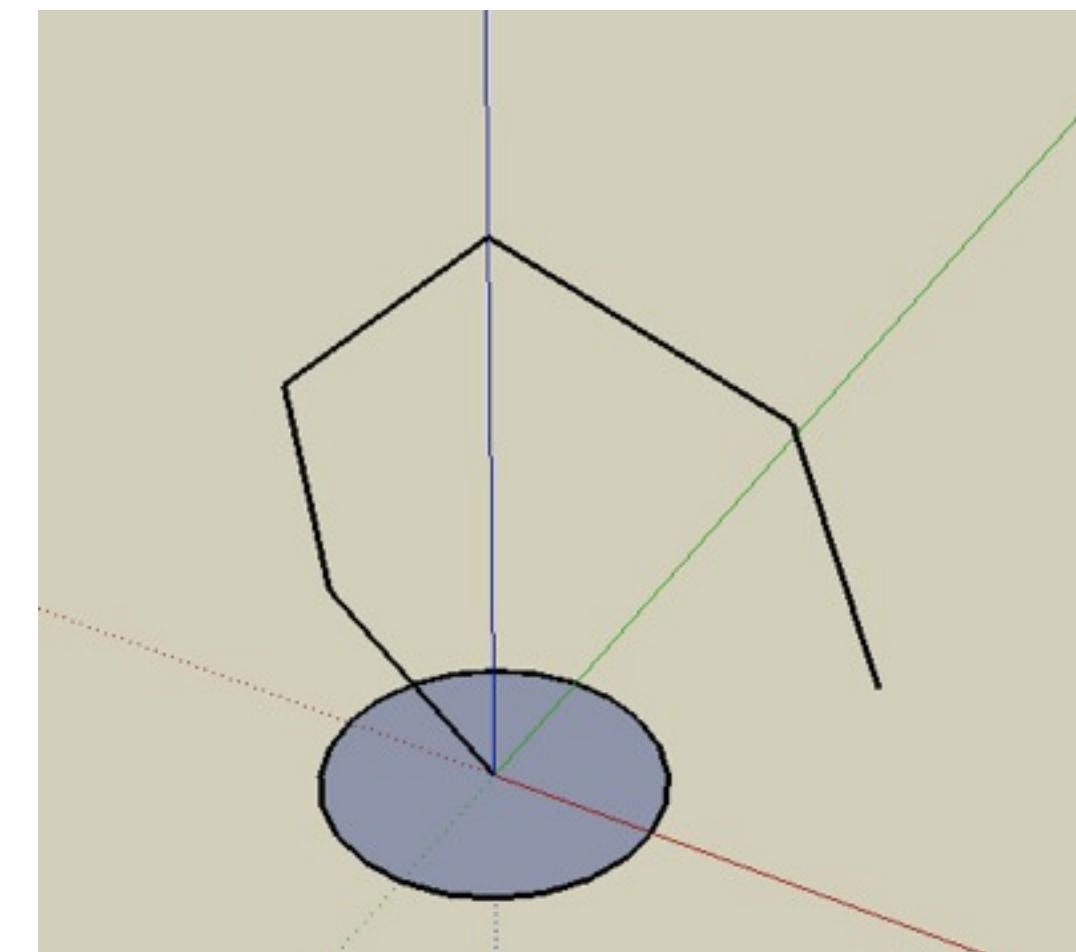


Extrusion (sweep object)

- Move a 2D shape along an arbitrary path
- possibly also scale in each step



<http://www.cadimage.net/cadtutor/lisp/helix-02.gif>



Rotation

- Rotate a 2D shape around an arbitrary axis
- Can be expressed by extrusion along a circle

- How can we model a vase?

-

-

-

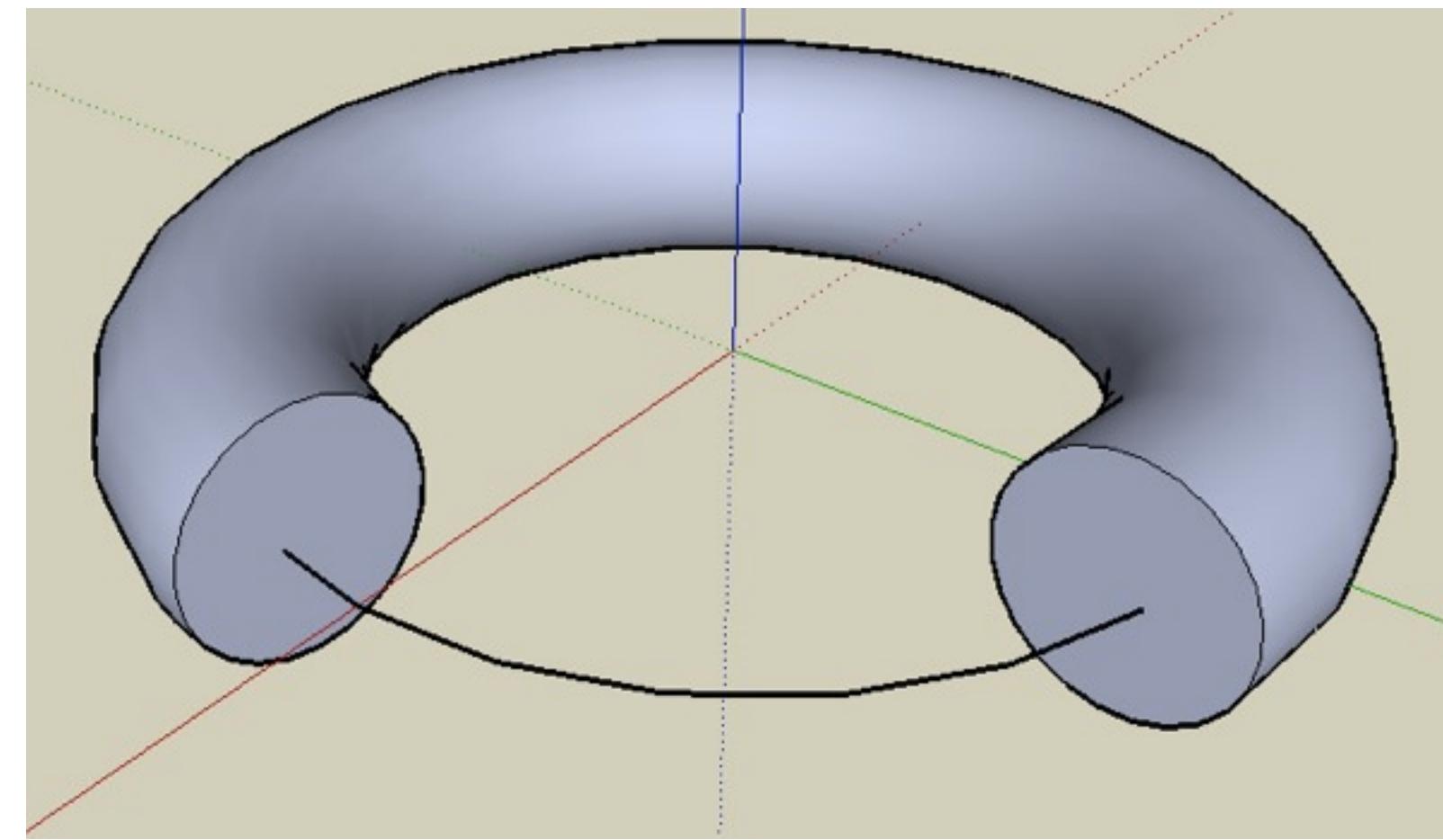
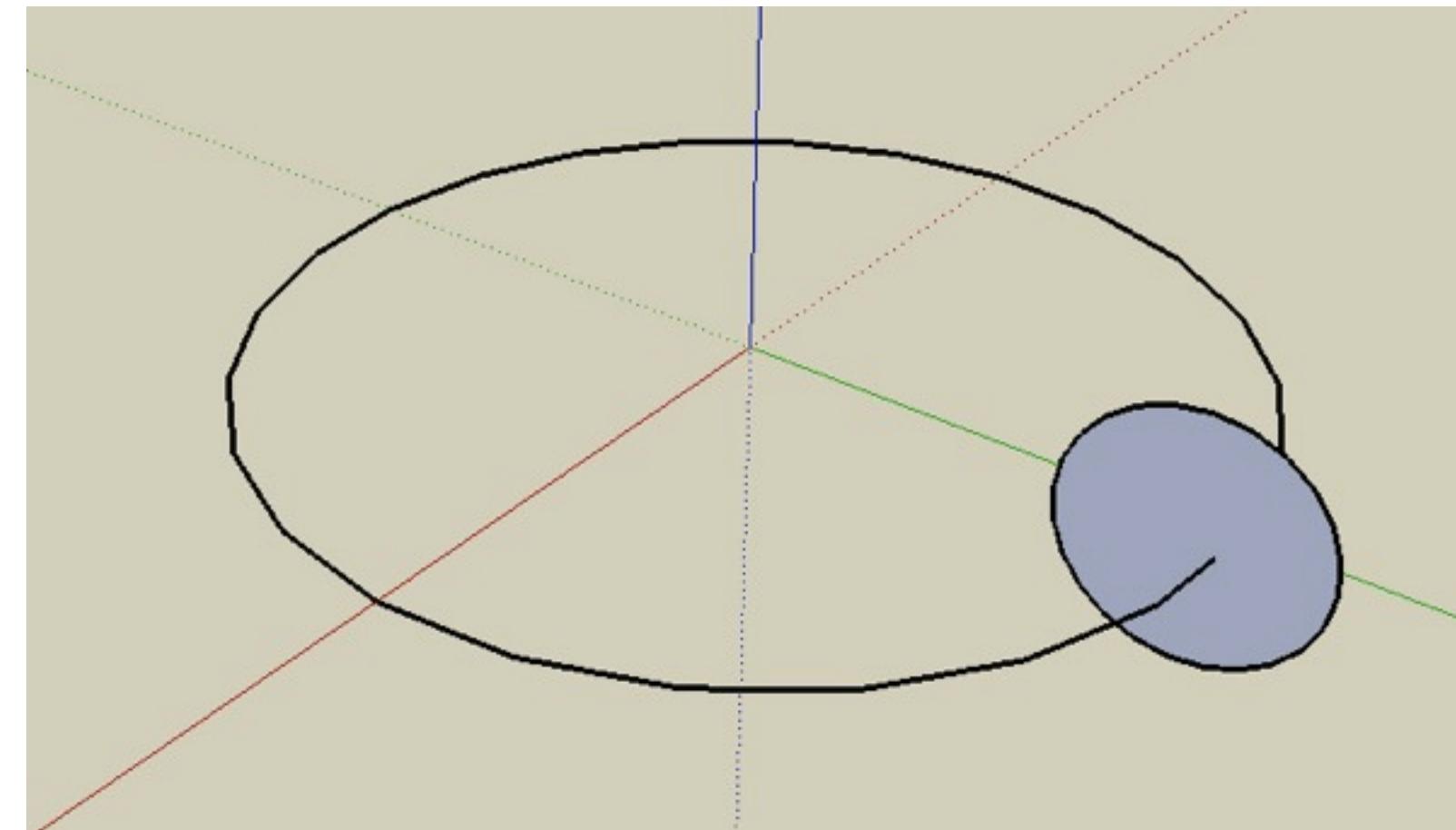
- How a Coke bottle?

-

-

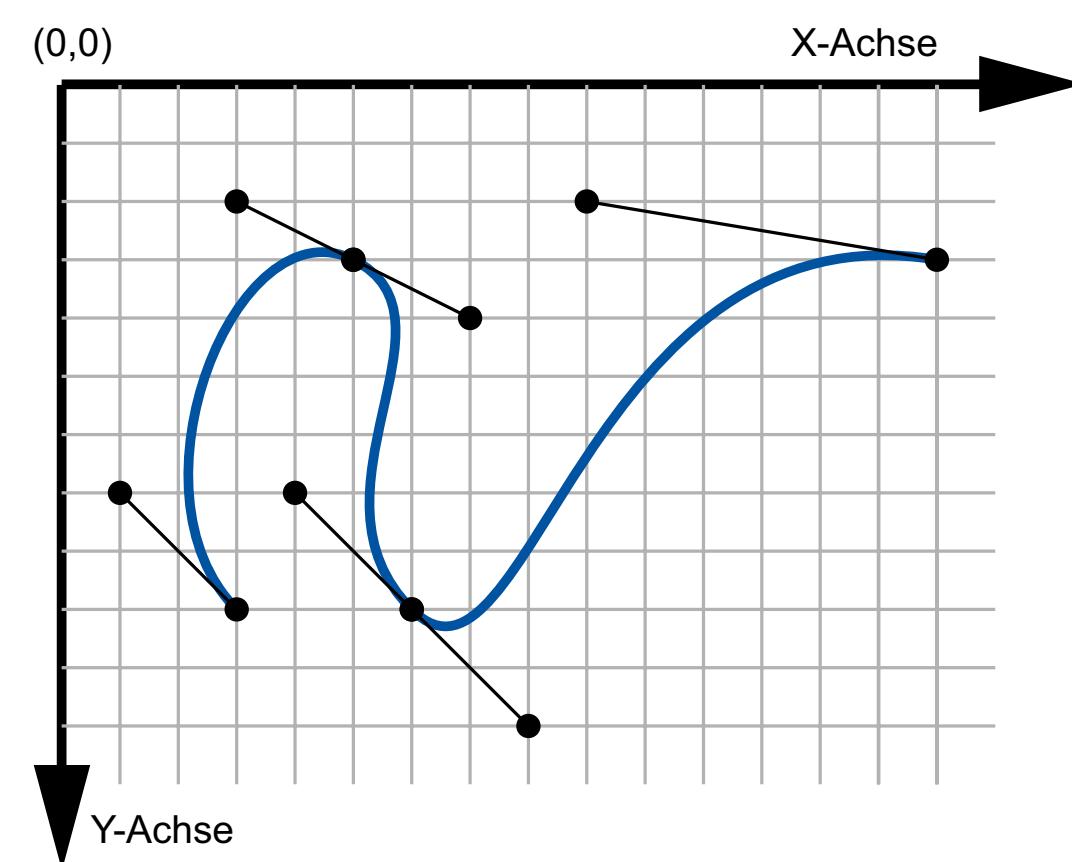
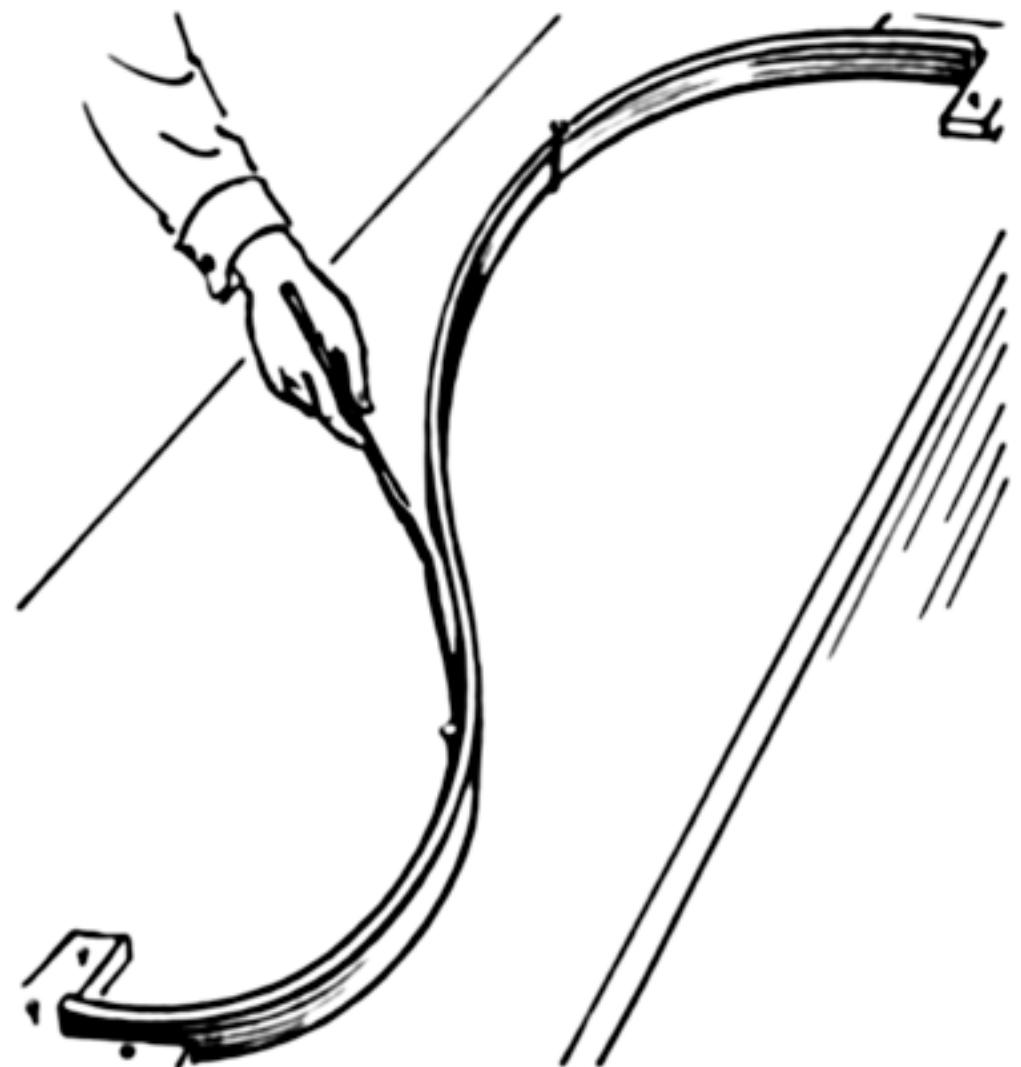
-

-



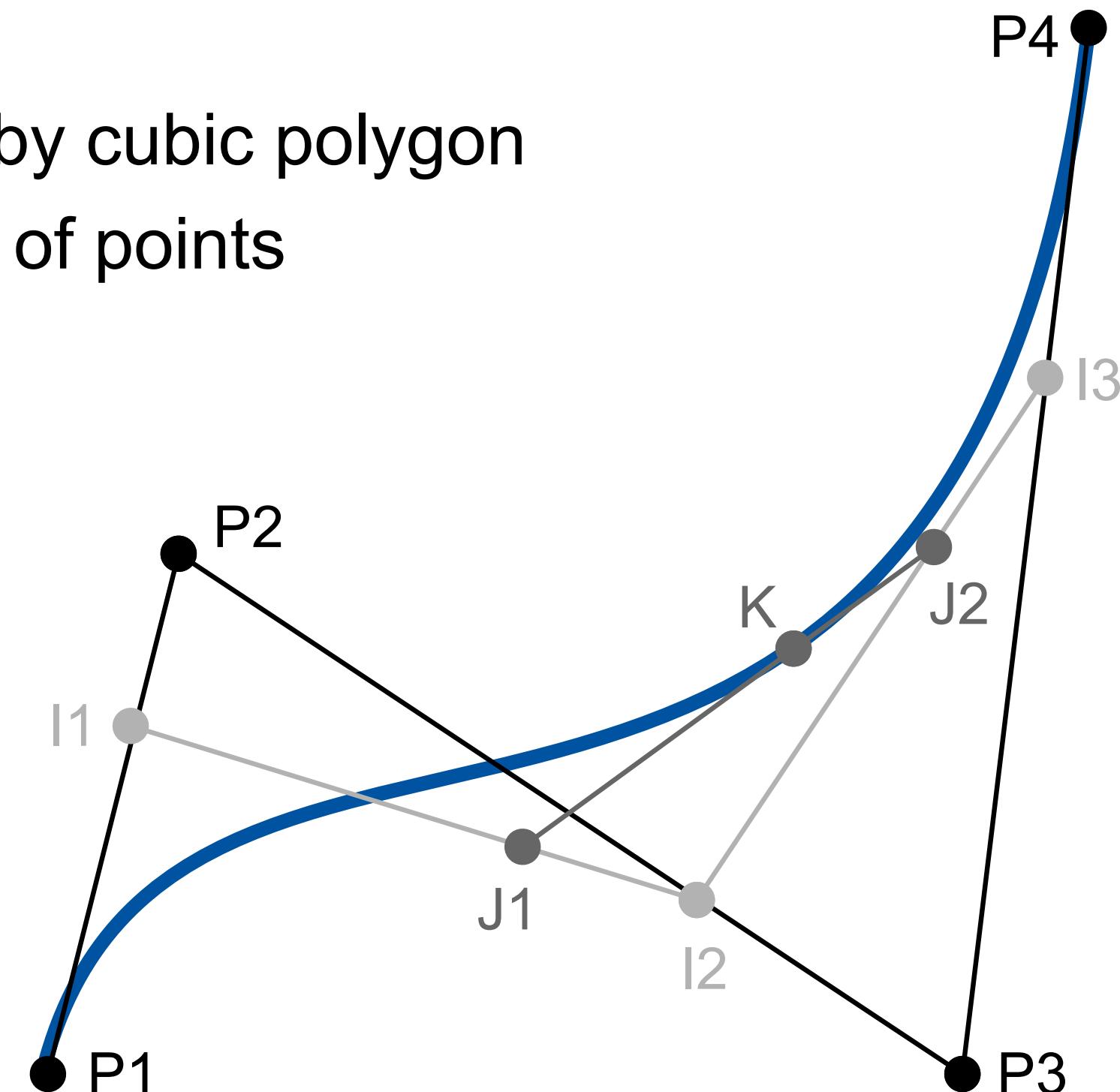
Interpolation Curves, Splines

- Original idea: „Spline“ used in ship construction to build smooth shapes:
 - Elastic wooden band
 - Fixed in certain positions and directions
 - Mathematically simulated by interpolation curves
 - piecewise described by polygons
- Different types exist
- Control points my be on the line or outside of it.



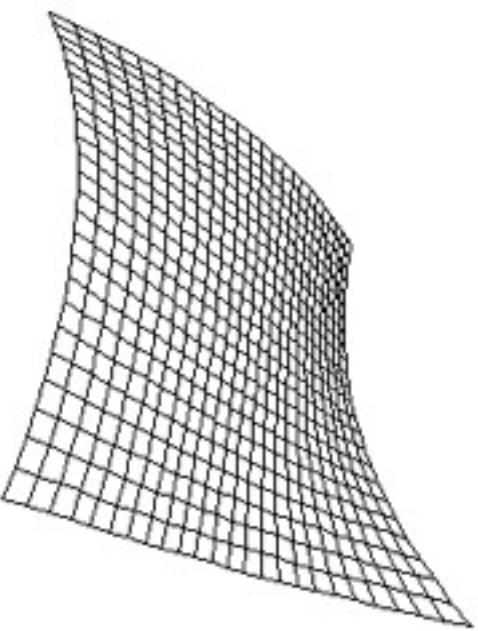
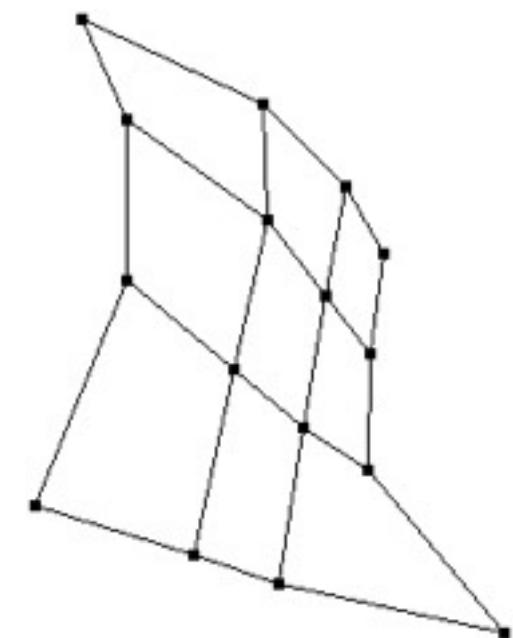
Bezier Curves (and Casteljau Algorithm)

- Bezier curves first used in automobile construction (1960s, Citroen)
- Degree 1: straight line interpolated between 2 points
- Degree 2: quadratic polygon
- Degree 3: cubic bezier curve, described by cubic polygon
- Curve is always contained in convex hull of points
- Algorithm (defines line recursively):
 - I1 is linearly interpolated between P1 and P2
 - I2 ... between P2 and P3
 - I3 ... between P3 and P4
 - J1 ... between I1 and I2
 - J2 ... between I2 and I3
 - K ... between J1 and J2
 - The bezier curve is the sum of all points K
- see <http://files.dmke.de/bezier.html> !!!



Bezier patches

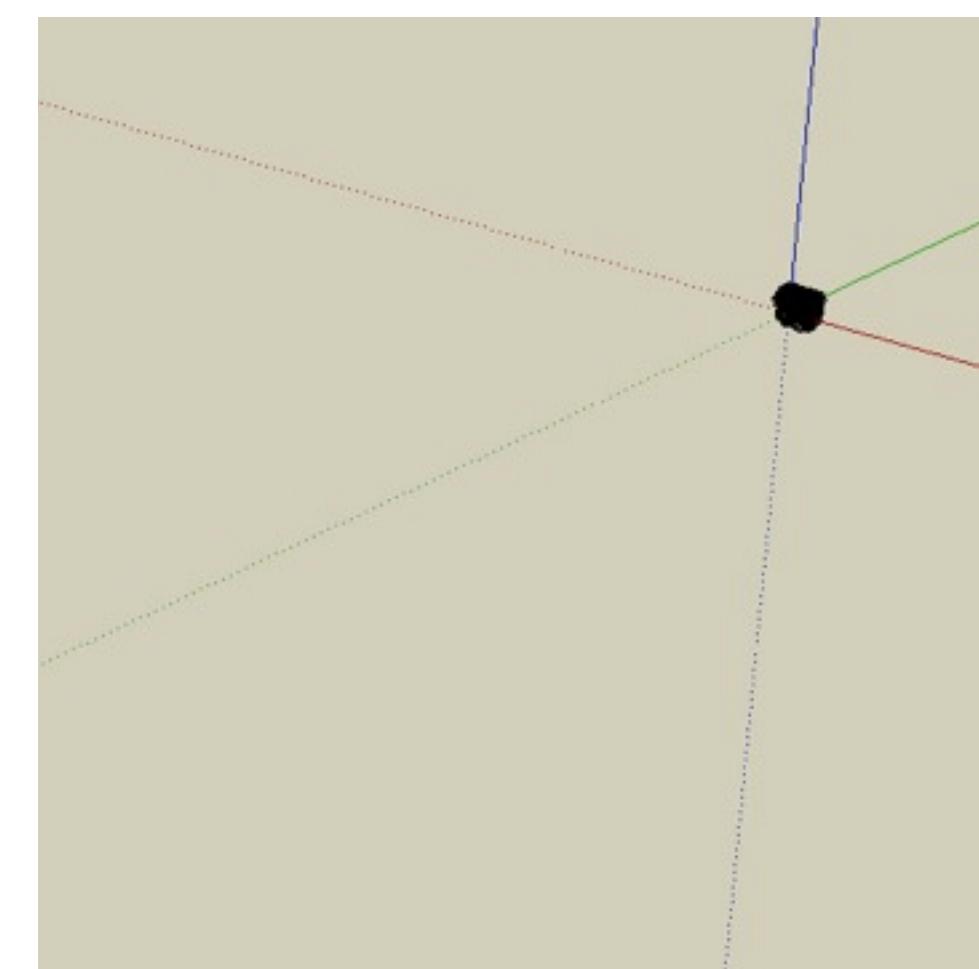
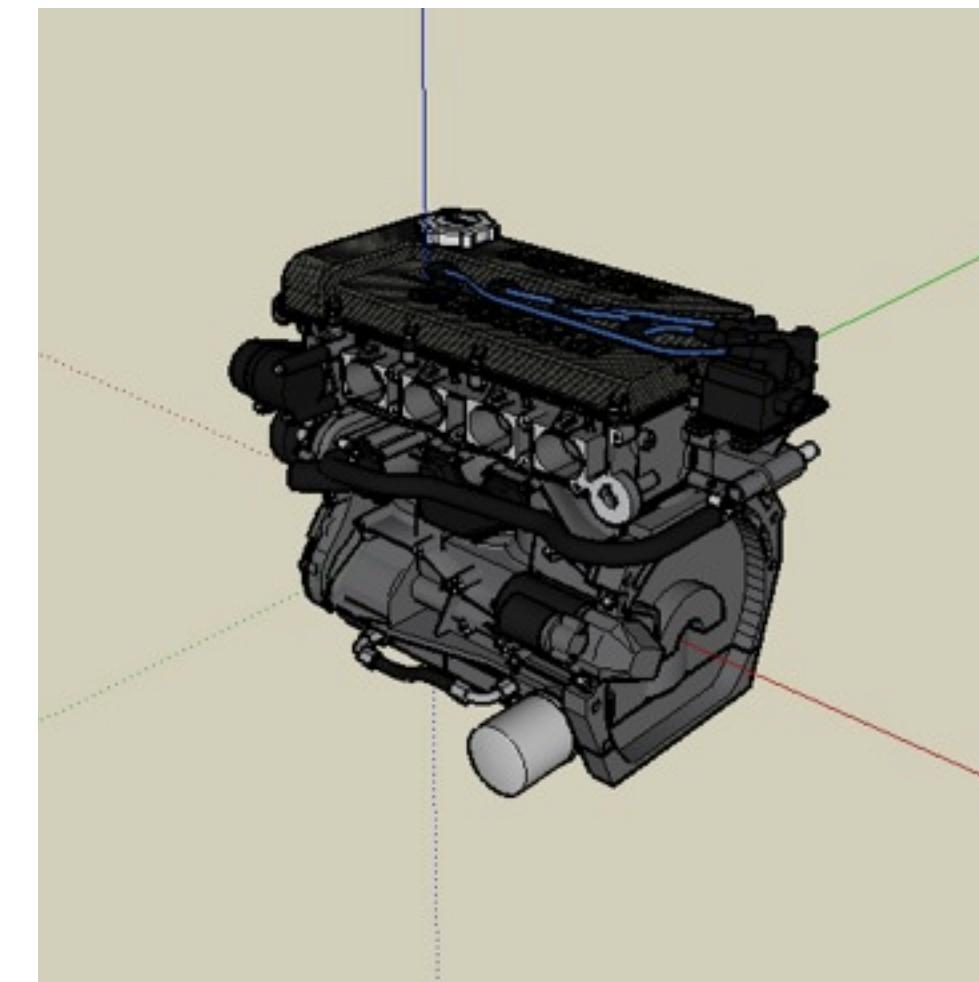
- Combine 4 Bezier curves along 2 axes
- Share 16 control points
- Results in a smooth surface
- Entire surface is always contained within the convex hull of all control points
- border line is fully determined by border control points
- several patches can be combined
 - connect perfectly if border control points are the same.
- Other interpolation surfaces based on other curves
- advantage: move just one control point to deform a larger surface...





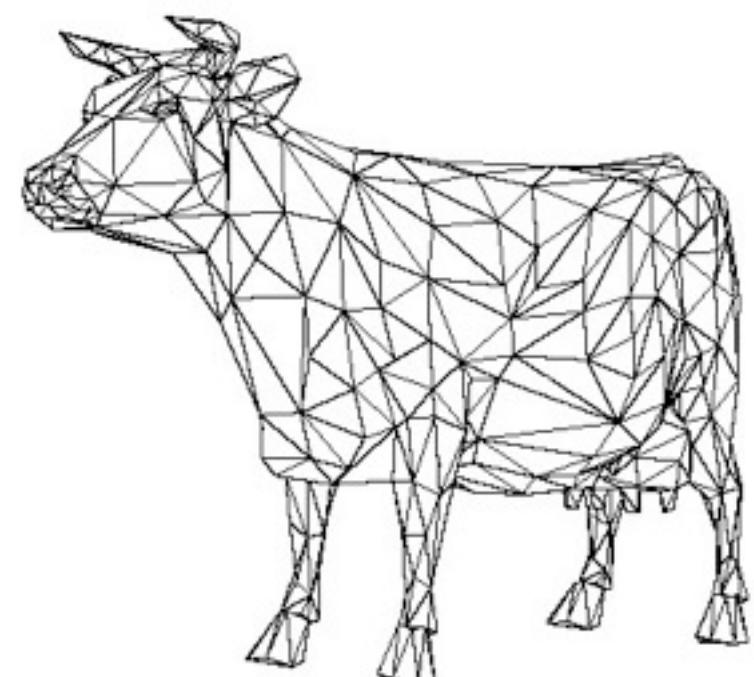
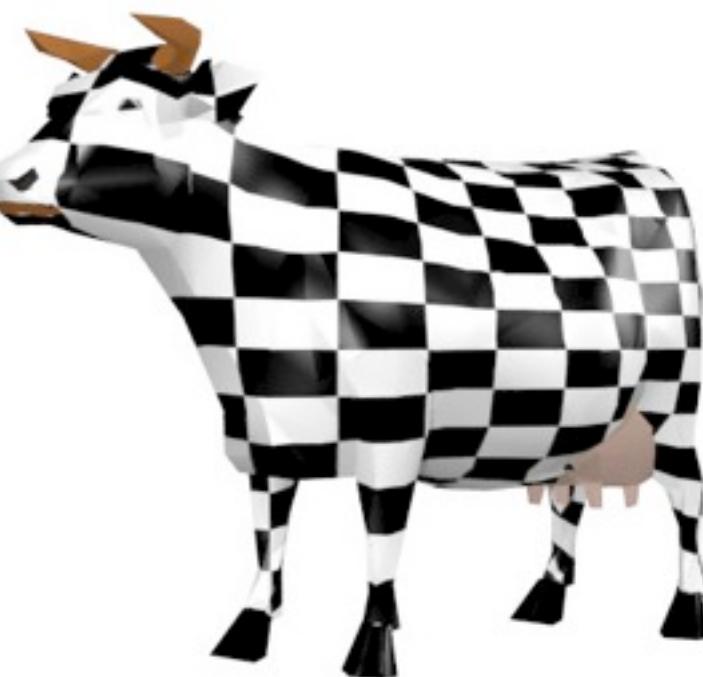
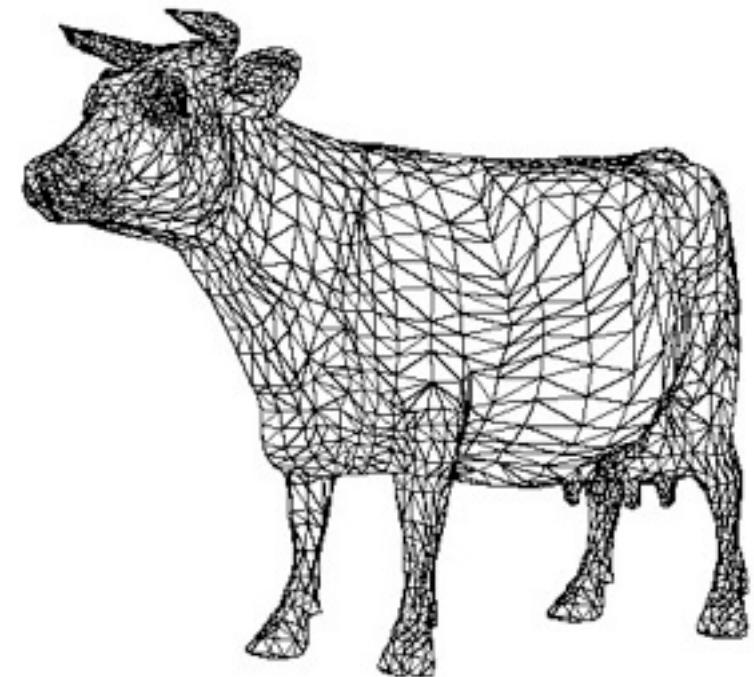
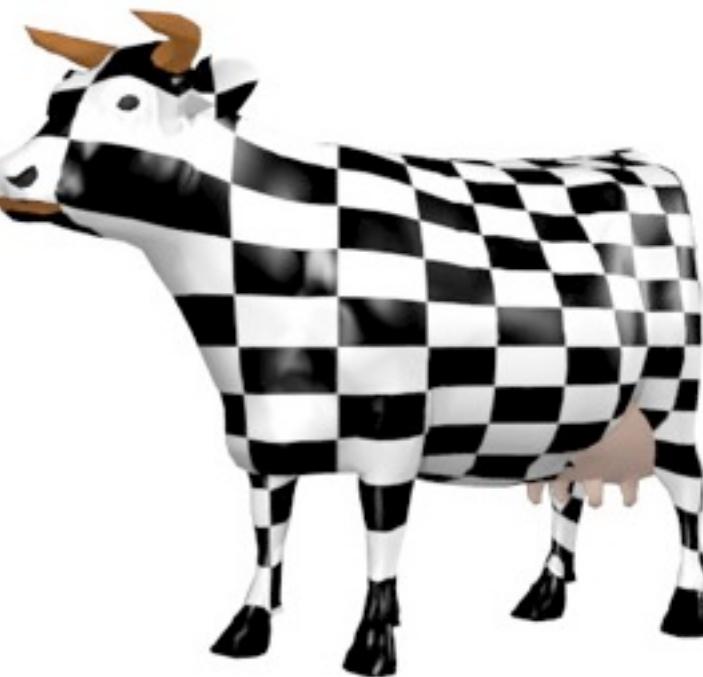
Levels of Detail

- Assume you have a very detailed model
 - from close distance, you need all polygons
 - from a far distance, it only fills a few pixels
 - How can we avoid drawing all polygons?
-
-
-



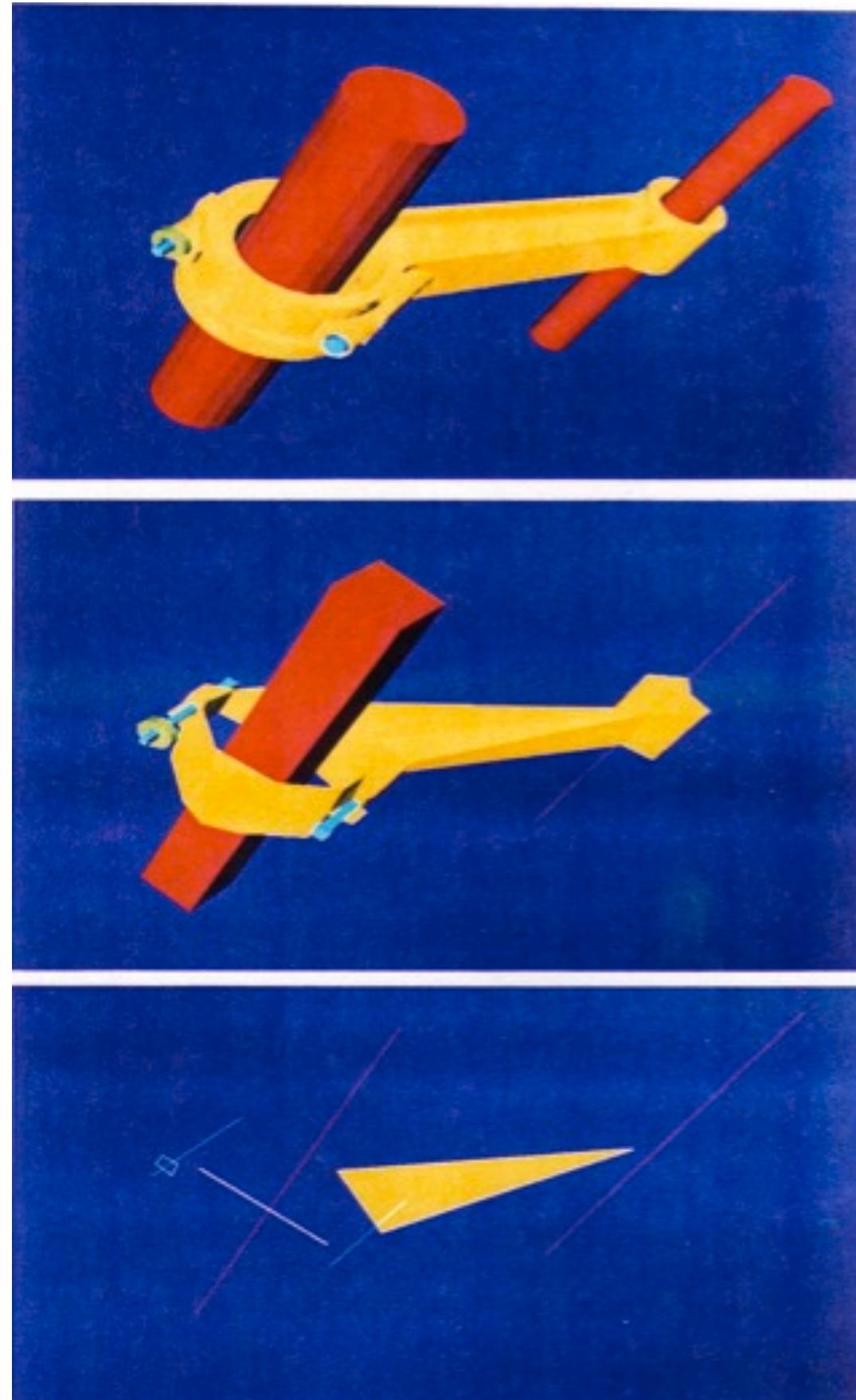
Mesh reduction

- Original: ~5.000 polygons
 - Reduced model: ~1.000 polygons
 - ==> about 80% reduction
-
- Very strong reductions possible, depending on initial mesh
 - Loss of shape if overdone



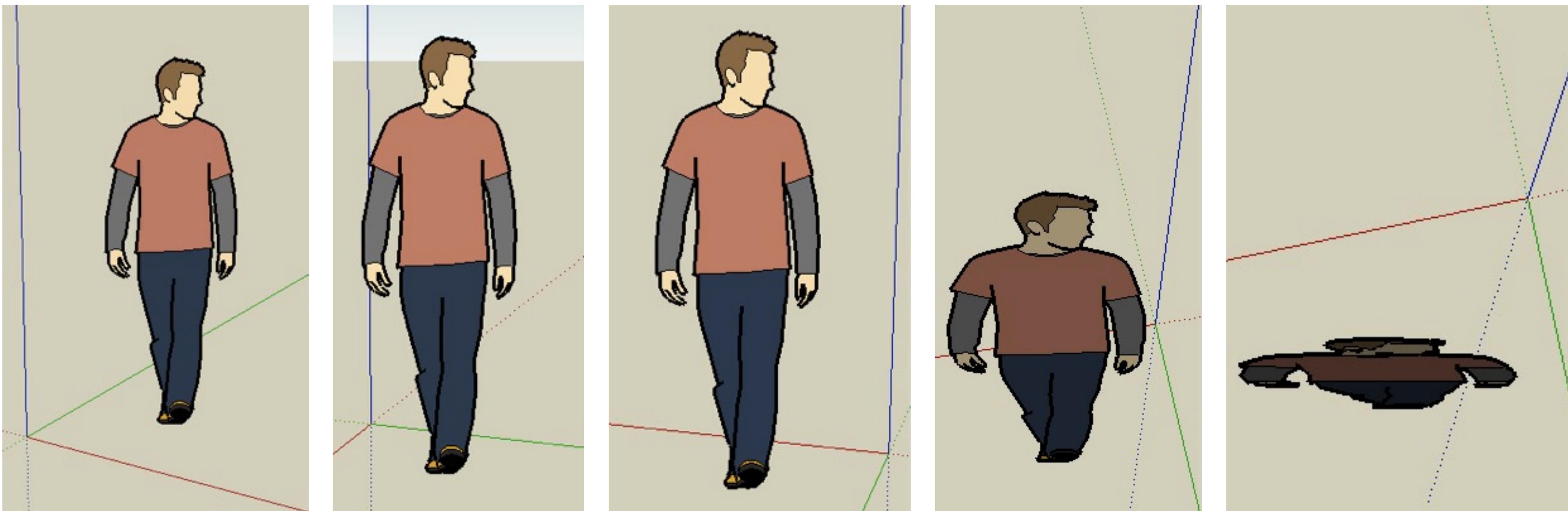
A method for polygon reduction

- Rossignac and Borell, 1992, „Vertex clustering“
- subdivide space into a regular 3D grid
- for each grid cell, melt all vertices into one
 - choose center of gravity of all vertices as new one
 - triangles within one cell disappear
 - triangles across 2 cells become edges (i.e. disappear)
 - triangles across 3 cells remain
- good guess for the minimum size of a triangle
 - edge length roughly = cell size
- yields constant vertex density in space
- does not pay attention to curvature
- more: <http://mkrus.free.fr/CG/LODS/xrds/>



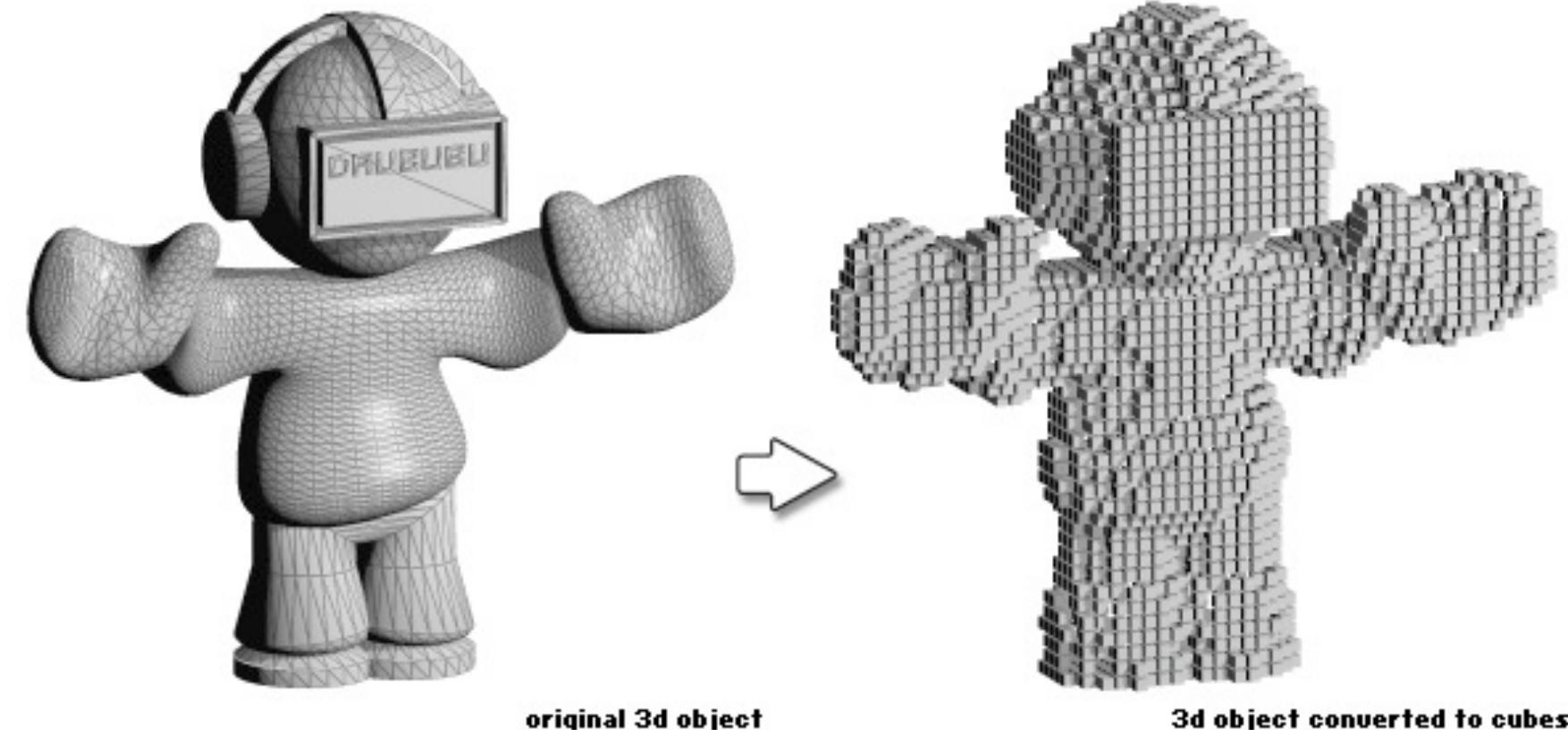
Billboard

- A flat object which is always facing you
- Very cheap in terms of polygons (2 triangles)
- Needs a meaningful texture
- Example (from SketchUp): guy in the initial empty world rotates about his vertical axis to always face you

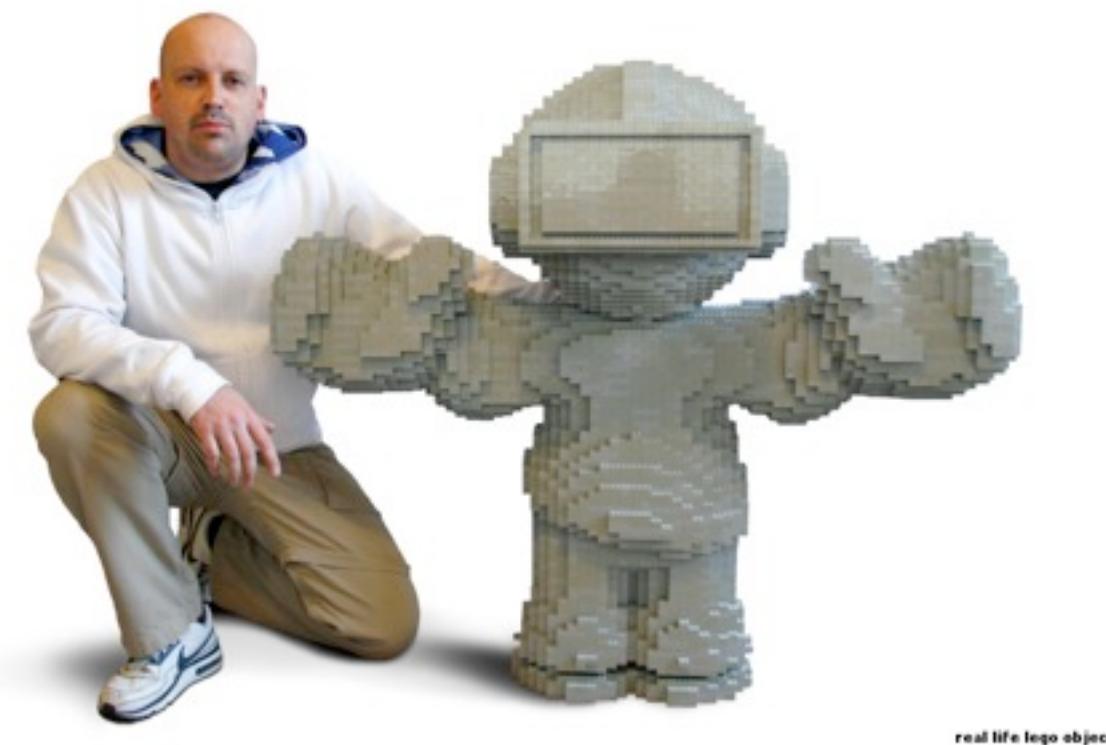


Voxel data

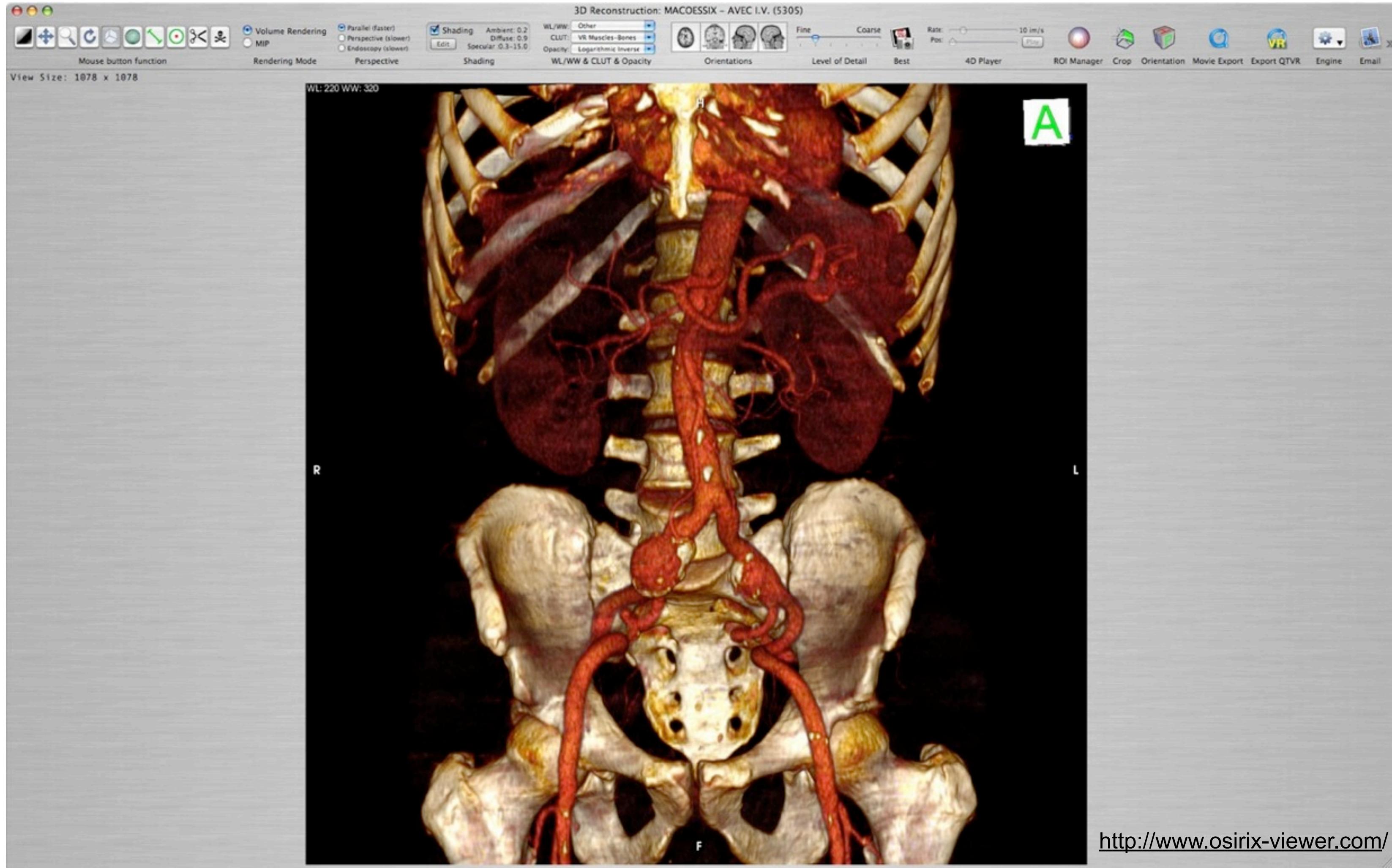
- „Voxel“ = „Volume“ + „Pixel“, i.e., voxel = smallest unit of volume
- Regular 3D grid in space
- Each cell is either filled or not
- Memory increases (cubic) with precision



- Easily derived from CSG models
- Also the result of medical scanning devices
 - MRI, CT, 3D ultrasonic
- Volume rendering = own field of research
- Surface reconstruction from voxels



<http://www.drububu.com/tutorial/voxels.html>



<http://www.osirix-viewer.com/>

Point-based graphics

- Objects represented by point samples of their surface („Surfels“)
- Each point has a position and a color
- Surface can be visually reconstructed from these points
 - purely image-based rendering
 - no mesh structure
 - very simple source data (x,y,z,color)
- Point-data is acquired e.g., by 3D cameras
- Own rendering techniques
- Own pipeline
- ==> own lecture ;-)



(C) 2004, CRS4 - Data courtesy of Stanford University